# Draft Grid Code – Grid Forming Converter Specification

**REFORMATTED – 14 JUNE 2021**

**Key – Black Text – Original Grid Code**

**Red Underlined Text – New requirements introduced for GC0137**

|  |  |
| --- | --- |
| Active Control Based Power | Is the **Active Power** output supplied by a **Grid Forming Plant** through controlled means (be it manual or automatic) in the positive phase sequence Root Mean Square **Active Power** or **Reactive Power** produced at fundamental **System Frequency** by the control system of a **Grid Forming Unit**  For **GBGF-I** **Plant** this is equivalent to that of a **Synchronous Generating Unit** with a traditional governor coupled to its prime mover.  **Active Control Based Power** includes **Active Power** changesthat results from a change to the **Grid Forming Plant Owners** available set points that have a 5 Hz limit on the bandwidth of the provided response.  **Active Control Based Power** alsoincludes **Active Power** components produced by the normal operation of a **Grid Forming Plant** that comply with the **Engineering Recommendation** P28 limits. These **Active Power** components do not have a 5 Hz limit on the bandwidth of the provided response.  **Active Control Based Power** does not include **Active Power** components proportional to **System Frequency**, slip or deviation that provide damping power to emulate the natural damping function provided by a real **Synchronous Generating Unit**. |
| Active Control Based Droop Power | **The Active Control Based Power** output supplied by a **Grid Forming Plant** through controlled means (be it manual or automatic).  For **GBGF-I** **Plant** is equivalent to that of a **Synchronous Generating Unit** with a traditional governor coupled to its prime mover.  **Active Control Based Droop Power** is used by **The Company to** control **System Frequency** changesthrough the instruction of **Primary Frequency Response** and **Secondary Frequency Response**. |
| Active Damping Power | The **Active Power** naturally injected or absorbed by a **Grid Forming Plant** to reduce **Active Power** oscillations in the **Total System**.  More specifically, **Active Damping Power** is the damped response of a **Grid Forming Plant** to an oscillation between the voltage at the **Grid Entry Point** or **User System Entry Point** and the voltage of the **Internal Voltage Source** of the **Grid Forming Plant**.  For the avoidance of doubt, **Active Damping Power** is an inherent capability of a **Grid Forming Plant** that starts to respond naturally, within less than 5ms to low frequency oscillations in the **System Frequency**. |
| Active Frequency Response Power | **Active Frequency Response Power** is the injection or absorption of **Active Power**  by a **Grid Forming Plant** to and from the **Total System** during a deviation of the **System Frequency** away from the **Target Frequency**.  For a **GBGF-I** **Plant** this is very similar to **Primary Response** but with a response time to achieve the declared service capability (which could be the **Maximum Capacity** or **Registered Capacity**) within 1 second.  For **GBGF-I Plant** this can rapidly add extra **Active Power** in addition to the phase-based **Active** **Inertia Power** to provide a system with desirable **NFP** plot characteristics.  **The Active Frequency Response Power** can be produced by any viable control technology. |
| Active Inertia Power | The injection or absorption of **Active Power** by a **Grid Forming Plant** to and from the **Total System** during a **System Frequency** change.  The amount of **Active Power** supplied or absorbed by the **Grid Forming Plant** is a function of the energy storage capability of the **Internal Voltage Source** and **ROCOF** or, in the case of an **HVDC System**, is a function of the **Active Power** provided by either the **Remote End HVDC Converter Station** or some extra **Plant**.  For the avoidance of doubt, this includes the rotational inertial energy of the complete drive train of a **Synchronous Generating Unit**.  **Active Inertia Power** is an inherent capability of a **Grid Forming Plant** to respond naturally, within less than 5 ms, to changes in the **System Frequency**.  For the avoidance of doubt the **Active Inertia Power** has a slower frequency response compared with **Active Phase Jump Power**. |
| Active Phase Jump Power | The transient injection or absorption of **Active Power** from a **Grid Forming Plant** to the **Total System** as a result of changes in the phase angle between the **Internal Voltage Source** of the **Grid Forming Plant** and the **Grid Entry Point** or **User System Entry Point**.  In the event of a disturbance or fault on the **Total System**, a **Grid Forming Plant** will instantaneously inject or absorb **Active** **Phase Jump Power** to the **Total System** as a result of the phase angle change.  For **GBGF-I** **Plant** as a minimum value this is up to the **Phase Jump Angle Limit Power**.  **Active Phase Jump Power** is an inherent capability of a **Grid Forming Plant** that starts to respond naturally, within less than 5 ms, and can have frequency components to over 1000 Hz. |
| Active ROCOF Response Power | **Active ROCOF Response Power** is defined as the **Active** **Inertia Power** developed from a **Grid Forming Plant** plus the **Active Frequency Response Power** that can be supplied by a **Grid Forming Plant** when subject to a rate of change of the **System Frequency**. |
| Control Based Reactive Power | **Control Based Reactive Power** is the **Reactive Power** supplied by a **Grid Forming Plant** through controlled means based on operator adjustment selectable setpoints (these may be manual or automatic). |
| Damping Factor (ζ) | It is the ratio of the actual damping to critical damping.  For a **GBGF-I** **Plant** the open loop phase angle, for an open loop gain of one, is measured from the systems **Nichols Chart.**  This angleis used to define the system’s equivalent **Damping Factor** that is the same as the **Damping Factor** of a second order system with the same open loop phase angle.  Alternatively, the **Damping Factor** refers to the damping of a specific oscillation mode that is associated with the second order system created by the power to angle transfer function as show in Figure ECC.6.3.19.3.2. |
| Defined Active Damping Power | The **Active Damping Power** supplied by a **GBGF-I Plant** when it is operating at the **Grid Oscillation Value** defined in Table ECC.6.3.19.3.2 of ECC.6.3.19.3(vii). |
| Dynamic Reactive Compensation Equipment | **Plant** capable of supplying or absorbing **Reactive Power** in a controlled manner which could include but not limited to a Synchronous Compensator, Static Var Compensator (SVC), or STATCOM. |
| Electronic Power Converter | A design which usesswitched solid state power electronic devices to produce a real voltage waveform, that has a fundamental component with harmonics. |
| Fast Fault Current Injection | The ability of a **Grid Forming Plant** to supply reactive current, that starts to rise in less than 5 ms, into the **Total System** when the voltage falls below 90% of its nominal value. |
| GBGF-I | Is any **Power Park Module**, **HVDC System**, **DC Converter**, **OTSDUW Plant and Apparatus**, **Non-Synchronous** **Electricity Storage Module**, **Dynamic Reactive Compensation Equipment** or any **Plant** and **Apparatus** (including a smart load)which is connected or partly connected to the **Total System** via an **Electronic Power Converter** whichhas a **Grid Forming Capability (GBGF-I)**. |
| GBGF-S | Is a **Synchronous Power Generating Module**, **Synchronous Electricity Storage Module** or **Synchronous Generating Unit** with a **Grid Forming Capability**. |
| Grid Forming Active Power | **Grid Forming Active Power** isthe inherent **Active Power** produced by **GBGF Plant** that includes **Active Inertia Power** plus **Active Phase Jump Power** plus **Active Damping Power**. |
| Grid Forming Capability | Is (but not limited to) a **Power Generating Module**, **HVDC Converter** (which could form part of an **HVDC System**), **Generating Unit**, **Power Park Module**, **DC Converter**, **OTSDUW Plant and Apparatus**, **Electricity Storage Module**, **Dynamic Reactive Compensation Equipment** or any **Plant** and **Apparatus** (including a smart load) whose supplied **Active Power** is directly proportional to the difference between the magnitude and phase of its **Internal Voltage Source** and the magnitude and phase of the voltage at the **Grid Entry Point** or **User System Entry Point** and the sine of the **Load Angle**. As a consequence, a **Plant** which has a **Grid Forming Capability** is one where the frequency of rotation of the **Internal Voltage Source** is the same as the **System Frequency** for normal operation, with only the **Load Angle** defining the relative position between the two. In the case of a **GBGF-I Plant** a **GBGF-I Unit** forming part of a **GBGF-I Plant** shall be capable of sustaining a voltage at its terminals irrespective of the voltage at the **Grid Entry Point** or **User System Entry Point** for normal operating conditions.  For **GBGF-I** Plant the control system, which determines the amplitude and phase of the **Internal Voltage Source**, shall have a response to the voltage and **System Frequency** at the **Grid Entry Point** or **User System Entry Point**) with a bandwidth that is less than a defined value as shown by the control system’s **NFP** Plot.  Exceptions to this rule are only allowed during transients caused by **System** faults, voltage dips/surges and/or a step or ramp changes in the phase angle which are large enough to cause damage to the **Grid Forming Plant** via excessive currents. |
| Grid Forming Electronic Power Converter | A **Grid Forming Plant** whose output is derived from a static solid state **Electronic Power Converter** with a **GBGF-I** capability. |
| Grid Forming Plant | A **Plant** which is classified as either a **GBGF-S** or a **GBGF-I** |
| Grid Forming Plant Owner | The owner or operator of a **Grid Forming Plant**. |
| Grid Forming Unit | A **Power Park Unit** or **Electricity Storage Unit** or a **Synchronous Power Generating Unit** or individual **Load** with a **Grid Forming Capability** |
| Grid Oscillation Value | This is an injected test frequency signal applied at nominal **System Frequency** with a superimposed oscillatory response overlayed onto the nominal **System Frequency** with an amplitude of 0.05 Hz peak to peak at a frequency of 1 Hz and is used for the rating of the **Defined** **Active Damping Power**. |
| Inertia Constant H | For a **Grid Forming Plant** is: -  For a **GBGF-S Generating Unit** the **Inertia Constant H** is measured in MWseconds / MVA. |
| Inertia Constant He | For a **GBGF- I Electronic Power Converter**, this is measured in MWseconds / MVA and produced by the **Active** **ROCOF Response Power**. |
| Internal Voltage Source or IVS | For a **GBGF-S Unit** a real magnetic field, that rotates synchronously with the **System Frequency** under normal operating conditions, which as a consequence induces an **Internal Voltage Source** in the stationary generator winding that has a real impedance.  In a **GBGF-I** design,switched power electronic devices are used to produce a voltage waveform, with harmonics, that has a fundamental rotational component called the **Internal Voltage source (IVS)** that rotates synchronously with the **System Frequency** under normal operating conditions.  For a **GBGF-I** **Plant** there must be an impedance with only real physical values, between the **Internal Voltage Source** and the **Grid Entry Point** or **User System Entry Point**.  For the avoidance of doubt a virtual impedance, is not permitted in **GBGF-I** **Plant**. |
| Load Angle | The angle in radians between the voltage of the **Internal Voltage Source** and the voltage at the **Grid Entry Point** or **User System Entry Point**. |
| Network Frequency Perturbation Plot | A **Network Frequency Perturbation (NFP) Plot** is a form of Bode Plot which plots the amplitude (%) and Phase (degrees) of the resulting output oscillation responding to an applied input oscillation across a frequency base. The plot will be used to assess the capability and performance of a **Grid Forming Plant** and to ensure it does not pose a risk to other **Plant** and **Apparatus** connected to the **Total System**.  For **GBGF-I** **Plant**, these are used to provide data to **The Company** which together with the associated **Nichols Chart** (or equivalent) defines the effects on a **GBGF-I** **Plant** for changes in the frequency of the applied input oscillation.  The input is the applied input oscillation and the output is the resulting oscillations in the **GBGF-I Plant’s** **Apparent Power**.  For the avoidance of doubt **GBGF-S** **Plant** provide their data using the existing formats and do not need to supply **NFP** plots. |
| Nichols Chart | For a **GBGF-I** **Plant** a **Nichols Chart** is derived from the open loop Bode Plots that are used to produce an **NFP Plot**. The **Nichols Chart** plots open loop gain versus open loop phase angle. This enables the open loop phase for an open loop gain of 1 to be identified for use in defining the **GBGF-I’s** equivalent **Damping Factor** |
| Non-CUSC Party | A Party who does not accede to the **Connection and Use of System Code** (**CUSC**). |
| Peak Current Rating | For a **GBGF-I** **Plant** this is the larger of either the: -   * The registered maximum steady-state current plus the maximum additional current to supply the **Active** **ROCOF Response Power** plus the **Defined Active Damping Power**; or. * The registered maximum steady-state current plus the maximum additional current to supply the **Phase Jump Angle** limit power, or.   The maximum short term total current defined by the **User** or **Non-CUSC Party**. |
| Phase Jump Angle | The **Phase Jump Angle** is the difference in the measured phase angle of the voltage at the **Grid Entry Point** or **User System Entry Point** (if **Embedded**) in a given mains half cycle compared with the measured phase angle of the voltage at the **Grid Entry Point** or **User System Entry Point** in the previous mains half cycle. |
| Phase Jump Angle Limit | The maximum **Phase Jump Angle** when applied to a **GBGF-I** **Plant** which will result in a linear controlled response without activating current limiting functions. This is specified for a **System** angle near to zero. |
| Phase Jump Angle Withstand | The maximum **Phase Jump Angle** when applied to a **GBGF-I** **Plant** which will result in the **GBGF-I Plant** remaining in stable operation with current limiting functions activated. This is specified for a **System** angle near to zero. |
| Power Generating Module Performance Chart | A diagram showing the **Active ~~Real~~ Power** (MW) and **Reactive Power** (MVAr) capability limits within which a **Synchronous Power Generating Module** or **Power Park Module** at its **Grid Entry Point** or **User System Entry Point** will be expected to operate under steady state conditions. |
| ROCOF | **Rate of Change of System Frequency** |
| Synchronous Generating Unit Performance Chart | A diagram showing the **Active ~~Real~~ Power** (MW) and **Reactive Power** (MVAr) capability limits within which a **Synchronous Generating Unit** at its stator terminals (which is part of a **Synchronous Power Generating Module**) will be expected to operate under steady state conditions. |
| Test Signal | A signal in the form of a sine wave, applied to a **GBGF-I Plant** to demonstrate its ability to contribute to **Active Damping Power**. |
| Voltage Jump Reactive Power | The transient **Reactive Power** transferred from a **Grid Forming Plant** to the **Total System** as a result of either a step or ramp change in the difference between the voltage magnitude and the voltage of the **Internal Voltage Source** of the **Grid Forming Plant** and **Grid Entry Point** or **User System Entry Point**.  In the event of a voltage magnitude and phase change at the **Grid Entry Point** or **User System Entry Point**, a **Grid Forming Plant** will instantaneously (within 5ms) supply **Voltage Jump** **Reactive Power** to the **Total System** as a result of the voltage magnitude change. |

