

Enhanced Frequency Control Capability Project Dissemination Event



25th February 2016

Operability Challenges and Innovation SOF Relationship to the Future of Energy

Future Energy
Landscape



Performance
Requirements

Operational
Challenges

Solutions and
Opportunities

1

Services and Capabilities

It is essential that **new system services** are developed to access existing and new capabilities from both synchronous and asynchronous generation

2

Whole System Solutions

Transmission and distribution companies must consider the **whole system** impact of technologies and enable access to demand side resources

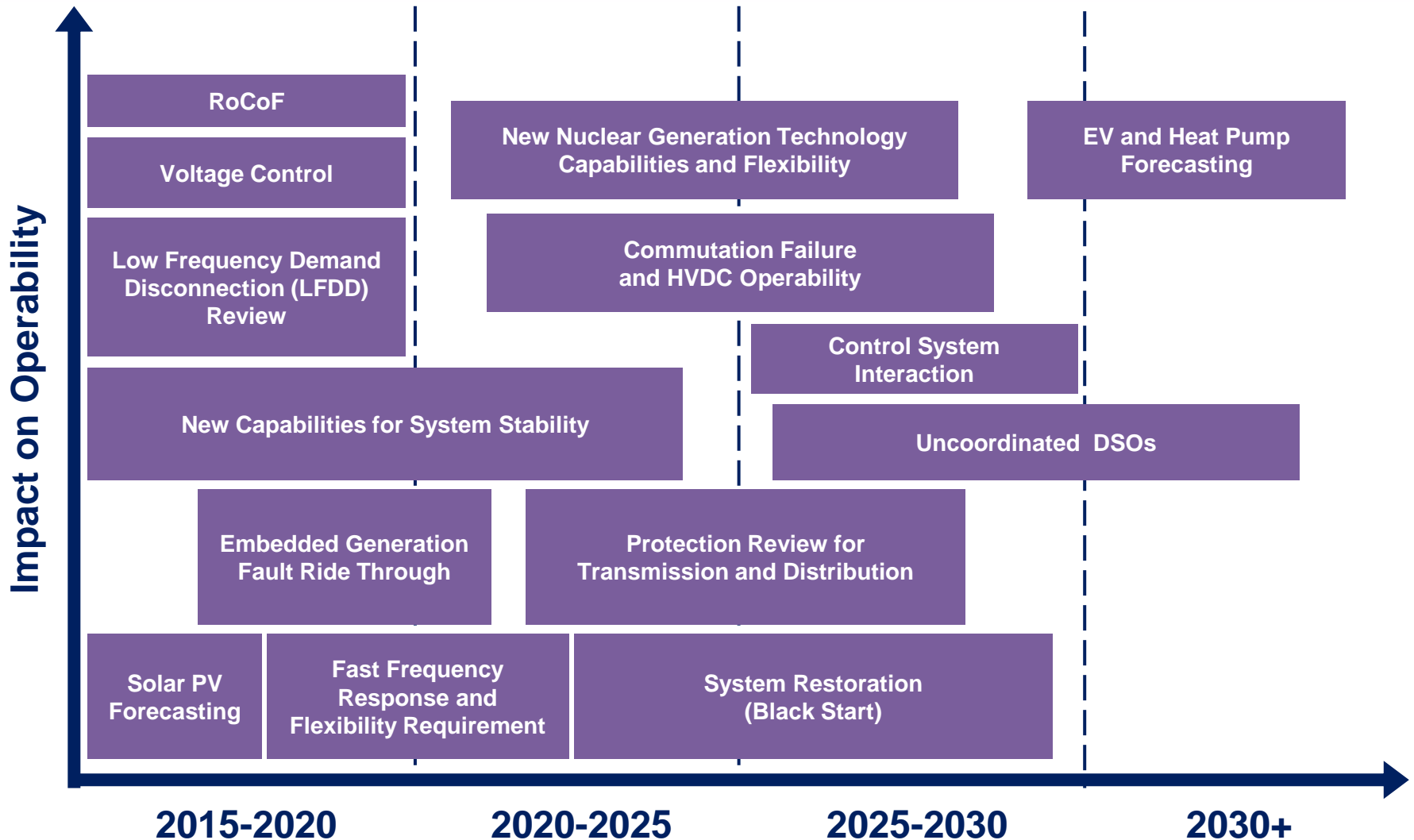
3

Increased Flexibility

The **value** of new system services, in particular **flexibility**, must be considered at the design stage by manufacturers and developers for future revenue streams