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**Extracts from the Planning Code**

PC.A.5.8 Grid Forming Related Information

PC.A.5.8.1 The following data need only be supplied by **Users** (be they a **GB Code User** or **EU Code User**) or **Non-CUSC Parties** who wish to offer a **Grid Forming Capability** as provided for ECC.6.3.19.3. Where such a **Grid Forming Capability** is provided then the following data items and models are to be supplied.

1. Each **GBGF-I Plant** shall be designed so as not to interact and affect the operation, performance, safety or capability of other **User’s Plant** and **Apparatus** connected to the **Total System**. To achieve this requirement, each **User** shall be required to submit a **Network Frequency Perturbation** **Plot** and **Nichols chart** (or equivalent as agreed with **The Company**) which shall be assessed in accordance with the requirements of ECP.A.3.9.3.

Each **User** or **Non-CUSC Party** is required to supply a high level equivalent architecture diagram of their **Grid Forming Plant** as shown in Figure PC.A.5.8.1 together with the equivalent linear classical block diagram model (using the Laplace Operator) of their **Grid Forming Plant** which should preferably be in the general form shown in Figure PC.A.5.8.1 (a) or Figure PC.A.5.8.1 (b). When submitting either Figure PC.A.5.8.1 (a) or Figure PC.A.5.8.1 (b), each **User** or **Non-CUSC Party** can use their own design, that may be very different to Figures PC.A.5.8.1 (a) or PC.A.5.8.1 (b),but should contain all relevant functions that can include simulation models and other equivalent data and documentation.

Each **User** or **Non CUSC Party** shall provide a model of their **Grid Forming** **Plant** which provides a true and accurate reflection of its **Grid Forming Capability**.



Figure PC.A.5.8.1



Figure PC.A.5.8.1 (a) Preferred simplified diagram of a **GBGF-I Plant** with a **Power System Stabiliser** “**PSS**” that can add damping to the **GBGF-I Plant**’s closed loop function shown by the solid red line and the dotted blue line.



Figure PC.A.5.8.1 (b) – Preferred simplified diagram of a system with a droop control ability that can add **Control-Based Active** **Droop Power.** This diagram does not add extra closed loop damping to the **GBGF-I Plant’s** closed loop function shown by the solid red line and the dotted blue line.

1. In order to participate in the **Grid Forming Capability** market, **User’s** and **Non-CUSC Parties** are required to provide data of their **GBGF-I** **Plant** in accordance with Figures PC.A.5.8.1(a) and PC.A.5.8.1(b) **Users** and **Non-CUSC Parties** in respect of **Grid Forming Plants** should indicate if the data is submitted on a unit or aggregated basis. Table PC.A.5.8.1(a) defines the notation used in Figure PC.5.8.1

|  |  |  |
| --- | --- | --- |
| **Parameter** | **Symbol** | **Units** |
| The primary reactance of the **Grid Forming Unit**, in pu. | Xin or Xts | pu on MVA **Rating of Grid Forming Unit** |
| The additional reactance, in pu, between the terminals of the **Grid Forming Unit** and the **Grid Entry Point** or **User System Entry Point** (if **Embedded**). | Xtr | pu on MVA **Rating of Grid Forming Unit** |
| The rated angle between the **Internal Voltage Source** and the input terminals of the **Grid Forming Unit**. |  | radians |
| The rated angle between the **Internal Voltage Source** and **Grid Entry Point** or **User System Entry Point** (if **Embedded**). |  | radians |
| The rated voltage and phase of the **Internal Voltage Source** of the **Grid Forming Unit**. |  | Voltage - pu  Phase - radians |
| The rated electrical angle between current and voltage at the input to the Grid transformer. |  | radians |

Table PC.A.5.8.1

1. In order to participate in a **Grid Forming Capability** market, **User’s** and **Non-CUSC Parties** are also required to provide the data of their **GBGF-I Plant** in accordance with Table PC.A.5.8.1.2 to **The Company**. The details and arrangements for **Users** and **Non-CUSC Parties** participating in this market shall be published on **The Company’s Website**.

|  |  |  |  |
| --- | --- | --- | --- |
| **Quantity** | **Units** | **Range**  **(where Applicable)** | **User Defined Parameter** |
| Type of **Plant** (eg **Generating Unit**, **Electricity Storage Module**, **Dynamic Reactive Compensation Equipment** | N/A |  |  |
| Maximum Continuous Rating at **Registered Capacity** or **Maximum Capacity** | MVA |  |  |
| Primary reactance Xin or Xts(see Table 1) | pu on MVA |  |  |
| Additional reactance Xtr (See Table 1) | pu on MVA |  |  |
| **Maximum Capacity** | MW |  |  |
| **Active ROCOF Response Power** (MW) supplied or absorbed at 1Hz/s **System Frequency** change (which is the maximum frequency change for linear operation of the **Grid Forming Plant**) | MW |  |  |
| **Phase Jump Angle Withstand** | degrees |  | 60 degrees specified |
| **Phase Jump Angle limit** | degrees |  | 5 degrees recommended |
| **Phase Jump Power** (MW) at the rated angle | MW |  |  |
| **Defined Active Damping Power** for a **Grid Oscillation Value** of 0.5 Hz peak to peak at 1 Hz | MW |  |  |
| The cumulative energy delivered for a 1Hz/s **System Frequency** fall from 52 Hz to 47 Hz This is the total **Active Power** transient output of the **Grid Forming Plant** | MWs or MJ |  |  |
| Inertia Constant (H) using equation 1 or declared in accordance with the simulation results of ECP.A.3.9.4 | H |  |  |
| Inertia Constant (He) using equation 2 or declared in accordance with the simulation results of ECP.A.3.9.4 | He |  |  |
| Continuous Overload Capability | % on MVA |  |  |
| Short Term duration Overload capability |  |  |  |
| Duration of Short Term Overload Capability | s |  |  |
| **Peak Current Rating** | pu |  |  |
| Nominal **Grid Entry Point** or **User System Entry Point** voltage | kV |  |  |
| **Grid Entry Point** or **User System Entry Point** | - Location |  |  |
| Continuous or defined time duration MVA Rating | MVA |  |  |
| Continuous or defined time duration MW Rating | MW |  |  |
| For a **GBGF-I** **Plant** the inverters maximum **Internal Voltage Source** (**IVS**) for the worst case condition – for example operation at maximum exporting **Reactive Power** at the maximum AC **System** voltage | pu |  |  |
| Maximum Three Phase Short Circuit Infeed at **Grid Entry Point** or **User System Entry Point** | kA |  |  |
| Maximum Single Phase Short Circuit Infeed at **Grid Entry Point** or **User System Entry Point** | kA |  |  |
| Will the **Grid Forming Plant** contribute to any other form of commercial service – for example Dynamic Containment, Firm Frequency Response, | Details to be provided |  |  |
| **Equivalent Damping Factor.** | ζ |  | 0.2 to 5.0 allowed |

Table PC.A.5.8.2

Equation 1  is H = Installed MWs / Rated installed MVA

Equation 1

He = (**Active** **ROCOF Response Power** at 1 Hz / s x **System Frequency**) / ( Installed MVA x 2 )

Equation 2

**Extracts from the Connection Conditions**

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CC.6.3.5 It is an essential requirement that the **National Electricity Transmission System** must incorporate a **Black Start Capability**. This will be achieved by agreeing a **Black Start Capability** with a number of strategically located **Black Start Service Providers**. For each **Black Start Service Provider** **The Company** will state in the **Bilateral Agreement** whether or not a **Black Start Capability** is required. For the avoidance of doubt, a **GBGF-I** **Plant** designed with a **Black Start Capability** would also be required to have a **Grid Forming Capability** in accordance with the requirements of ECC.6.3.19.

**Extracts from the European Connection Conditions**

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ECC.6.3.5.3 Where an **EU Code User** has entered into a **Black Start** **Contract** to provide a **Black Start Capability** in respect of a **Type C** **Power Generating Module** or **Type D** **Power Generating Module** (including **DC Connected Power Park Modules)** the following requirements shall apply.

1. The **Power-Generating Module** or **DC Connected Power Park Module** shall be capable of starting from shutdown without any external electrical energy supply within a time frame specified by **The Company** in the **Black Start Contract**;
2. Each **Power Generating Module** or **DC Connected Power Park Module** shall be able to synchronise within the **System Frequency** limits defined in ECC.6.1.2 and, where applicable, voltage limits specified in ECC.6.1.4;
3. The **Power Generating** **Module** or **DC Connected Power Park Module** shall be capable of connecting on to an unenergised **System**;
4. The **Power-Generating Module** or **DC Connected Power Park Module** shall be capable of automatically regulating dips in voltage caused by connection of demand;
5. The **Power Generating Module** or **DC Connected Power Park Module** shall:

be capable of **Block Load Capability**

be capable of operating in **LFSM-O** and **LFSM-U**, as specified in ECC.6.3.7.1 and ECC.6.3.7.2

control **System Frequency** in case of overfrequency and underfrequency within the whole **Active Power** output range between the **Minimum Regulating Level** and **Maximum Capacity** as well as at houseload operation levels

be capable of parallel operation of a few **Power Generating Modules** including **DC Connected Power Park Modules** within an isolated part of the **Total System** that is still supplying **Customers**, and control voltage automatically during the system restoration phase,

**Generators** and **HVDC System Owners** who own and operate **Power Park Modules** (including **DC Connected Power Park Modules**) and **HVDC Equipment** which provide a **Black Start Capability**, shall also be capable of satisfying the **Grid Forming Capability** requirements defined in ECC.6.3.19;

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ECC.6.3.13 FREQUENCY, RATE OF CHANGE OF FREQUENCY AND VOLATGE PROTECTION SETTING ARRANGEMENTS

ECC.6.3.13.1 **EU** **Generators** (including in respect of **OTSDUW Plant and Apparatus**) and **HVDC System Owners** will be responsible for protecting all their **Power Generating Modules** (and **OTSDUW Plant and Apparatus**) or **HVDC Equipment** against damage should **Frequency** excursions outside the range 52Hz to 47Hz ever occur. Should such excursions occur, it is up to the **EU** **Generator** or **HVDC System** **Owner** to decide whether to disconnect his **Apparatus** for reasons of safety of **Apparatus**, **Plant** and/or personnel.