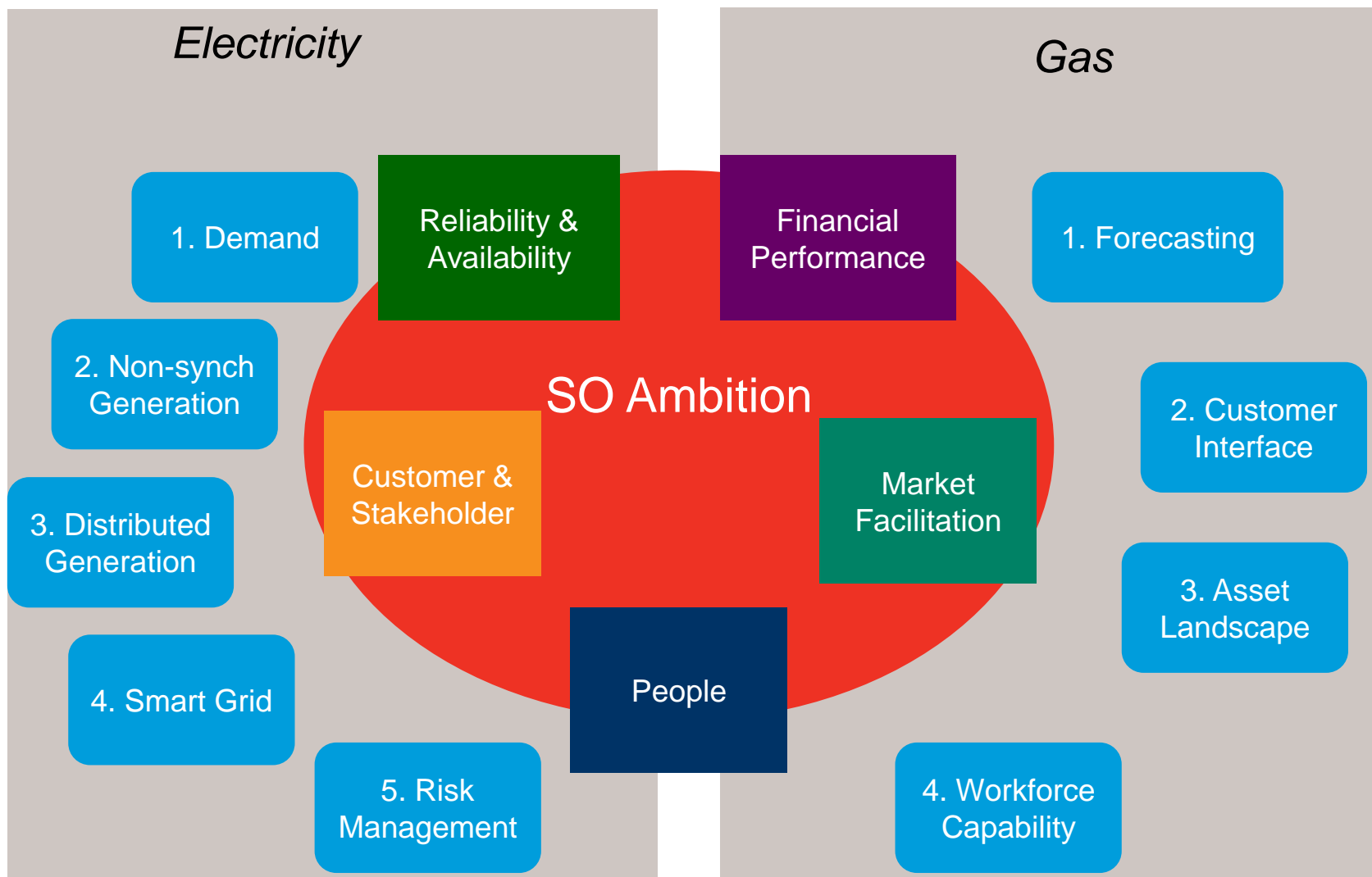
Operability Challenges and Innovation

Timeline of Operability Challenges



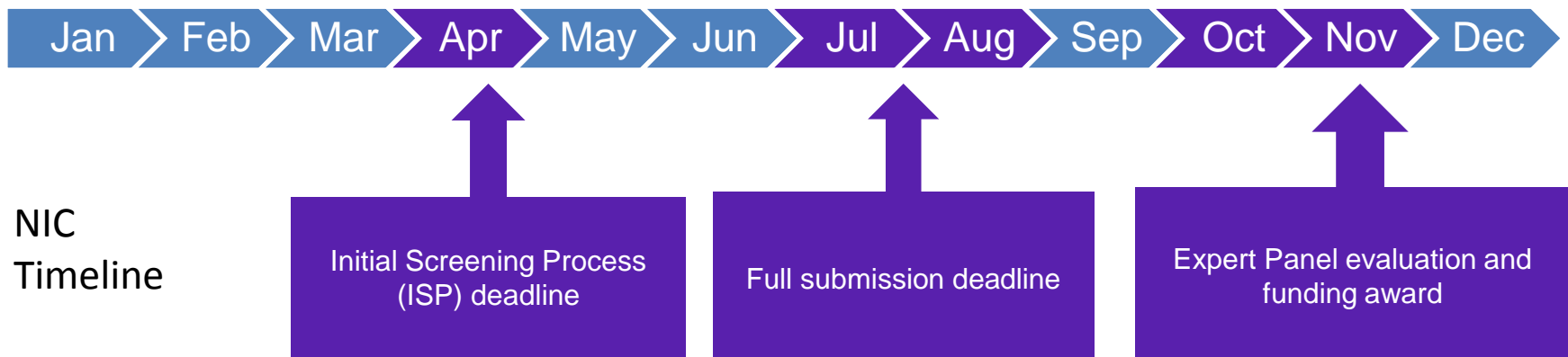
Operability Challenges and Innovation

National Grid SO Innovation Themes



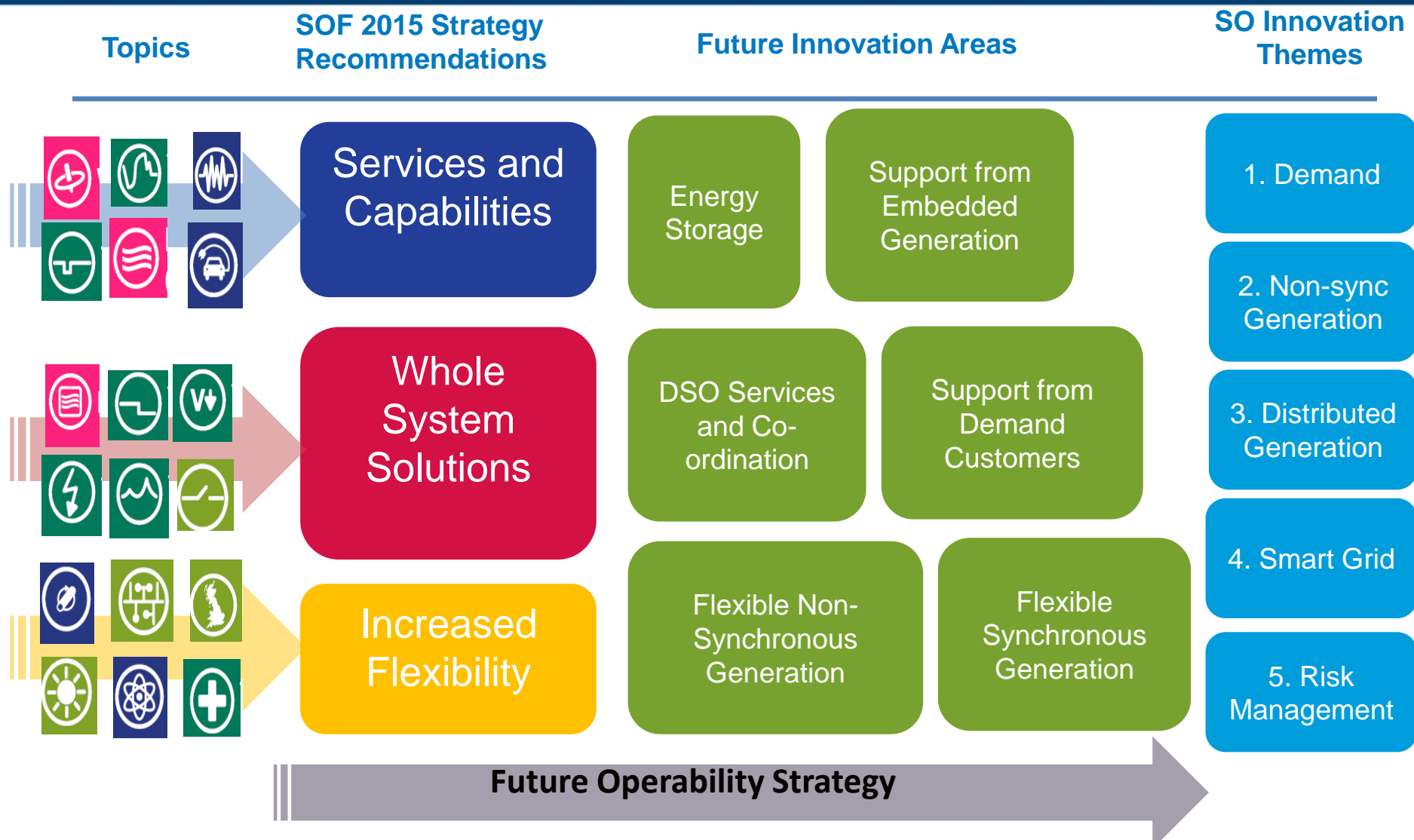
- Following the SOF 2014 we identified 2 major innovation projects:
 - Enhanced Frequency Control Capability Project ([Non-Synch Generation](#))
 - South East Smart Grid ([Smart Grid](#))
- Other ongoing projects include:
 - DIVIDE Voltage Dependent Load Behaviour ([Demand](#))
 - Control & Protection Challenges in Power Systems ([Non-Synch Generation](#))
 - PV Monitoring & Forecasting ([Distributed Generation](#))
 - Detection and Control of Inter Area Oscillations ([Non-Synch Generation](#))