ECC.6.3.13.2 Each **Power Park Module** with a **Grid Forming Capability** as provided for in ECC.6.3.19, when connected and synchronised to the **System**, is required to be capable of withstanding without tripping a rate of change of **Frequency** up to and including 2 Hz per second as measured over a rolling 500 milliseconds period. All other **Power Generating Modules** when connected and synchronised to the **System**,shall be capable of withstanding without tripping a rate of change of **Frequency** up to and including 1 Hz per second as measured over a rolling 500 milliseconds period. . Voltagedips may cause localised rate of change of **Frequency** values in excess of 1 Hz per second (or 2Hz/s in the case of **Power Park Modules** with a **Grid Forming Capability**) for short periods, and in these cases, the requirements under ECC.6.3.15 (**Fault Ride Through**) supersedes this clause. For the avoidance of doubt, this requirement relates to the capabilities of **Power Generating Modules** only and does not impose the need for rate of change of **Frequency** protection nor does it impose a specific setting for anti-islanding or loss-of-mains protection relays.

ECC.6.3.13.3 Each **HVDC System** and **Remote End HVDC Converter Station** when connected and synchronised to the **System**,shall be capable of withstanding without tripping a rate of change of **Frequency** up to and including ±2.5Hz per second as measured over the previous 1 second period. Voltagedips may cause localised rate of change of **Frequency** values in excess of ±2.5 Hz per second for short periods, and in these cases, the requirements under ECC.6.3.15 (**Fault Ride Through**) supersedes this clause. For the avoidance of doubt, this requirement relates to the capabilities of **HVDC Systems** and **Remote End HVDC Converter Stations** only and does not impose the need for rate of change of **Frequency** protection nor does it impose a specific setting for anti-islanding or loss-of-mains protection relays.

ECC.6.3.13.4 Each **DC Connected** **Power Park Module** when connected to the **System**,shall be capable of withstanding without tripping a rate of change of **Frequency** up to and including ±2.0Hz per second as measured over the previous 1 second period. **Voltage** dips may cause localised rate of change of **Frequency** values in excess of ±2.0 Hz per second for short periods, and in these cases, the requirements under ECC.6.3.15 (**Fault Ride Through**) supersedes this clause. For the avoidance of doubt, this requirement relates to the capabilities of **DC Connected Power Park Modules** only and does not impose the need for rate of change of **Frequency** protection nor does it impose a specific setting for anti-islanding or loss-of-mains protection relays.

ECC.6.3.13.5 As stated in ECC.6.1.2, the **System** **Frequency** could rise to 52Hz or fall to 47Hz and the **System** voltage at the **Grid Entry Point** or **User System Entry Point** could rise or fall within the values outlined in ECC.6.1.4. Each **Type C** and **Type D** **Power Generating Module** (including **DC Connected Power Park Modules** and **Grid Forming Plant**)or any constituent element must continue to operate within this **Frequency** range for at least the periods of time given in ECC.6.1.2 and voltage range as defined in ECC.6.1.4 unless **The Company** has agreed to any simultaneous overvoltage and underfrequency relays and/or simultaneous undervoltage and over frequency relayswhich will trip such **Power Generating Module** (including **DC Connected Power Park Modules**), and any constituent element within this **Frequency** or voltage range. In the case of **Grid Forming Plant**, **Grid Forming Plant Owners** are also required to satisfy the **System Frequency** and **System** voltage requirements as defined in ECC.6.3.19.

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ECC.6.3.16 **FAST FAULT CURRENT INJECTION**

ECC.6.3.16.1 General **Fast Fault Current Injection**, principles and concepts applicable to Type B, Type C and Type D **Power Park Modules** and **HVDC Equipment**.

ECC.6.3.16.1.1 In addition to the requirements of ECC.6.1.4, ECC.6.3.2, ECC.6.3.8 and ECC.A.7, each **Type B**, **Type C** and **Type D Power Park Module** or each **Power Park Unit** within a **Type B**, **Type C** and **Type D Power Park Module** or **HVDC Equipment** shall be required to satisfy the following requirements unless operating in a **Grid Forming Capability** mode in which case the requirements of ECC.6.3.19 shall apply instead. For the purposes of this requirement, current and voltage are assumed to be positive phase sequence values.

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ECC.6.3.19 **GRID FORMING CAPABILITY** FOR GREAT BRITAIN

ECC.6.3.19.1In order for the **National Electricity Transmission System** to satisfy the stability requirements defined in the **National Electricity Transmission System Security and Quality of Supply Standards**, it is an essential requirement that an appropriate volume of **Grid Forming Plant** is available and capable of providing a **Grid Forming Capability**.

ECC.6.3.19.2 **Grid Forming** **Capability** is not a mandatory requirement but one which will be delivered through market arrangements, the details of which shall be published on **The Company’s Website**. **Grid Forming Capability** can be implemented by any technology including **Electronic Power Converters** with a **GBGF- I** ability, rotating **Synchronous Generating Units** or a combination of the two.

ECC.6.3.19.3 As noted in ECC.6.3.19.2, **Grid Forming Capability** is not a mandatory requirement, however where a **User** (be they a **GB Code User** or **EU Code User**) or **Non-CUSC Party** wishes to offer a **Grid Forming Capability**, then they will be required to ensure their **Grid Forming Plant** meets the following requirements.

1. The **Grid Forming Plant** must fully comply with the applicable requirements of the Grid Code including but not limited to the **Planning Code** (**PC**), **Connection Conditions** (**CC**’s) or **European Connection Conditions** (**ECC**’s) (as applicable), **Compliance Processes** (**CP**’s) or **European Compliance Processes** (**ECP**’s) as applicable, **Operating Codes** (**OC**’s), **Balancing Codes** (**BC**’s) and **Data Registration Code** (**DRC**).
2. Each **GBGF-I** **Plant** shall comprise an **Internal Voltage Source** and reactance. For the avoidance of doubt, the reactance between the **Internal Voltage Source** and **Grid Entry Point** or **User System Entry Point** (if **Embedded**) within the **Grid Forming Plant** can only be made by a combination of several physical discrete reactances. This could include the reactance of the **Synchronous Generating Unit** or **Power Park Unit** or **HVDC System** or **Electricity Storage Unit** or **Dynamic Reactive Compensation Equipment** and the electrical **Plant** connecting the **Synchronous Generating Unit** or **Power Park Unit** or **HVDC System** or **Electricity Storage Unit** (such as a transformer) to the **Grid Entry Point** or **User System Entry Point** (if **Embedded**).
3. In addition to meeting the requirements of CC.6.3.15 or ECC.6.3.15, each **Grid Forming Plant** is required to remain in synchronism with the **Total System** and maintain a **Load Angle** whose value can vary between 0 and 90 degrees (π/2 radians).
4. When subject to a fault or disturbance, or **System Frequency** change, each **Grid Forming Plant** shall be capable of supplying **Active ROCOF Response Power**, **Active Phase** **Jump Power**, **Active Damping Power**, **Active** **Control Based Power**, **Control Based Reactive Power**, **Voltage Jump Reactive Power** and **Fast Fault Current Injection**.
5. Each **GBGF-I Plant** shall be capable of:-
6. Providing a symmetrical ability for importing and exporting **Active** **ROCOF Response Power**, **Active** **Phase** **Jump Power**, **Active Damping Power** and **Active** **Control Based Power** under both rising and falling **System Frequency** conditions. Such requirements would apply over the full **System Frequency** range as detailed in CC.6.1.2 and CC.6.1.3 or ECC.6.1.2 (as applicable). In satisfying these requirements, **User’s** and **Non-CUSC Parties** should be aware of (but not limited to) the exclusions in CC.6.3.3, CC.6.3.7 and BC3.7.2.1 (as applicable for **GB Code User’s**) or ECC.6.1.2, ECC.6.3.3, ECC.6.3.7 and BC3.7.2.1(b)(i) (as applicable for **EU Code User’s** and **Non-CUSC Parties**) during **System Frequencies** between 47Hz – 52Hz, excluding CC.6.1.3 or ECC.6.1,2.1,2 for system with time limited output ratings. For the avoidance of doubt, an asymmetrical response is permissible as agreed with **The Company** when required to protect **User’s** and **Non CUSC Parties Plant** and **Apparatus** or asymmetry in energy availability.
7. Operating as a voltage source behind a real reactance.

being designed so as not to cause any undue interactions which could cause damage to the **Total System** or other **User’s Plant** and **Apparatus**.

1. include an **Active Control Based Power** part of the control system that can respond to changes in the **Grid Forming Plant** or external signals from the **Total System** available at the **Grid Entry Point** or **User System Entry Point** but with a bandwidth below 5 Hz to avoid AC **System** resonance problems.
2. meeting the requirements of ECC.6.3.13 irrespective of being owned or operated by a **GB Code User**, **EU Code User** or **Non-CUSC Party**.
3. **GBGF-I Plant** with an importing capability mode of operation such as **DC Converters**, **HVDC Systems** and **Electricity Storage Modules** are required to have a predefined frequency response operating characteristic over the full import and export range which is contained within the envelope defined by the red and blue lines shown in Figure ECC.6.3.19.3. This characteristic shall be submitted to **The Company**. For the avoidance of doubt, **Grid Forming Plants** which are only capable of exporting **Active Power** to the **Total System** are only required to operate over the exporting power region

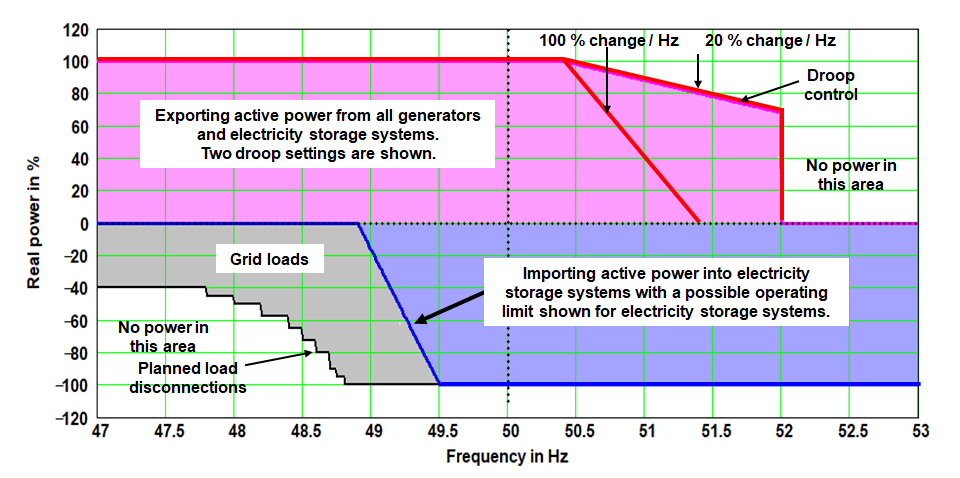
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Figure ECC.6.3.19.3

1. Each **User** shall design their **GBGF-I** system with an equivalent **Damping Factor** of between 0.2 and 5.0. It is down to the **User** or **Non-CUSC Party** to determine the **Damping Factor**, whose value shall be agreed with **The Company**.It is typical for the **Damping Factor** to be less than 1.0, though this would be dependent upon the parameters of the **Grid Forming Plant** and the equivalent **System** impedance at the **Grid Entry Point** or **User System Entry Point**.