- As in other areas, innovation is key to meeting network challenges.
- We already work with many partners nationally and internationally (e.g. DS3) on operability challenges and to identify innovation needs
- Innovation funding is available including our Network Innovation Allowance (NIA) and the Network Innovation Competition (NIC)
- We'd like ideas and support to develop further innovation projects.



Operability Challenges and Innovation

SOF 2015 Future Innovation Areas



- Enhanced Frequency Control Capability Project
 - Addresses key operability challenges.
 - Fits with our SOF 2015 Recommendations
 - Is a key part of our current innovation project portfolio.
 - Will develop the frequency services that we are going to need.
- The project has been running for around 12 months and we are starting to see tangible progress and outputs.

Network Innovation Competition: Enhanced Frequency Control Capability, EFCC (SMART Frequency Control)



Charlotte Grant
Technical Project Manager

Network Innovation Competition: Enhanced Frequency Control Capability, EFCC (SMART Frequency Control)



Video here

Frequency Limits

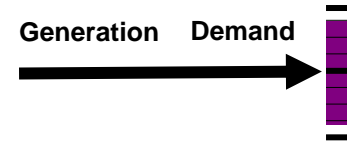


Generation



Demand

50.0 Hz



50.0

Normal operating frequency

50.5

Upper statutory limit

52.0

Generators tripping

49.5

Lower statutory limit

48.8

Demand disconnection starts

47.8

Demand disconnection complete



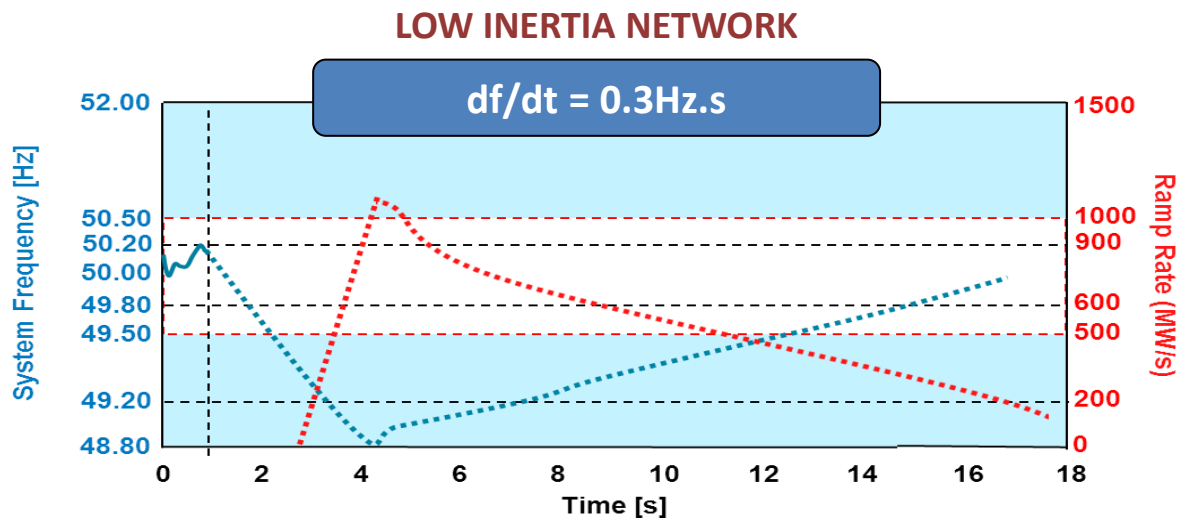
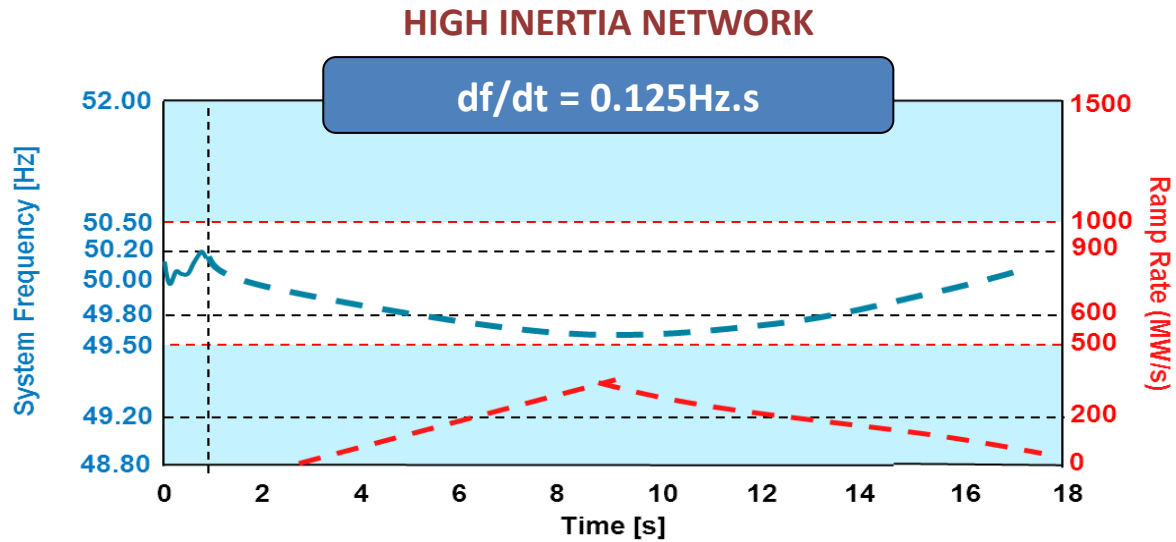
Balancing
Services
Types