The output of the **Grid Forming Plant** shall be designed such that following a disturbance on the **System**, the **Active Power** output and **Reactive Power** output shall be adequately damped. The damping shall be judged to be adequate if the corresponding **Active Power** response to a disturbance decays to with a response that is in line with the response of second order system that has the same equivalent **Damping Factor**.

1. Each **GBGF-I Plant** shall be designed so as not to interact and affect the operation, performance, safety or capability of other **User’s Plant** and **Apparatus** connected to the **Total System**. To achieve this requirement, each **User** and **Non CUSC Party** shall be required to submit the data required in PC.A.5.8

ECC.6.3.19.4 In addition to the requirements of ECC.6.3.19.1 – ECC.6.3.19.3 each **Grid Forming Plant** shall also be capable of: -

1. satisfying the requirements of ECC.6.3.19.5.
2. operating at a minimum short circuit level of zero MVA at the **Grid Entry Point** or **User System Entry Point**.
3. providing any additional quality of supply requirements, including but not limited to Temporary Over-voltage limits (TOV’s) and **System Frequency** bandwidth limitations, with **The Company**. Such requirements would be pursuant to the terms of the **Bilateral Agreement**. For the avoidance of doubt, this requirement is in addition the minimum quality of supply requirements detailed in CC.6.1.5, CC.6.1.6 and CC.6.1.7 (as applicable) or ECC.6.1.5, ECC.6.1.6 and ECC.6.1.7 (as applicable),

ECC.6.3.19.5 **Fast Fault Current Injection** applicable to **GBGF-I** **Plant**

ECC.6.3.19.5.1 For any balanced fault which results in the positive phase sequence voltage falling below the voltage levels specified in CC.6.1.4 or ECC.6.1.4 (as applicable) at the **Grid Entry Point** or **User System Entry Point** (if **Embedded**), a **Grid Forming Plant** shall, as a minimum be required to inject a reactive current of at least their **Peak Current Rating** when the voltage at the **Grid Entry Point** or **User System Entry Point** drops to zero. For intermediate retained voltages at the **Grid Entry Point** or **User System Entry Point**, the injected reactive current shall be on or above a line drawn from the bottom left hand corner of the normal voltage control operating zone (shown in the rectangular green shaded area of Figure ECC.6.3.19.5(a)) and the specified **Peak Current Rating** at a voltage of zero at the **Grid Entry Point** or **User System Entry Point** as shown in Figure ECC.16.3.19.5(a). Typical examples of limit lines are shown in Figure ECC.16.3.19.5(a) for a **Peak Current Rating** of 1.0pu where the injected reactive current must be on or above the black line and a **Peak Current Rating** of 1.5pu where injected reactive current must be on or above the red line.

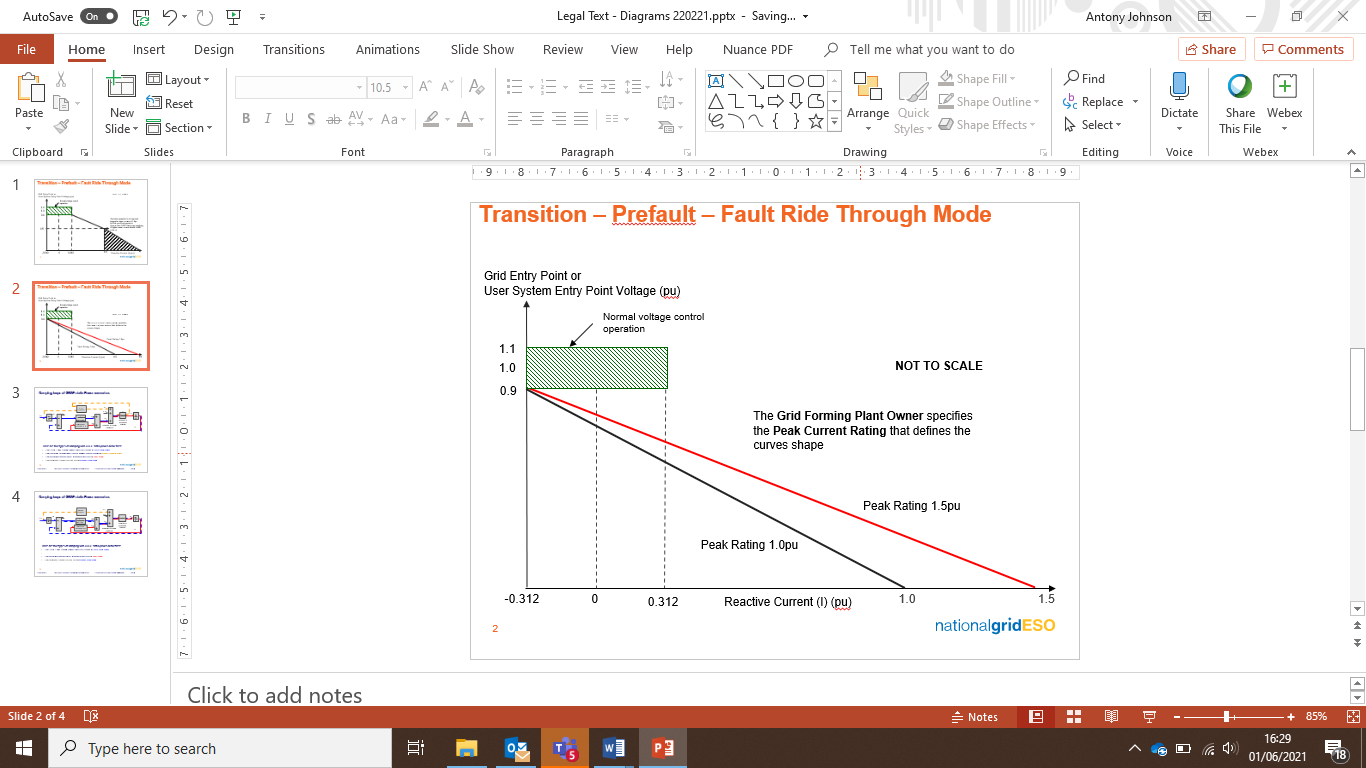


Figure ECC.6.3.19.5(a)

ECC.6.3.19.5.2 Figure ECC.6.3.19.5(a) defines the reactive current to be supplied under a faulted condition which shall be dependent upon the pre-fault operating condition and the retained voltage at the **Grid Entry Point** or **User System Entry Point** voltage. For the avoidance of doubt, each **Grid Forming Plant** (and any constituent element thereof), shall be required to inject a reactive current which shall be not less than its pre-fault reactive current and which shall as a minimum, increase each time the voltage at the **Grid Entry Point** or **User System Entry Point** (if **Embedded**) falls below 0.9pu whilst ensuring the overall rating of the **Grid Forming Plant** (or constituent element thereof) shall not be exceeded.

ECC.6.3.19.5.3 In addition to the requirements of ECC.6.3.19.5.1 and ECC.6.3.19.5.2, each **Grid Forming Plant** shall be required to inject reactive current above the shaded area shown in Figure ECC.6.3.19.5(b) when the retained voltage at the **Grid Entry Point** or **User System Entry Point** falls to 0pu. Where the retained voltage at the **Grid Entry Point** or **User System Entry Point** is below 0.9pu but above 0pu (for example when significant active current is drawn by loads and/or resistive components arising from both local and remote faults or disturbances from other **Plant** and **Apparatus** connected to the **Total System**) the injected reactive current component shall be in accordance with Figure ECC.6.3.19.5(a).

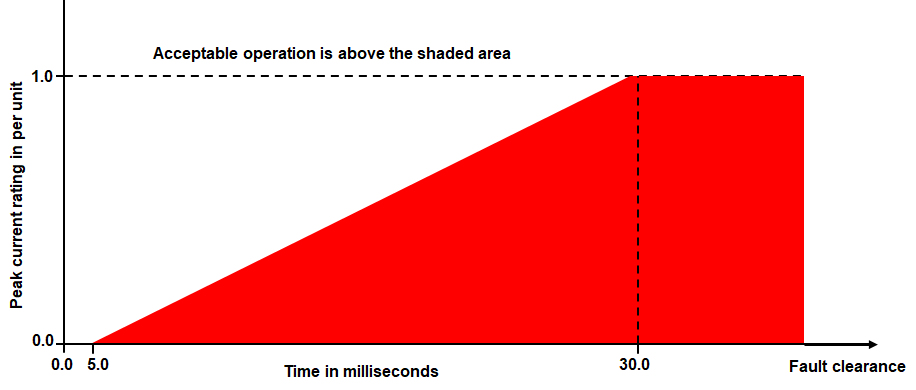


Figure ECC.16.3.19.5(b)

ECC.6.3.19.5.4 The injected current shall be above the shaded area shown in Figure ECC.6.3.19.5(b). Under any faulted condition, where the voltage falls outside the limits specified in CC.6.1.4 or ECC.6.1.4 (as applicable), there would be no requirement for each **Grid Forming Plant** or constituent part to exceed its transient or steady state rating as defined in Table ECC.6.3.19.3.2 of ECC.6.3.19.3(x).

ECC.6.3.19.5.5 For any planned or switching events (as outlined in CC.6.1.7 or ECC.6.1.7 of the Grid Code) or unplanned events which results in temporary power **System Frequency** over voltages (TOV’s), each **Grid Forming Plant** will be required to satisfy the transient overvoltage limits specified in the **Bilateral Agreement**.

ECC.6.3.19.5.6 For the purposes of this requirement, the maximum rated current would be the **Peak Current** **Rating** declared by the **Grid Forming Plant** owner in accordance with Table ECC.6.3.19.3.2 of ECC.6.3.19.3(ix).

ECC.6.3.19.5.7 Each **Grid Forming Plant** shall be designed to ensure a smooth transition between voltage control mode and **Fault Ride Through** mode in order to prevent the risk of instability which could arise in the transition between the steady state voltage operating range as defined under CC.6.1.4 or ECC.6.1.4 (as applicable) and abnormal conditions where the retained voltage falls below 90% of nominal voltage. Such a requirement is necessary to ensure adequate performance between the pre-fault operating condition of the **Grid Forming Plant** and its subsequent behaviour under faulted conditions. **Grid Forming Plant** owners are required to both advise and agree with **The Company** the control strategy employed to mitigate the risk of such instability.

ECC.6.3.19.5.8. Each **Grid Forming Plant** shall be designed to reduce the risk of transient over voltage levels arising following clearance of the fault and in order to mitigate the risk of any form of instability which could result. The requirements for the maximum transient overvoltage withstand capability and associated time duration, shall be agreed between the **User** or **Non-CUSC Party** and **The Company** as part of the **Bilateral Agreement**.

ECC.6.3.19.5.9 In addition to the requirements of CC.6.3.15 or ECC.6.3.15, each **Grid Forming Plant** owner is required to confirm to **The Company**, their repeated ability to supply **Fast Fault Current** to the **System** each time the voltage at the **Grid Entry Point** or **User System Entry Point** falls outside the limits specified in CC.6.1.4 or ECC.6.1.4 (as applicable). **Grid Forming Plant** ownersshould inform **The Company** of the maximum number of repeated operations that can be performed under such conditions and any limiting factors to repeated operation such as protection or thermal rating.

ECC.6.3.19.5.10 In the case of a **Power Park Module** or **DC Connected Power Park Module**, where it is not practical to demonstrate the compliance requirements of ECC.6.3.19.5.1 to ECC.6.3.19.5.5 at the **Grid Entry Point** or **User System Entry Point**, **The Company** will accept compliance of the above requirements at the **Power Park Unit** terminals.