Increase in demand (Primary Response)

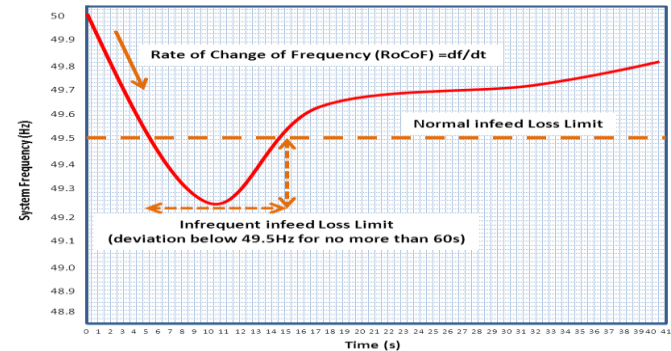
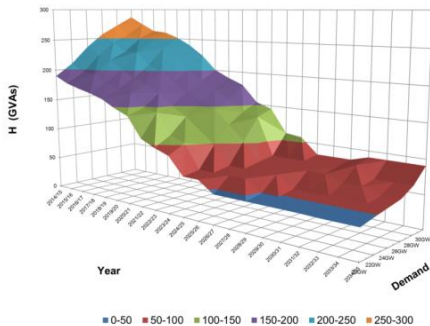
Decrease in demand (High Response)

Recovering system frequency (Secondary Response)

Reduction of System Inertia & Frequency Containment



Reduction of System Inertia & Cost of Frequency Control



Cost Benefit Analysis 2014

Balancing
Services
Methods

Solution

Cost (2020 Gone Green)

Constrain generators

Extra £600m

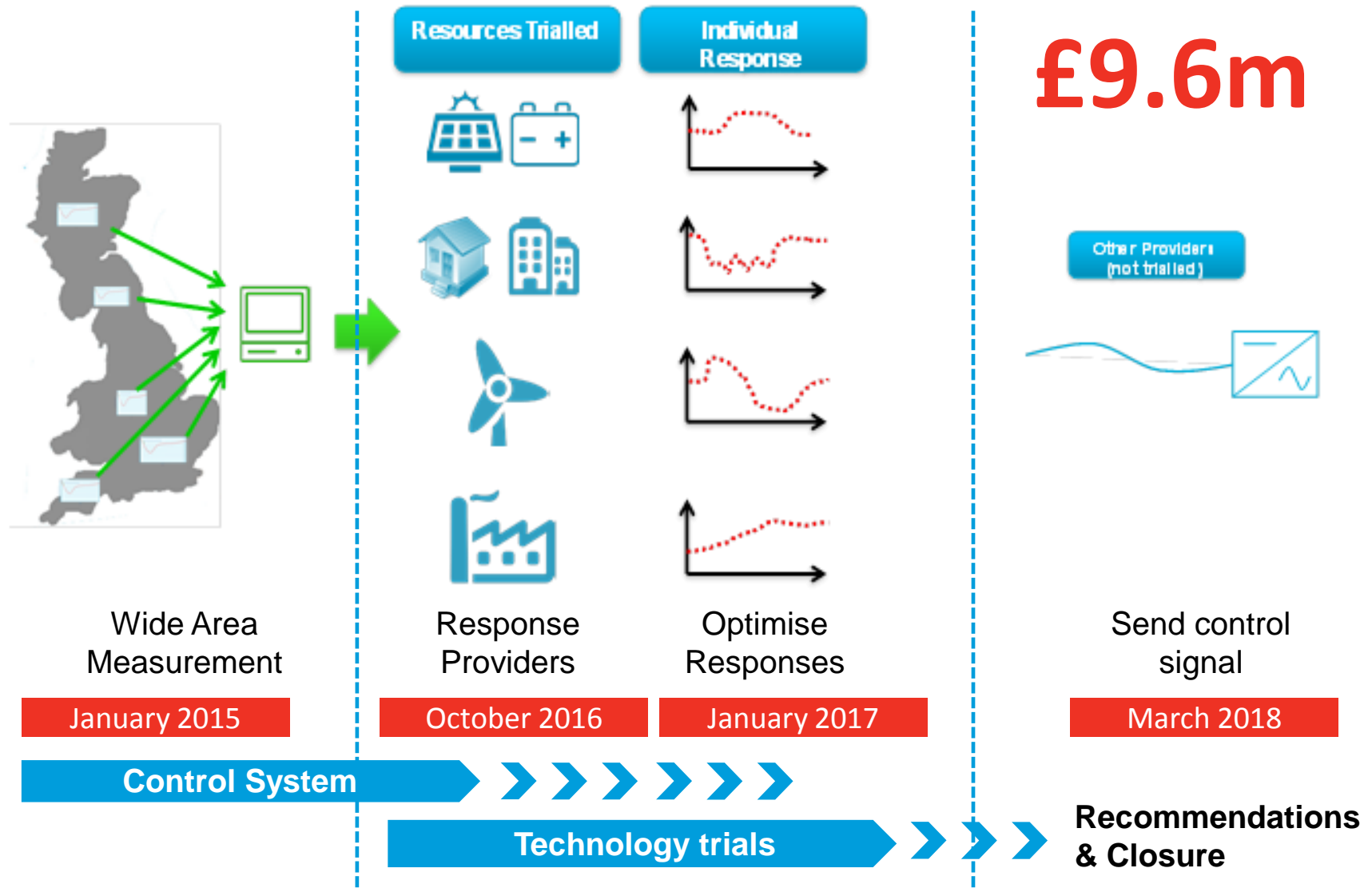
Constrain largest infeed/outfeed

Extra £130m-£270m (depending when the large infeeds are connected)