ECC.6.3.19.5.11 In the case of an unbalanced fault, each **Grid Forming Plant**,shall be required to inject current which shall as a minimum increase with the fall in the unbalanced voltage without exceeding the transient **Peak Current Rating** of the **Grid Forming Plant** (or constituent element thereof).

ECC.6.3.19.5.12 In the case of an unbalanced fault, the **User** or **Non-CUSC Party** shall confirm to **The Company** their ability to prevent transient overvoltages arising on the remaining healthy phases and the control strategy employed.

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ECC.6.6.1.8 The facilities for quality of supply and dynamic system behavior monitoring shall include arrangements for the **HVDC System Owner** and **The Company** and/or **Relevant Transmission Licensee** to access the information electronically. The communications protocols for recorded data shall be agreed between the **HVDC System Owner**, **The Company** and the **Relevant Transmission Licensee**.

ECC.6.6.1.9 In order to accurately monitor the performance of a **Grid Forming Plant**, each **Grid Forming Plant** shall be equipped with a facility to accurately record the following parameters at a rate of 10ms : -

* **System Frequency** using a nominated algorithm as defined by **The Company**
* The **ROCOF** rate using a nominated algorithm as defined by **The Company** based on a 500ms rolling average
* A technique for recording the **Grid Phase Jump Angle** by using either a nominated algorithm as defined by **The Company** or an algorithm that records the time period of each half cycle with a time resolution of 10 microseconds. For a 50Hz **System**, a 1 degree phase jump is a time period change of 55.6 microseconds. .

ECC.6.6.1.10 Detailed specifications for **Grid Forming Capability** dynamic performance including triggering criteria and sample rates are listed as **Electrical Standards** in the **Annex** to the **General Conditions**. For **Grid Forming Capability** dynamic monitoring, the specification for the communication protocol and recorded data shall also be included in the **Electrical Standard**.

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ECC.6.6.3.2 The signals which shall be provided by the **User** to **The Company** for onsite monitoring shall be of the following resolution, unless otherwise agreed by **The Company**:

(i) 1 Hz for reactive range tests

(ii) 10 Hz for **System Frequency** control tests

(iii) 100 Hz for voltage control tests

(iv) 1 kHz for **Grid Forming Plant** signals including fast fault current measurements

(v) 100Hz for the other **Grid Forming Plant** tests carried out in accordance with ECC.6.6.1.9

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**Extracts from the European Compliance Processes**

**EUROPEAN COMPLIANCE PROCESSES**

# ECP.1 INTRODUCTION

ECP.1.1 The **European** **Compliance Processes** ("**ECP**") specifies the compliance process in relation to directly connected and **Embedded Power Stations** (subject to a **Bilateral Agreement**), **HVDC Systems**, **Grid Forming Plant** and **Network Operator’s** or **Non-Embedded Customer’s** **Plant** and **Apparatus**.For the avoidance of doubt, the requirements of the **European Compliance Processes** do not apply to **Demand Response Providers** unless they are also an **EU Code User** and have entered into a **CUSC Contract** with **The Company**. **Generators** in respect of **Electricity Storage Modules** are required to meet the requirements of this **ECC** but are not required to satisfy the requirements of **European Regulation** (EU) 2016/631, **European Regulation** 2016/1388 or **European Regulation** 2016/1485. Any derogation in respect of **Electricity Storage Modules** would therefore be against the GB Grid Code as the requirements applicable to **Electricity Storage Modules** are not enforceable by EU Law:

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# ECP.3 SCOPE

ECP.3.1 The **ECP** applies to **The Company** and to **Users**, which in the **ECP** means:

1. **EU Generators** (other than in relation to **Embedded** **Power Stations** not subject to a **Bilateral Agreement**) including those undertaking **OTSDUW**.
2. **Network Operators** who are either;
3. **EU Code Users** in respect of theirentire distribution **System;** or
4. **GB Code Users** in respect of their **EU Grid Supply Points** only

(c) **Non-Embedded Customers** who are **EU Code Users;**

1. **HVDC System Owners** (other than those which only have **Embedded HVDC Systems** not subject to a **Bilateral Agreement**).
2. **Grid Forming Plant Owners** who own and operate a Grid Forming Plant and intend to satisfy the requirements of ECC.6.3.19

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ECP.4.2 The provisions contained in ECP.5 to ECP.7 detail the process to be followed in order for the **User’s Plant** and **Apparatus** (including **OTSUA**) to becomeoperational. This process includes

1. the acceptance of an **Installation Document** for a **Type A Power Generating Module**;
2. for energisation an **EON** for **Type B**, **Type C** or **Type D Power Generating Modules**,or **HVDC Equipment**, **Grid Forming Plant** or **Network Operator’s** or **Non-Embedded Customer’s Plant** and **Apparatus**;
3. for synchronising an **ION** for **Type B**, **Type C** or **Type D Power Generating Modules** or **HVDC Equipment**;
4. for operating by using the **Grid Supply Point** an **ION** for;
   1. **Network Operators** who are **EU Code Users** in respect of their entire distribution **System;**
   2. **Network Operators** who are **GB Code Users** in respect of their **EU Grid Supply Points** only; or
   3. **Non-Embedded Customers** who are **EU Code Users;**
5. for final certification a **FON**.

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ECP.4.2.2 The provisions contained in ECP.6 and ECP.7 provide the process for **Generators**, **HVDC System Owners**, **Grid Forming Plant Owners**, **Network Operators** and **Non-Embedded Customers** to demonstrate compliance with the **Grid Code** and with, where applicable, the **CUSC Contract(s)** prior to and during the course of such **Generator’s**, **HVDC System Owner’s** (including **OTSUA** up to the **OTSUA Transfer Time**), **Network Operator’s** and **Non-Embedded Customer’s** **Plant** and **Apparatus**) becomingoperational.

ECP.4.2.3 The provisions contained in ECP.8 detail the process to be followed when:

(a) a **Generator’s** or **HVDC System Owner**’s,or **Grid Forming Plant Owner’s**,or **Network Operator’s** or **Non-Embedded Customer’s** **Plant** and/or **Apparatus** (including the **OTSUA**) is unable to comply with any provisions of the **Grid Code** and **Bilateral Agreement**; or,

(b) following any notification by a **Generator** or a **HVDC System Owner** or a **Grid Forming Plant Owner** ora **Network Operator** or a **Non-Embedded Customer** under the **PC** of any change to its **Plant** and **Apparatus** (including any **OTSUA**); or,

(c) a **Modification** toa **Generator’s** or a **HVDC System Owner’s** or a **Grid Forming Plant Owner’s** or a **Network Operator’s** or a **Non-Embedded Customer’s** **Plant** and/or **Apparatus**.

ECP.4.2.4 For **Grid Forming Plant Owners** the Operational Notification Process of this ECP shall apply in relation to the type of **Plant** to which the **Grid Forming Capability** is provided (be it a **GBGF-S** or **GBGF-I**),

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ECP.10.7 In the case of a co-located site, for example **Electricity Storage Modules** or **GB Grid Forming Plant** connected within a new or existing **Power Station**, **The Company** will accept demonstration of compliance at the **Grid Entry Point** or **User System Entry Point** (if **Embedded**) through a combination of the capabilities of the **Power Generating Modules** and **Electricity Storage Modules** (which could include **GB Grid Forming Plant**) or **Electricity Storage Modules** and **Generating Units** or **Power Park Modules** (which could include **Grid Forming Plant**). **Generators** or **GB Grid Forming Plant Owners** should however be aware that for the purposes of compliance, full Grid Code compliance should be demonstrated when, for example, the **Electricity Storage Module** or **Grid Forming Plant** is out of service and the remaining **Power Generating Module** is in service or the **Electricity Storage Module** or **Grid Forming Plant** is in service and the **Power Generating Module** is out of service. Equally, **The Company** will accept **Manufacturer’s Data & Performance Reports** for the purposes of proving compliance at co-located sites.

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ECP.A.3.1.6 In the case of a co-located site, for example **Electricity Storage Modules** or **GB Grid Forming Plant** connected within a new or existing **Power Station**, **The Company** will accept simulation studies to demonstrate compliance at the **Grid Entry Point** or **User System Entry Point** (if **Embedded**) through a combination of the capabilities of the **Power Generating Modules** (which could include **GB Grid Forming Plant**) and **Electricity Storage Modules** or **Electricity Storage Modules** (which could include **GB Grid Forming Plant**) and **Generating Units** or **Power Park Modules**. **Generators** should however be aware that for the purposes of simulations, full Grid Code compliance should be demonstrated when, for example, the **Electricity Storage Module** or **GB** **Grid Forming Plant** is out of service and the remaining **Power** **Generating** **Module** is in service or the **Electricity Storage Module** or **Grid Forming Plant** is in service and the **Power Generating Module** is out of service.

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ECP.A.5.1.8 In the case of a co-located site, for example **Electricity Storage Modules** or **GB Grid Forming Plant** connected within a new or existing **Power Station**, **The Company** will accept test results to demonstrate compliance at the **Grid Entry Point** or **User System Entry Point** (if **Embedded**) through a combination of the capabilities of the **Power Generating Modules** (which could include **GB Grid Forming Plant**) and **Electricity Storage Modules** or **Electricity Storage Modules** (which could include a **GB Grid Forming Plant**) and **Generating Units** or **Power Park Modules**. **Generators** should however be aware that for the purposes of testing, full Grid Code compliance should be demonstrated when, for example, the **Electricity Storage Module** or **GB Grid Forming Plant** is out of service and the remaining **Power Generating Module** is in service or the **Electricity Storage Module** or **GB Grid Forming Plant** is in service and the **Power Generating Module** is out of service. In the case of a **Synchronous Electricity Storage Module**, **The Company** would expect the full set of tests to be completed as detailed in ECP.A.5.2 to ECP.A.5.9.

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ECP.A.6.1.10 In the case of a co-located site, for example **Electricity Storage Modules** or **GB Grid Forming Plant** connected within a new or existing **Power Station**, **The Company** will accept test results to demonstrate compliance at the **Grid Entry Point** or **User System Entry Point** (if **Embedded**) through a combination of the capabilities of the **Power Generating Modules** (which could include a **GB Grid Forming Plant**) and **Electricity Storage Modules** or **Electricity Storage Modules** (which could include a **GB Grid Forming Plant**) and **Generating Units** or **Power Park Modules**. **Generators** should however be aware that for the purposes of testing, full Grid Code compliance should be demonstrated when, for example, the **Electricity Storage Module** or **GB Grid Forming Plant** is out of service and the remaining **Power Generating Module** is in service or the **Electricity Storage Module** or **GB Grid Forming Plant** is in service and the **Power Generating Module** is out of service. In the case of a **Non-Synchronous** **Electricity Storage Module**, **The Company** would expect the full set of tests to be completed as detailed in ECP.A.6.2 to ECP.A.6.8.

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**APPENDIX 3**

ECP.A.3.9 **Grid Forming Plant** verification and validation

ECP.A.3.9.1 This section applies to **Users** and **Non CUSC Parties** who own and operate **GBGF-I Plant** to demonstrate the ability of their **Grid Forming Plant** to satisfy the requirements of ECC.6.3.19. For the avoidance of doubt these requirements are not necessary from owner and operators of **GBGF-S Plant**.

ECP.A.3.9.2 For initial approval **Users** and **Non CUSC Parties** are required to submit the following data of their **Grid Forming Plant** to **The Company**: -

1. The representation of their **Grid Forming Plant** in a format either the same as Figure PC.A.5.8.1 of PC.A.5.8.1 or in an equivalent format.
2. The data associated with their **Grid Forming Plant** as required in PC.A.5.8.1 ~~Table ECC.6.3.19.3.1 and Table ECC.6.3.19.3.2 of ECC.6.3.19.3.~~
3. A linearised model and parameters of the **Grid Forming Plant** in the frequency domain in the same format as required in PC.A.5.8.1 ~~Figure ECC.6.3.19.3.2(a) or Figure ECC.6.3.19.3.2 (b) as shown in ECC.6.3.19.3(viii)~~ or equivalent.
4. A **Network Frequency Perturbation Plot** with a **Nichols Chart** demonstrating the equivalent **Damping Factor**.
5. For the items a) to d) the **User** or **Non-CUSC Party** can submit the data in any equivalent format as agreed with **The Company**.

ECP.A.3.9.3 For **GBGF-I** **Plant** the **User** or **Non-CUSC Party** may be required to supply other versions of the **Network Frequency Perturbation Plot** for different input and output signals as defined by **The Company**.

ECP.A.3.9.4 For final approval **Users** and **Non CUSC Parties** are required to demonstrate that the **GBGF\_I** **Plant** model is capable of supplying **Active** **ROCOF Response Power**, and **Active** **Phase Jump Power**, and submit a full 3 phase simulation study in the time domain representing the response of the **Grid Forming Plant** over a range of operating conditions. The simulation study shall comprise of the following stages.

1. A simulation study to the equivalent shown in Figure ECP.A.3.9.4.



Figure ECP.A.3.9.4

1. The first simulation test is to demonstrate that the **GBGF-I Plant** model is capable of supplying **Active** **ROCOF Response Power** to the **Total System** as a result of a **System Frequency** change. In this simulation, with the **Grid Forming Plant** initially running at **Registered Capacity** or **Maximum Capacity**, the Grid **System Frequency** is increased from 50Hz to 51Hz at a rate of 1Hz/s with measurements of the **Grid Forming Plant’s Active ROCOF Response Power**, **System Frequency** and time in (ms). The simulation is required to assess correct operation of the **Grid Forming Plant** without saturating. Repeat for 50Hz to 49Hz at 1Hz.s
2. The second simulation test is to demonstrate the **GBGF-I Plant’s** ability to supply **Active** **ROCOF Response Power** and asses its withstand capability under extreme **System Frequencies**. The Grid **System Frequency** is increased from 50Hz to 52Hz at a rate of 1Hz/s with measurements of the **Active** **ROCOF Response Power**, **System Frequency** and time in (ms). This is repeated when the Grid **System Frequency** is increased from 50Hz to 52Hz at a rate of 2 Hz/s with measurements of the **Active** **ROCOF Response Power**, **System Frequency** and time in (ms). Repeat for 50Hz to 48 Hz at 1 Hz/s and 50Hz to 48 Hz at 2 Hz/s.
3. The third simulation is to demonstrate the **Grid Forming Plant’s** ability to supply **Active** **ROCOF Response Power** over the full **System Frequency** range.
4. With the **System Frequency** set to 50Hz, the **Grid Forming Plant** should be initially running at 75% **Maximum Capacity** or **75% Registered Capacity**, zero MVAr output and both **Limited Frequency Sensitive Mode** and **Frequency Sensitive Mode** disabled.
5. The **System Frequency** is then increased from 50Hz to 52Hz at a rate of 1Hz/s over a 2 second period. Allow conditions to stabilise for 5 seconds and then decrease the **System Frequency** from 52Hz to 47Hz at a rate of 1Hz/s over a 5 second period. Allow conditions to stabilise.
6. Record results of phase based **Active** **ROCOF Response Power**, **Reactive Power**, voltage and **System Frequency**.
7. The simulation now needs to be re-run in the opposite direction. The same initial conditions should be applied as per ECP.A.3.9.2iv) (a).
8. The **System Frequency** is then decreased from 50Hz to 47Hz at a rate of 1Hz/s over a 3 second period. Allow conditions to stabilise for 5 seconds and then increase the **System Frequency** from 47Hz to 52Hz at a rate of 1Hz/s over a 5 second period. Allow conditions to stabilise.
9. Record results of **Active** **ROCOF Response Power**, **Reactive Power**, voltage and **System Frequency**.
10. The simulation is required to ensure the **Grid Forming Plant** can deliver **Active** **ROCOF Response Power** without going into saturation and that a behaviour that is equivalent to pole slipping does not occur.
11. The fourth simulation is to demonstrate the **Grid Forming Plant’s** ability to supply **Active Phase Jump Power** under normal operation.
12. With the **System Frequency** set to 50Hz, the **Grid Forming Plant** should initially be running at **Maximum Capacity** or **Registered Capacity** ora suitable loading point to demonstrate **Grid Forming Capability** as agreed with **The Company**, zero MVAr output and all control actions (e.g., **Limited Frequency Sensitive Mode**, **Frequency Sensitive Mode** and voltage control) disabled.
13. Apply a positive phase jump of the **Phase Jump Angle Limit** value at the **Grid Entry Point** or **User System Entry Point.**
14. Record traces of **Active Power**, **Reactive Power**, voltage, current and **System Frequency** for a period of 10 seconds after the step change in phase has been applied. Repeat with a negative phase jump.
15. The fifth simulation is to demonstrate the **Grid Forming Plant’s** ability to supply **Active** **Phase Jump Power** under extreme conditions.
16. With the **System Frequency** set to 50Hz, the **Grid Forming Plant** should be initially running at its **Minimum Stable Operating Level or Minimum Stable Generation**, zero MVAr output and all control actions (e.g., **Limited Frequency Sensitive Mode**, **Frequency Sensitive Mode** and voltage control) disabled.
17. Apply a phase jump equivalent to the positive **Phase Jump Angle Withstand** value at the **Grid**.
18. Record traces of **Active Power**, **Reactive Power**, voltage, current and **System Frequency** for a period of 10 seconds after the step change in phase has been applied. Repeat with a negative phase jump.
19. Repeat steps (a), (b) and (c) of ECP.A.3.9.4(vi) but on this occasion apply a phase jump equivalent to the positive **Phase Jump Angle Limit** at the Grid.
20. The sixth simulation is to demonstrate the **Grid Forming Plant’s** ability to supply **Fault Ride Through** and **Fast Fault Current Injection** during a faulted condition
21. With the **System Frequency** set to 50Hz, the **Grid Forming Plant** should be initially running at its **Maximum Capacity** or **Registered Capacity**, zero MVAr output and all control actions (e.g., **Limited Frequency Sensitive Mode**, **Frequency Sensitive Mode**, **Fast Fault Current Injection**, **Fault Ride Through** and voltage control other than current limiters) disabled.
22. Apply a solid three phase short circuit fault at the **Grid Entry Point or User System Entry Point** for 140ms.
23. Record traces of **Active Power**, **Reactive Power**, voltage, current and **System Frequency** for a period of 10 seconds after the fault has been applied. The **GBGF-I Plant’s** current limit should be observed to operate.
24. Repeat steps (a) to (c) but on this occasion with **Fault Ride Through**, **Fast Fault Current Injection**, **Limited Frequency Sensitive Mode** and voltage control switched into service.
25. Record traces of **Active Power**, **Reactive Power**, voltage, current and **System Frequency** for a period of 10 seconds after the fault has been applied and confirm correct operation.

ECP.A.3.9.5 To demonstrate the **GBGF-I** **Plant** model is capable of supplying **Active** **ROCOF Response Power** and **Active** **Phase Jump Power**, under extreme conditions the **Grid Forming** **Plant** owner shall submit a simulation study representing the response of the **Grid Forming Plant**. To demonstrate the performance of the **Grid Forming Plant** under these conditions, the simulation study shall represent the following scenario.

1. The **User** or **Non CUSC Party** in respect of **GBGF-I Plant** should supply a simulation study to **The Company** equivalent to Figure ECP.A.3.9.5.



Figure ECP.A.3.9.5

1. In this simulation (as shown in Figure ECP.A.3.9.5) the parameters of the variable frequency Grid shall be supplied by **The Company**. The Load Y is also defined by **The Company.**
2. With the system running in steady state the **GBGF-I Plant** and thevariable frequencyAC Gridshould each be running at load Y/2 with the **System Frequency** of the test network being 50Hz. All control actions (e.g., **Limited Frequency Sensitive Mode**, **Frequency Sensitive Mode** and voltage control) should be disabled.
3. With the system in steady state, apply a solid (zero impedance) three phase short circuit fault at point A of Figure ECP.A.3.9.3 and then open circuit breaker B, 140ms after the fault has been applied.
4. Record traces of **Active Power**, **Reactive Power**, voltage and **System Frequency** and record for a period of time after fault inception after allowing conditions to stabilise.

ECP.A.3.9.6 To demonstrate the **Grid Forming Plant** model is capable of contributing to **Active Damping Power**, the **GBGF-I Plant** owner is required to supply a simulation study by injecting a **Test Signal** in the time domain into the **GBGF-I Plant Owner’s** plant model.

The **GBGF-I Plant** model should take the equivalent form shown in either Figure ECP.A.3.9.6(a) or Figure ECP.A.3.9.6(b) as applicable. Each **User** or **Non-CUSC Party** can use their own design, that may be very different to Figures ECP.A.3.9.6(a) or ECP.A.3.9.6 (b) but should contain all relevant functions. In either case the following tests should be completed, and results supplied to verify the following criteria: -

Figure ECP.A.3.9.6(a)



Figure ECP.A.3.9.6(b)

1. Demonstration of **Damping** by injecting a **Test Signal** in the time domainat the **Grid Oscillation Value** and frequency into the **GBGF-I Plant** owner’s plant model. An acceptable performance would be judged when the result matches the **NFP Plot** declared by the **Grid Forming Plant** owner as submitted in PC.A.5.8.1(i)~~ECC.6.3.19.3(viii)~~.
2. Test i) is repeated with variations in the frequency of the **Test Signal** An acceptable performance would be judged when the result matches the **NFP Plot** declared by the **Grid Forming Plant** owner as submitted in PC.A.5.8.1(i) ~~ECC.6.3.19.3(viii)~~.
3. Demonstration of phase based **Active Control Output Power** (or Pc) by injecting a **Test Signal** into the **Grid Forming Plant** controller to demonstrate that the **Active** **Control Based Power** output is supplied below the 5Hz bandwidth limit An acceptable performance would be judged where the overshoot and decay matches the **Damping Factor** declared by the **Grid Forming Plant** owner as submitted in PC.A.5.8.1~~ECC.6.3.19.3(viii)~~ in addition to assessment against the requirements of CC.A.6.2.6.1 or ECC.A.6.2.6.1 or CC.A.7.2.2.5 or ECC.A.7.2.5.2 as applicable.