Carry larger volumes of response

Extra £210m

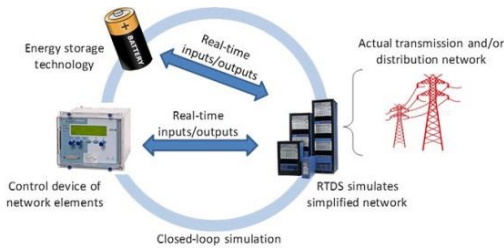
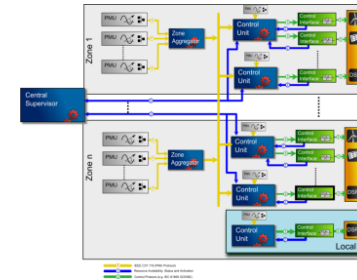
Enhanced Frequency Control Capability, EFCC (SMART Frequency Control Project)



Enhanced Frequency Control Capability, EFCC (SMART Frequency Control Project)



GE Grid Solutions
formerly Alstom



SMART Frequency Control



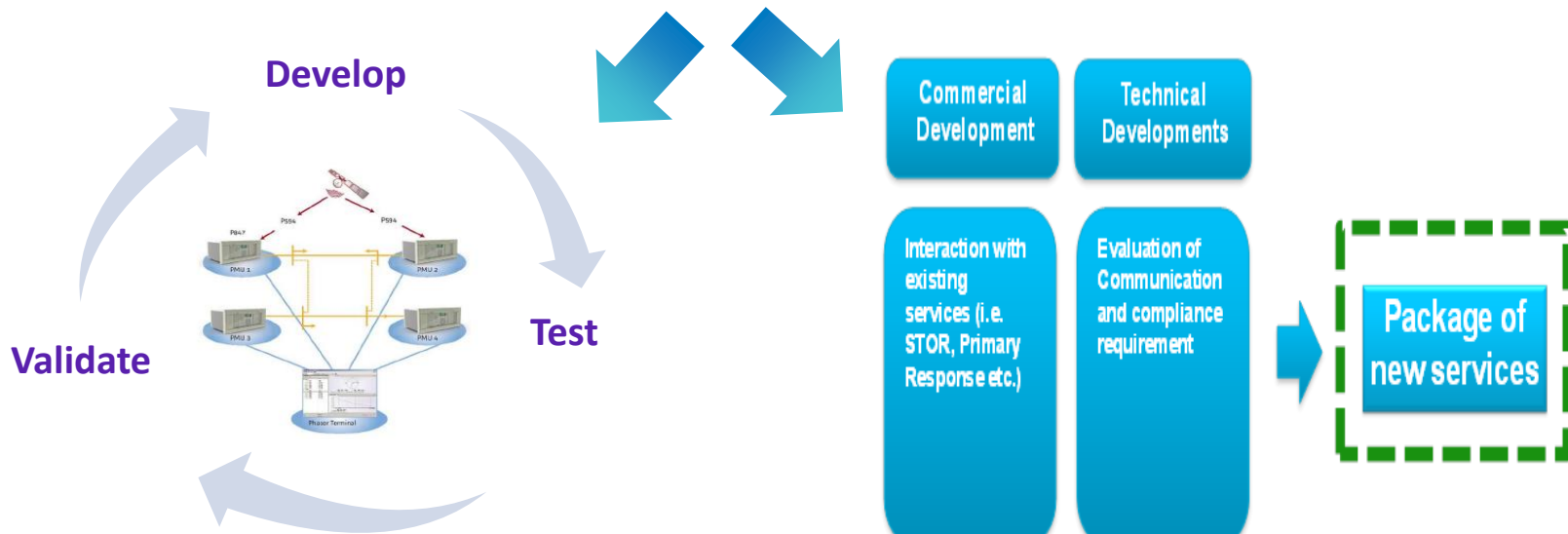
Enhanced Frequency Control Capability, EFCC (SMART Frequency Control Project)



VISOR Visualisation of Real Time System
Dynamics using Enhanced Monitoring



SMART Frequency Control



July 2015

March 2018

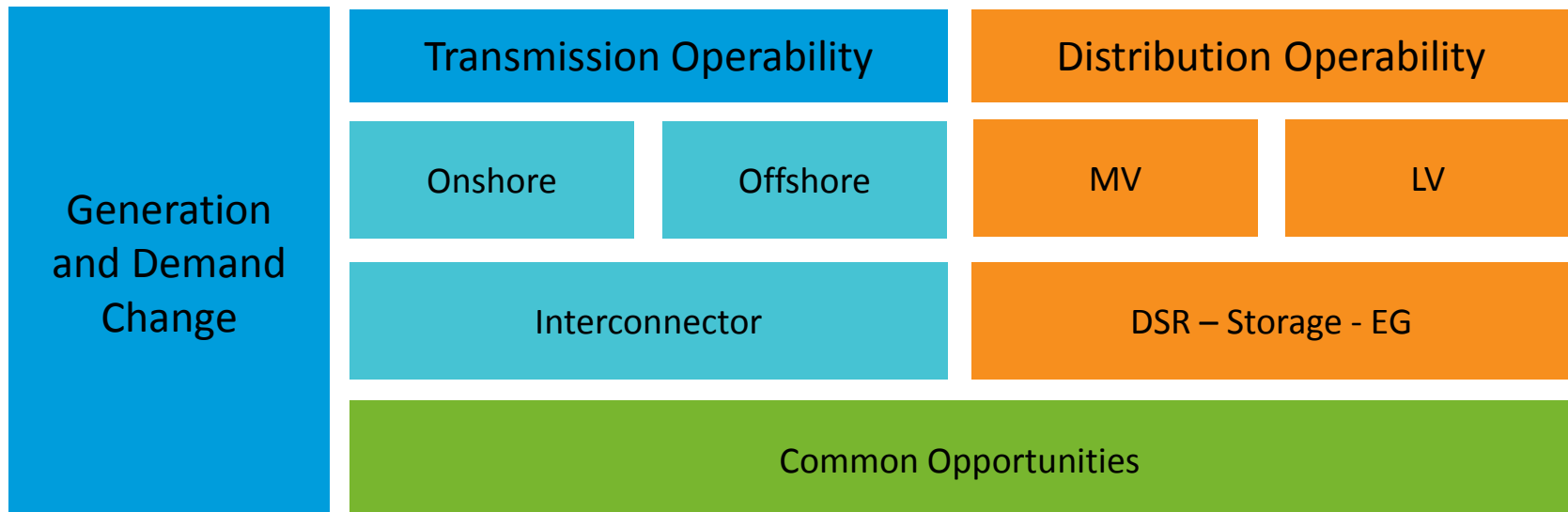
Commercial Service and IS Comms

Recommendations & Closure

SMART Frequency Control



GB Power System Operability





Wide-Area Frequency Control Scheme

Smart Frequency Control

Douglas Wilson & Seán Norris

25/02/2016



Imagination at work

GE proprietary information

Contents

1. SFC Technical Challenge
2. Control Scheme
3. Applications
4. Perspective of a Service Provider



Technical Challenge



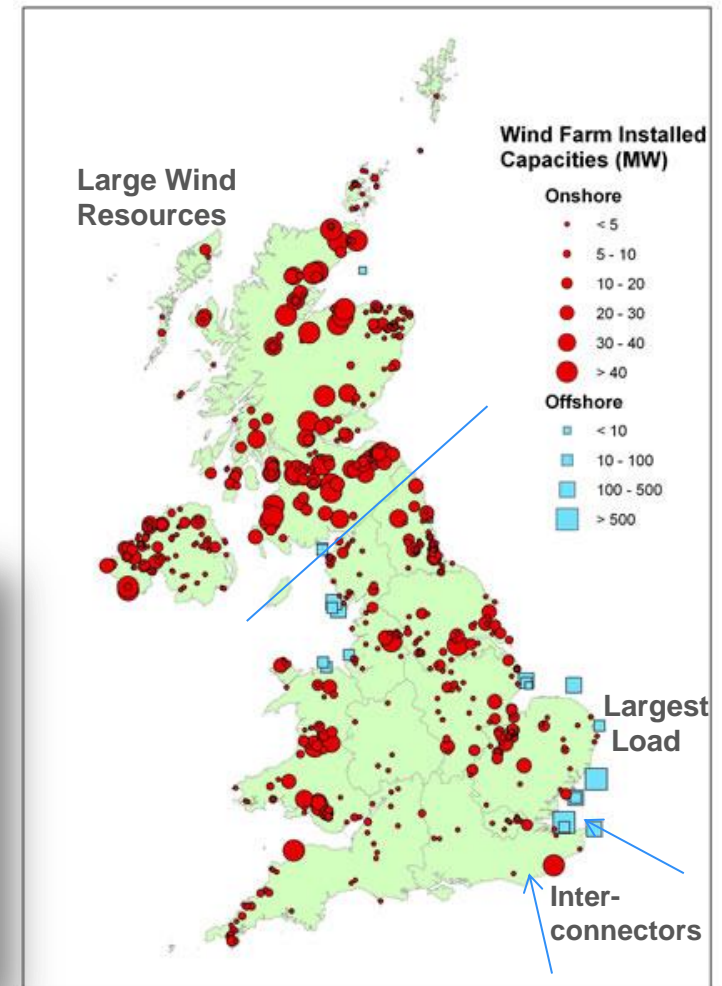
Reducing Inertia with Increasing Share of Wind

Large high wind N→S power flow

Major constraint Scotland-England

Inertia reducing, especially in Scotland

- Wind power - no inertia
- Interconnectors – no inertia
- Synchronous plant closed or constrained off



Longannet power station to close next year

© 23 March 2015 | Scotland business



Cockenzie Power station demolition gets under way



The Fast-Frequency Response Challenge

Rate of Change of Frequency (RoCoF) Is not equal across system

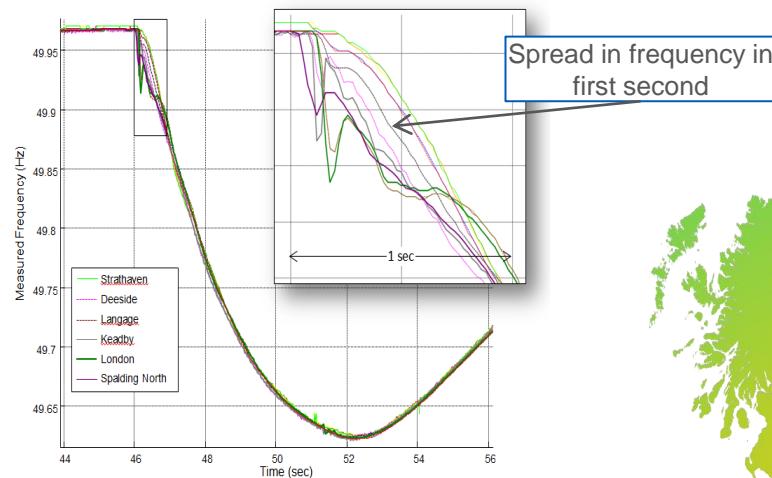
- Dependent upon event proximity & Regional Inertia
- Reflects changes in power flows as the angle behaviour is perturbed

What is the danger of Fast Frequency Response (FFR)?