……………………………

Extracts from ECP Appendix 4

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ECP.A.4.3.6 In the case of a **GBGF-I** system, the following signals shall be supplied to **The Company** by the **Grid Forming Plant** owner in accordance with ECC.6.6.3. For the avoidance of doubt, **User’s** and **Non-CUSC Parties** would also be required to undertake the necessary testing of their **Plant** in accordance with the requirements of ECC.A.4 and OC5 as applicable.

|  |  |
| --- | --- |
|  | Each **Grid Forming Plant**  at **Grid Entry Point** or **User System Entry Point** |
| ECP.A.4.3.6(a)  Real Time Downloadable | Signals required shall be agreed with **The Company** in accordance with ECC.6.6.3.2(iv) and ECC.6.6.3.2(v) |

APPENDIX 9

COMPLIANCE TESTING FOR GRID FORMING PLANT

ECP.A.9.1 SCOPE

ECP.A.9.1.1 This Appendix outlines the general testing requirements for **Users** or **Non-CUSC Parties** to demonstrate compliance with the relevant aspects of the **Grid Code**, **Ancillary Services Agreement** and **Bilateral Agreement**. The tests specified in this Appendix will normally be sufficient to demonstrate compliance of a **GBGF-I** **Plant**, however **The Company** may:

1. agree to an alternative set of tests provided **The Company** deem the alternative set of tests sufficient to demonstrate compliance with the **Grid Code**, **Ancillary Services Agreement** and **Bilateral Agreement**; and/or
2. require additional or alternative tests if information supplied to **The Company** during the compliance process suggests that the tests in this Appendix will not fully demonstrate compliance with the relevant section of the **Grid Code**, **Ancillary Services Agreement** or **Bilateral Agreement**; and/or
3. require additional tests if control functions to improve damping of power system oscillations or additional functions to prove the capability of the **GBGF-I Plant** is required by the **Bilateral Agreement** or included in the control scheme; and/or
4. agree a reduced set of tests for the subsequent **GBGF-I Plant** following successful completion of the first **Grid Forming** tests in the case of an installation comprising of two or more **GBGF-I Plant’s** which **The Company** reasonably considers to be identical if: -

(a) the tests performed pursuant to ECP.A.9.1.9 in respect of subsequent **GBGF-I Plants** do not replicate the full tests for the first **GBGF-I Plant**; or

(b) any of the tests performed pursuant to ECP.A.9.1.9 do not fully demonstrate compliance with the relevant aspects of the **Grid Code**, **Ancillary Services Agreement** and / or **Bilateral Agreement.**

ECP.A.9.1.2 The **User or Non-CUSC Party** is responsible for carrying out the tests set out in and in accordance with this Appendix and the **User** or **Non-CUSC Party** retains the responsibility for the safety of personnel and plant during the test. **The Company** will witness all of the tests outlined or agreed in relation to this Appendix unless **The Company** decides and notifies the **User** or **Non-CUSC Party** otherwise. For all on site at **The Company** witnessed tests, the **User** or **Non-CUSC Party** must ensure suitable representatives from the **Grid Forming Plant’s** manufacturer (if appropriate) are available on site for the entire testing period. In all cases and in addition to any recording of signals conducted by **The Company**, the **User** or **Non-CUSC Party** shall record all relevant test signals as outlined in ECP.A.4.

ECP.A.9.1.3 In addition to the dynamic signals supplied in ECP.A.4, the **User or Non-CUSC Party** shall inform **The Company** of the following information prior to the commencement of the tests and any changes to the following, if any values change during the tests:

1. All relevant transformer tap numbers, if used.
2. Number of **Grid Forming Units** in operation.

ECP.A.9.1.4 The **User or Non-CUSC Party** shall submit a detailed schedule of tests to **The Company** in accordance with ECP.6.3.1, and this Appendix.

ECP.A.9.1.5 Prior to the testing of the **GBGF-I Plant** the **User** or **Non-CUSC Party** shall complete the **Integral Equipment Tests** procedure in accordance with OC.7.5.

ECP.A.9.1.6 Full **GBGF-I Plant** testing as required by ECP.7.2 is to be completed as defined in ECP.A.9.1.9.

ECP.A.9.1.7 **The Company** will permit relaxation from the requirements in ECP.A.9.1.9 where an **Equipment Certificate** for **GBGF-I Plant** has been provided which details the characteristics from tests on a representative installation with the same equipment and settings and the performance of the **GBGF-I Plant** can, in **The Company’s** opinion, reasonably represent that of the installed **GBGF-I Plant** at that site. The relevant **Equipment Certificate** must be supplied in the **Users Data File structure**.

ECP.A.9.1.8 Prior to any **GBGF-I Plant** tests taking place, the **User** or **Non-CUSC Party** shall have completed the relevant compliance tests on the **GBGF-I** **Plant, Power Generating Module** or **Generating Unit** as required under ECP.A.5 or OC5. A.2 (as relevant) or **Power Park Module** as required under ECP.A.6 or OC5. A.3 (as applicable) or **HVDC Systems** or **DC Converters** as required under ECP.A.7 or OC5. A.4 (as applicable).

ECP.A.9.1.9 Demonstration of **Grid Forming Capability**

ECP.A.9.1.9.1 This section details the procedure for demonstrating **Active** **ROCOF Response Power**. Ideally if the test is being completed as part of a type test on an isolated network and it is possible to change thefrequency of the isolated network then the tests should be completed using a variable network **Frequency**. **The Company** recognise that it is not possible in a large number of cases to adjust thenetwork frequencyof the network to which the **Grid Forming Plant** is connected. If a suitable test network is not available, performance of the **GBGF-I Plant** will need to be demonstrated through online monitoring as detailed in CC.6.6 or ECC.6.6 and simulation studies as required under ECP.A.3.9.4 would be required during the Interim Operational Notification Process as provided for under CP.6 or ECP.6 (as applicable).

ECP.A.9.1.9.2 In this test, with the **Grid Forming Plant** initially running at full load, the test network frequency is ideally increased from 50Hz to 51 Hz at a rate of 1Hz/s with measurements of the **Grid Forming Plant’s Active ROCOF Response Power**, **System Frequency** and time in (ms). The test is required to assess correct operation of the **Grid Forming Plant** without saturating. This test is then repeated for a 50 Hz to 49 Hz at a rate of 1Hz/s.

ECP.A.9.1.9.3 These tests are required to assess the **Grid Forming Plant’s** withstand capabilities under extreme **System Frequencies**.

(i) For **Grid Forming Plant** comprising a **GBGF-I** thefrequency of the test network is increased from 50Hz to 52Hz at a rate of 2Hz/s with measurements of the **Grid Forming Plant’s Active ROCOF Response Power**, **System Frequency** and time in (ms).

(ii) For a **Grid Forming Plant** comprising a **GBGF-I** thefrequency of the test network is increased from 50Hz to 52Hz at a rate of 1Hz/s with measurements of the **Grid Forming Plant’s Active ROCOF Response Power**, **System Frequency** and time in (ms).

(iii) For **Grid Forming Plant** comprising a **GBGF-I** thefrequencyof the test network is decreased from 50Hz to 47 Hz at a rate of 2Hz/s with measurements of the **Grid Forming Plant’s Active ROCOF Response Power**, **System Frequency** and time in (ms).

(iv) For **Grid Forming Plant** comprising a **GBGF-I** thefrequencyof the test network is decreased from 50Hz to 47 Hz at a rate of 1Hz/s with measurements of the **Grid Forming Plant’s Active ROCOF Response Power**, **System Frequency** and time in (ms).

ECP.A.9.1.9.4 This test is to demonstrate the **Grid Forming Plant’s** ability to supply **Active** **ROCOF Response Power** over the full **System Frequency** range.

1. With thefrequency of the test network set to 50Hz, the **GBGF-I Plant** should be initially running at 75% **Maximum Capacity or Registered Capacity**, zero MVAr output and both **Limited Frequency Sensitive Mode** and **Frequency Sensitive Mode** disabled.
2. The frequency is then increased from 50Hz to 52Hz at a rate of 1Hz/s over a 2 second period. Allow conditions to stabilise for 5 seconds and then decrease thefrequencyfrom 52Hz to 47Hz at a rate of 1Hz/s over a 5 second period. Allow conditions to stabilise.
3. Record results of **Active** **ROCOF Response Power**, **Reactive Power**, voltage and frequency.
4. The test now needs to be re-run in the opposite direction. The same initial conditions should be applied as per ECP.A.9.1.9.4(a).
5. Thefrequencyis then decreased from 50Hz to 47Hz at a rate of 1Hz/s over a 3 second period. Allow conditions to stabilise for 5 seconds and then increase the **frequency** from 47Hz to 52Hz at a rate of 1Hz/s over a 5 second period. Allow conditions to stabilise.
6. Record results of **Active** **ROCOF Response Power**, **Reactive Power**, voltage and frequency.

ECP.A.9.1.9.5 This test is to demonstrate the **Grid Forming Plant’s** ability to supply **Active** **Phase Jump Power** under normal operation.

1. With the frequency of the test network set to 50Hz, the **GBGF-I Plant** should be initially running at **Maximum Capacity** or **Registered Capacity** or at its agreed deloaded point, zero MVAr output and all control actions (e.g. **Limited Frequency Sensitive Mode**, **Frequency Sensitive Mode** and voltage control) disabled.
2. Apply a positive phase jump of up to the **Phase Jump Angle Limit** at the **Grid Entry Point** or **User System Entry Point** (if **Embedded**).
3. This test can then be repeated by injecting the same angle into the **Grid Forming Plant’s** control system (as indicatively shown in Figure ECP.A.9.1.9.5). This specific test can be repeated on site as required for a routine performance evaluation test. It should be noted that Figure ECP.A.9.1.9.5 is a simplified representation. Each **Grid Forming Plant Owner** can use their own design, that may be very different to Figure ECP.A.9.1.9.5 but should contain all relevant functions that can include test points and other equivalent data and documentation. Any additional signals, measurements, parameters and tests shall be agreed between the **Grid Forming Plant Owner** and **The Company**.
4. Repeat tests (b) and (c) with a negative injection up to the **Phase Jump Angle Limit**.
5. Record traces of **Active Power**, **Reactive Power**, voltage, current and frequency for a period of 10 seconds after the step change in phase has been applied.



Figure ECP.A.9.1.9.5

As part of these tests, the corresponding **Active Power** change resulting from a phase shift will be a function of the local reactance and the location of where the phase shift is applied in addition to additional upstream impedance between the **GBGF-I Plant** and phase step location.

ECP.A.9.1.9.6 This test is to demonstrate the **Grid Forming Plant’s** ability to supply **Active** **Phase Jump Power** under extreme conditions. Where it is not possible to undertake this test as part of a type test, **The Company** will accept demonstration through a combination of simulation studies as required under ECP.A.3.9.4(vi) and online monitoring as required under ECC.6.6.1.9.

1. With thefrequencyof the test network set to 50Hz, the **Grid Forming Plant** should be initially running at its **Minimum Stable Operating Level** or **Minimum Stable Generation**, zero MVAr output and all control actions (e.g., **Limited Frequency Sensitive Mode**, **Frequency Sensitive Mode** and voltage control) disabled.
2. Apply a phase jump of 60 degrees at the connection point of the **GBGF-I Plant** or into the **Grid Forming Plant’s** control system as shown in Figure ECP.A.9.1.9.5.
3. Record traces of **Active Power**, **Reactive Power**, voltage, current and frequency for a period of 10 seconds after the step change in phase has been applied.
4. Repeat steps (a), (b) and (c) of ECP.A.9.1.9.6 but on this occasion apply a phase jump equivalent to the positive **Phase Jump Angle Limit** at the Grid.

ECP.A.9.1.9.7 This test is to demonstrate the **GBGF-I Plant’s** ability to supply **Active** **Phase Jump Power**, **Fault Ride Through** and **Fast Fault Current Injection** during a faulted condition. Where it is not possible to undertake this test as part of a type test, **The Company** will accept demonstration through a combination of simulation studies as required under ECP.A.3.9.4(vii) and online monitoring as required under CC.6.6 and ECC.6.6.1.9.

1. With the frequency set to 50Hz, the **Grid Forming Plant** should be initially running at its **Maximum Capacity** or **Registered Capacity** or at an alternative loading point as agreed with **The Company**, zero MVAr output and all control actions (e.g., **Limited Frequency Sensitive Mode**, **Frequency Sensitive Mode** and voltage control) disabled.
2. Apply a solid three phase short circuit fault at the connection point in the test network forming part of the type test for 140ms or alternatively the equivalent of a zero retained voltage for 140ms.
3. Record traces of **Active Power**, **Reactive Power**, voltage, current and frequency for a period of 10 seconds after the fault has been applied.
4. Repeat steps (a) to (c) but on this occasion with fault ride through, **Fast Fault Current Injection** **Limited Frequency Sensitive Mode** and voltage control switched into service.
5. Record traces of **Active Power**, **Reactive Power**, voltage, current and frequency for a period of 10 seconds after the step change in phase has been applied and confirm correct operation.

ECP.A.9.1.9.8 The final test required is to demonstrate the **GBGF-I** **Plant** is capable of contributing to **Active Damping Power**. The **Grid Forming Plant** owner should configure their **Grid Forming Plant** in form or equivalent (as agreed with **The Company**) as shown in Figure ECP.A.3.9.6(a) or Figure ECP.A.3.9.6(b) as applicable. Each **Grid Forming Plant Owner** can use their own design, that may be very different to Figures ECP.A.3.9.6(a) or ECP.A.3.9.6 (b) but should contain all relevant functions.