- Similar time frame to first swing angular stability
- Risk of system splitting

Need to consider the angle behaviour through a coordinated response

- Used to prioritise action closer to event
- Using wide-area measurements



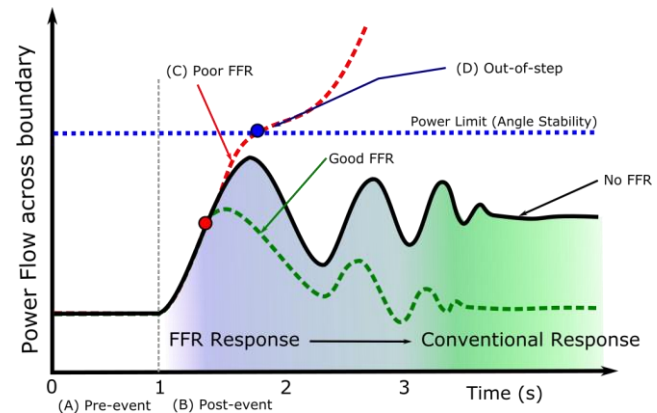
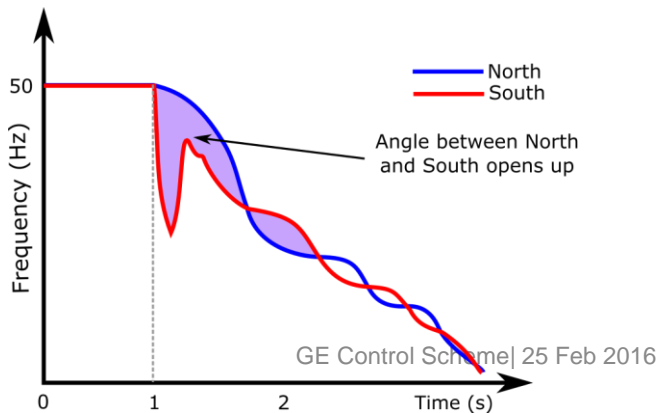
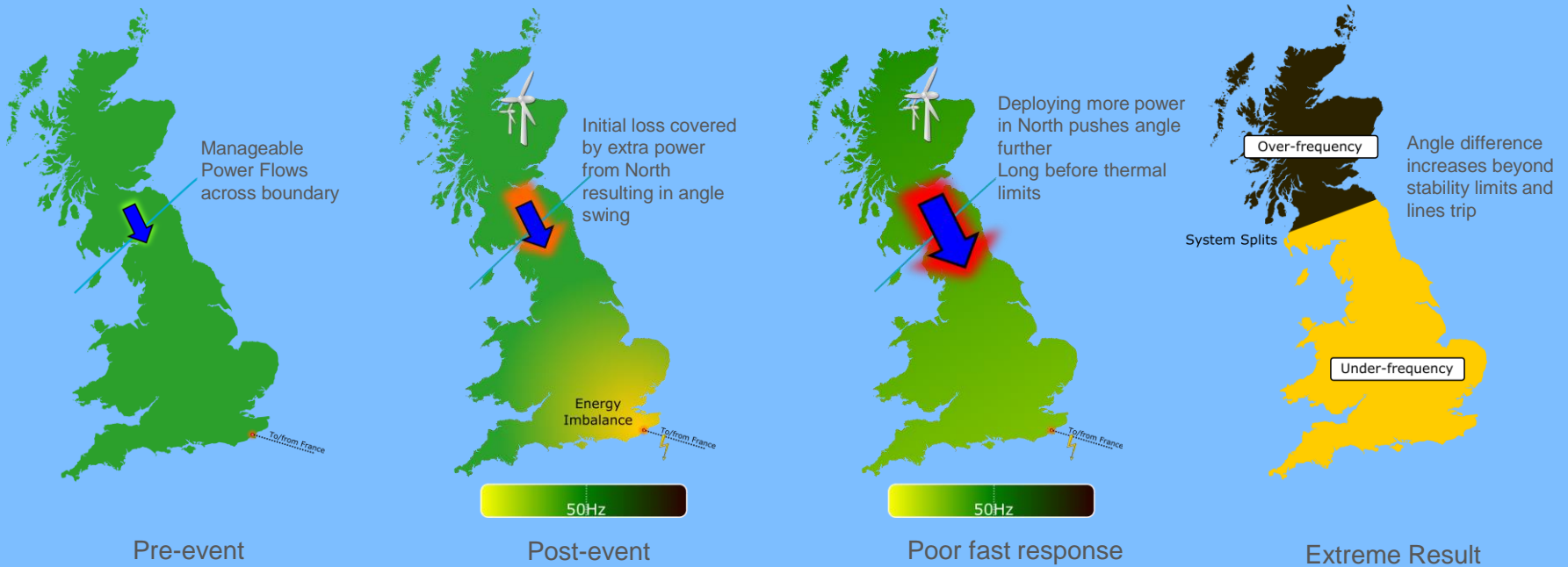
Measured Frequency response to generator loss

Phasor angles change across system



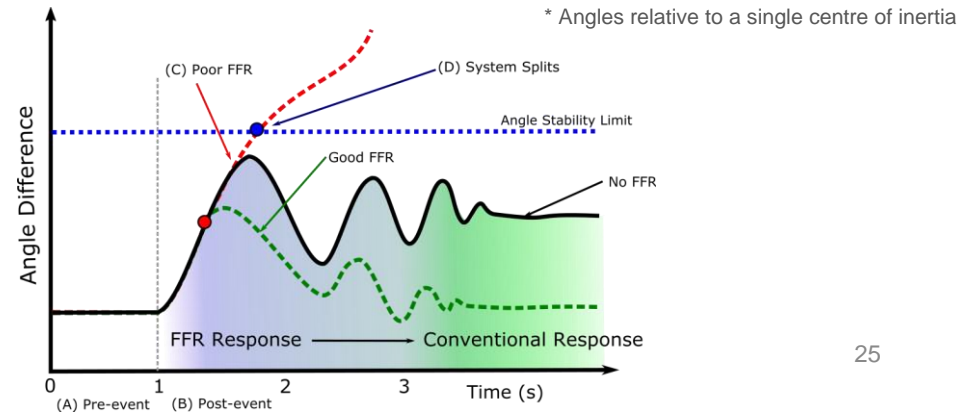
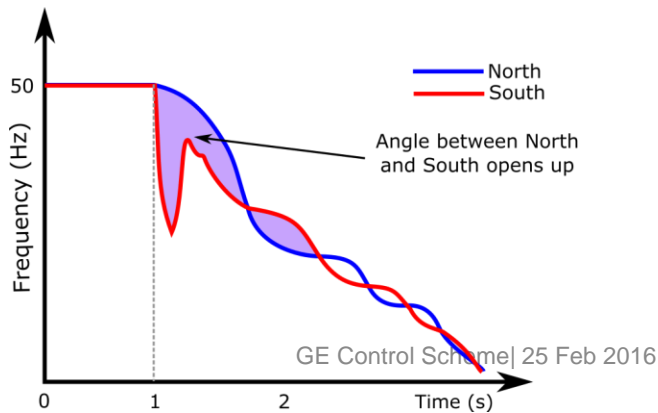
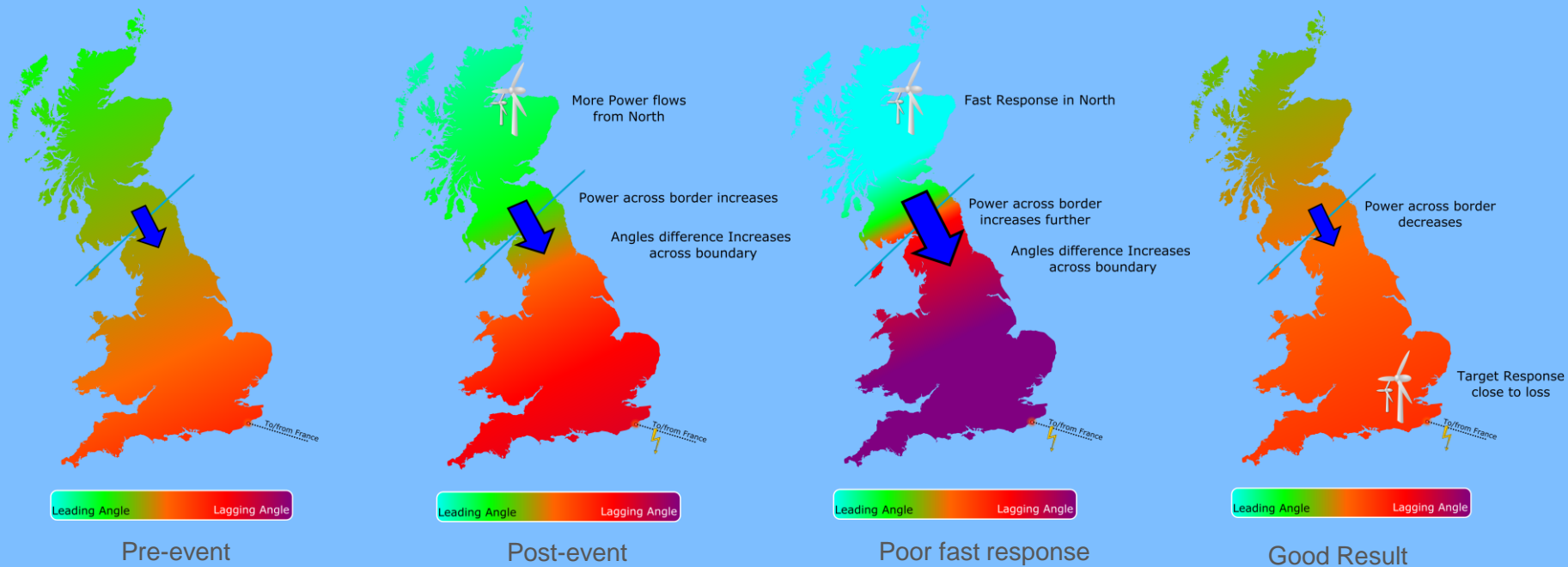
Implications of Poor FFR Location