As part of this test, the **Grid Forming Plant** owner is required to inject a signal into the **Grid Forming Plant** controller. The results supplied need to verify the following criteria:-

1. Inject a **Test Signal** into the **Grid Forming Plant** controller to demonstrate the **Active** **Control Based Power** output is supplied below the 5Hz bandwidth limit An acceptable performance would be judged where the overshoot or decay matches the **Damping Factor** declared by the **Grid Forming Plant** owner as submitted in PC.A.5.8.1~~ECC.6.3.19.3(viii)~~ in addition to assessment against the requirements of CC.A.6.2.6.1 or ECC.A.6.2.6.1 or CC.A.7.2.2.5 or ECC.A.7.2.5.2 as applicable.

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**Extracts from the Data Registration Code**

DRC.6 DATA TO BE REGISTERED

DRC.6.1 Schedules 1 to 20 ~~19~~ attached cover the following data areas.

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DRC.6.1.19 Schedule 19 – User Data File Structure

Comprising information relating to the **User Data File Structure**.

DRC.6.1.20 Schedule 20 – Grid Forming Plant Capability Data

Comprising information relating to **Grid Forming Plant Capability**

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**SCHEDULE 19 – USER DATA FILE STRUCTURE**

**PAGE 1 OF 2**

The structure of the **User Data File Structure** is given below.

| **i.d.** | **Folder name** | **Description of contents** |
| --- | --- | --- |
| **Part A: Commercial & Legal** | | |
| **A2** | Commissioning | Commissioning & Test Programmes |
| **A3** | Statements | Statements of Readiness |
| **A9** | AS Monitoring | Ancillary Services Monitoring |
| **A10** | Self-Certification | User Self Certification of Compliance |
| **A11** | Compliance statements | Compliance Statement |
| **Part 1: Safety & System Operation** | | |
| **1.1** | Interface Agreements | Interface Agreements |
| **1.2** | Safety Rules | Safety Rules |
| **1.3** | Switching Procedures | Local Switching Procedures |
| **1.4** | Earthing | Earthing |
| **1.5** | SRS | Site Responsibility Schedules |
| **1.6** | Diagrams | Operational and Gas Zone Diagrams |
| **1.7** | Drawings | Site Common Drawings |
| **1.8** | Telephony | Control Telephony |
| **1.9** | Safety Procedures | Local Safety Procedures |
| **1.10** | Co-ordinators | Safety Co-ordinators |
| **1.11** | RISSP | Record of Inter System Safety Precautions |
| **1.12** | Tel Numbers | Telephone Numbers for Joint System Incidents |
| **1.13** | Contact Details | Contact Details (fax, tel, email) |
| **1.14** | Restoration Plan | Local Joint Restoration Plan (incl. black start if applicable) |
| **1.15** | Maintenance | Maintenance Standards |
| **Part 2: Connection Technical Data** | | |
| **2.1** | DRC Schedule 5 | DRC Schedule 5 – Users System Data |
| **2.2** | Protection Report | Protection Settings Reports |
| **2.3** | Special Automatic Facilities | Special Automatic Facilities e.g. intertrip |
| **2.4** | Operational Metering | Operational Metering |
| **2.5** | Tariff Metering | Tariff Metering |
| **2.6** | Operational Comms | Operational Communications |
| **2.7** | Monitoring | Performance Monitoring |
| **2.8** | Power Quality | Power Quality Test Results (if required) |

**SCHEDULE 19 – USER DATA FILE STRUCTURE**

**PAGE 2 OF 2**

|  |  |  |
| --- | --- | --- |
| **Part 3: Generator Technical Data** | | |
| **3.1** | DRC Schedule 1 | DRC Schedule 1 - Generating Unit, Power Generating Module, HVDC System and DC Converter Technical Data |
| **3.2** | DRC Schedule 2 | DRC Schedule 2 - Generation Planning Data |
| **3.3** | DRC Schedule 4 | DRC Schedule 4 – Frequency Droop & Response |
| **3.4** | DRC Schedule 14 | DRC Schedule 14 – Fault Infeed Data – Generators |
| **3.5** | Special Generator Protection | Special Generator Protection eg Pole slipping; islanding |
| **3.6** | Compliance Tests | Compliance Tests & Evidence |
| **3.7** | Compliance Studies | Compliance Simulation Studies |
| **3.8** | Site Specific | Bilateral Connections Agreement Technical Data & Compliance |
| **3.9** | DRC Schedule 20 | DRC Schedule 20 - Grid Forming Capability Data |
| **Part 4: General DRC Schedules** | | |
| **4.1** | DRC Schedule 3 | DRC Schedule 3 – Large Power Station Outage Information |
| **4.2** | DRC Schedule 6 | DRC Schedule 6 – Users Outage Information |
| **4.3** | DRC Schedule 7 | DRC Schedule 7 – Load Characteristics |
| **4.4** | DRC Schedule 8 | DRC Schedule 8 – BM Unit Data (if applicable) |
| **4.5** | DRC Schedule 10 | DRC Schedule 10 –Demand Profiles |
| **4.6** | DRC Schedule 11 | DRC Schedule 11 – Connection Point Data |
| **Part 5: OTSDUW Data a~~A~~nd Information**  (if applicable and prior to **OTSUA Transfer Time**) | | |
|  |  | Diagrams |
|  |  | Circuits Plant and Apparatus |
|  |  | Circuit Parameters |
|  |  | Protection Operation and Autoswitching |
|  |  | Automatic Control Systems |
|  |  | Mathematical model of dynamic compensation plant |

**SCHEDULE 20 – GRID FORMING PLANT CAPABILITY DATA**

The following data need only be supplied by **Users** (be they a **GB Code User** or **EU Code User**) or **Non-CUSC Parties** who wish to offer a **Grid Forming Capability** as provided for ECC.6.3.19.3. Where such a **Grid Forming Capability** is provided then the following data items and models are to be supplied in respect of each Grid Forming Plant.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| DATA DESCRIPTION |  | GRID FORMING PLANT DATA | | |
|  |  | 1 | 2 | 3 |
| Submission of **Network Frequency Perturbation Plot** and **Nichols Chart** for each **GBGF-I Plant** (PC.A.5.8.1) | Graphs |  |  |  |
| High level equivalent architecture diagram of Grid Forming Plant (PC.A.5.8.1) | Diagram |  |  |  |
| **GBGF-I Grid Forming Plant** Block Diagram (Laplace Operator) in the general form shown in Figure PC.A.5.8.1 or as agreed with **The Company**.  When submitting either Figure PC.A.5.8.1 (a) or Figure PC.A.5.8.1 (b), each **User** or **Non-CUSC Party** can use their own design, that may be very different to Figures PC.A.5.8.1 (a) or PC.A.5.8.1 (b), but should contain all relevant functions that can include simulation models and other equivalent data and documentation | Block Diagram (Laplace Operator)  Documentation |  |  |  |
| Each **User** or **Non CUSC Party** shall provide a model of their **Grid Forming** **Plant** which provides a true and accurate reflection of its **Grid Forming Capability**. | Model and documentation – format to be agreed with **The Company** |  |  |  |

In order to participate in the **Grid Forming Capability** market, **User’s** and **Non-CUSC Parties** are required to provide data of their **GBGF-I** **Plant** in accordance with Figures PC.A.5.8.1(a) and PC.A.5.8.1(b) **Users** and **Non-CUSC Parties** in respect of **Grid Forming Plants** should indicate if the data is submitted on a unit or aggregated basis. The Table below defines the notation used in Figure PC.5.8.1

|  |  |  |
| --- | --- | --- |
| **Parameter** | **Symbol** | **Units** |
| The primary reactance of the **Grid Forming Unit**, in pu. | Xin or Xts | pu on MVA **Rating of Grid Forming Unit** |
| The additional reactance, in pu, between the terminals of the **Grid Forming Unit** and the **Grid Entry Point** or **User System Entry Point** (if **Embedded**). | Xtr | pu on MVA **Rating of Grid Forming Unit** |
| The rated angle between the **Internal Voltage Source** and the input terminals of the **Grid Forming Unit**. |  | radians |
| The rated angle between the **Internal Voltage Source** and **Grid Entry Point** or **User System Entry Point** (if **Embedded**). |  | radians |
| The rated voltage and phase of the **Internal Voltage Source** of the **Grid Forming Unit**. |  | Voltage - pu  Phase - radians |
| The rated electrical angle between current and voltage at the input to the Grid transformer. |  | radians |

In order to participate in a **Grid Forming Capability** market, **User’s** and **Non-CUSC Parties** are also required to provide the data of their **GBGF-I Plant** in accordance with the Table below to **The Company**. The details and arrangements for **Users** and **Non-CUSC Parties** participating in this market shall be published on **The Company’s Website**.

|  |  |  |  |
| --- | --- | --- | --- |
| **Quantity** | **Units** | **Range**  **(where Applicable)** | **User Defined Parameter** |
| Type of **Plant** (eg **Generating Unit**, **Electricity Storage Module**, **Dynamic Reactive Compensation Equipment** | N/A |  |  |
| Maximum Continuous Rating at **Registered Capacity** or **Maximum Capacity** | MVA |  |  |
| Primary reactance Xin or Xts(see Table 1) | pu on MVA |  |  |
| Additional reactance Xtr (See Table 1) | pu on MVA |  |  |
| **Maximum Capacity** | MW |  |  |
| **Active ROCOF Response Power** (MW) supplied or absorbed at 1Hz/s **System Frequency** change (which is the maximum frequency change for linear operation of the **Grid Forming Plant**) | MW |  |  |
| **Phase Jump Angle Withstand** | degrees |  | 60 degrees specified |
| **Phase Jump Angle limit** | degrees |  | 5 degrees recommended |
| **Phase Jump Power** (MW) at the rated angle | MW |  |  |
| **Defined Active Damping Power** for a **Grid Oscillation Value** of 0.5 Hz peak to peak at 1 Hz | MW |  |  |
| The cumulative energy delivered for a 1Hz/s **System Frequency** fall from 52 Hz to 47 Hz This is the total **Active Power** transient output of the **Grid Forming Plant** | MWs or MJ |  |  |
| Inertia Constant (H) using equation 1 or declared in accordance with the simulation results of ECP.A.3.9.4 | H |  |  |
| Inertia Constant (He) using equation 2 or declared in accordance with the simulation results of ECP.A.3.9.4 | He |  |  |
| Continuous Overload Capability | % on MVA |  |  |
| Short Term duration Overload capability |  |  |  |
| Duration of Short Term Overload Capability | s |  |  |
| **Peak Current Rating** | pu |  |  |
| Nominal **Grid Entry Point** or **User System Entry Point** voltage | kV |  |  |
| **Grid Entry Point** or **User System Entry Point** | - Location |  |  |
| Continuous or defined time duration MVA Rating | MVA |  |  |
| Continuous or defined time duration MW Rating | MW |  |  |
| For a **GBGF-I** **Plant** the inverters maximum **Internal Voltage Source** (**IVS**) for the worst case condition – for example operation at maximum exporting **Reactive Power** at the maximum AC **System** voltage | pu |  |  |
| Maximum Three Phase Short Circuit Infeed at **Grid Entry Point** or **User System Entry Point** | kA |  |  |
| Maximum Single Phase Short Circuit Infeed at **Grid Entry Point** or **User System Entry Point** | kA |  |  |
| Will the **Grid Forming Plant** contribute to any other form of commercial service – for example Dynamic Containment, Firm Frequency Response, | Details to be provided |  |  |
| **Equivalent Damping Factor.** | ζ |  | 0.2 to 5.0 allowed |

Table PC.A.5.8.2

Equation 1  is H = Installed MWs / Rated installed MVA

Equation 1

He = (**Active** **ROCOF Response Power** at 1 Hz / s x **System Frequency**) / ( Installed MVA x 2 )

Equation 2