Example Extreme Behaviour during a frequency event

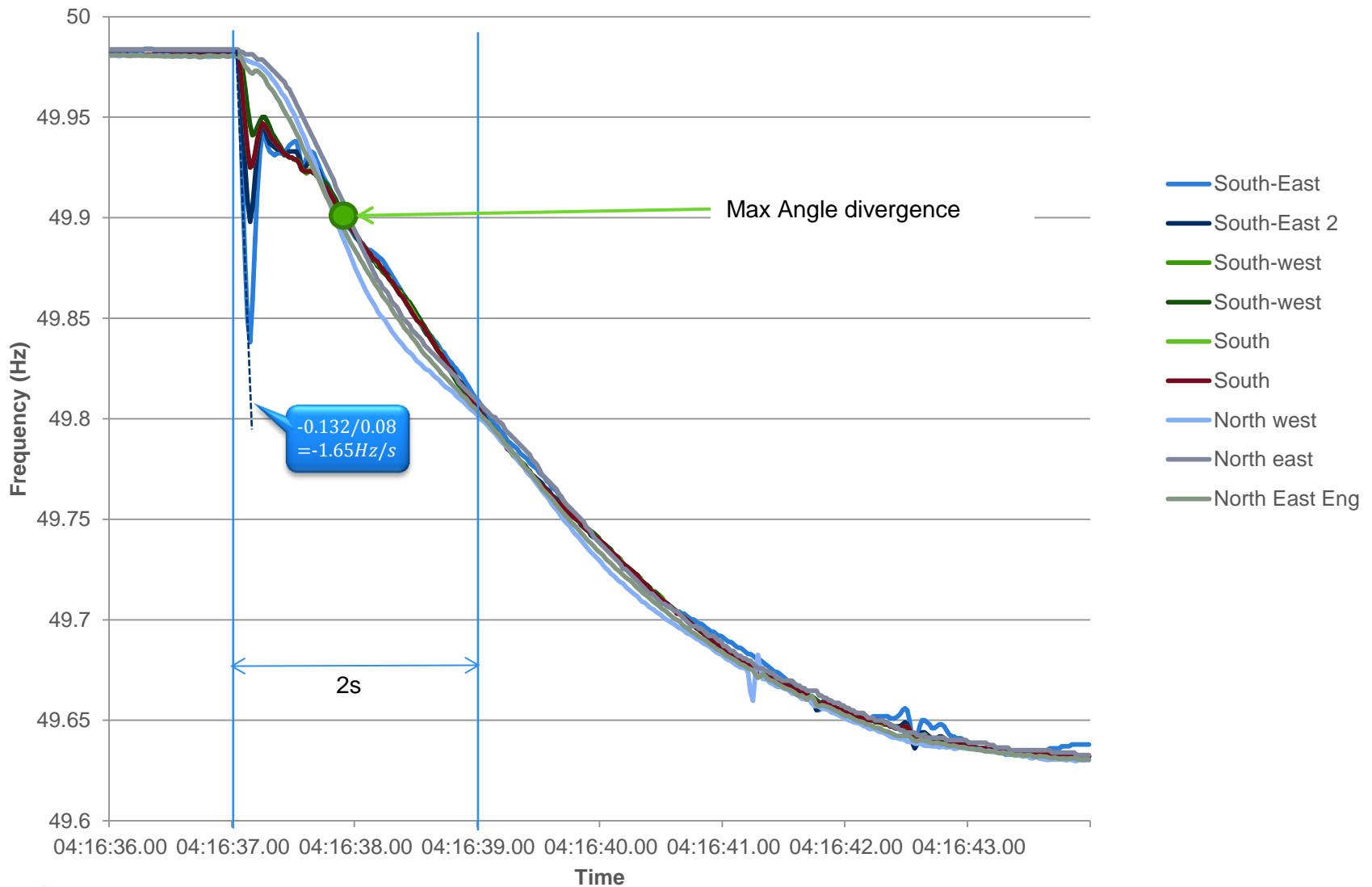


Implications of Poor FFR Location (angles)

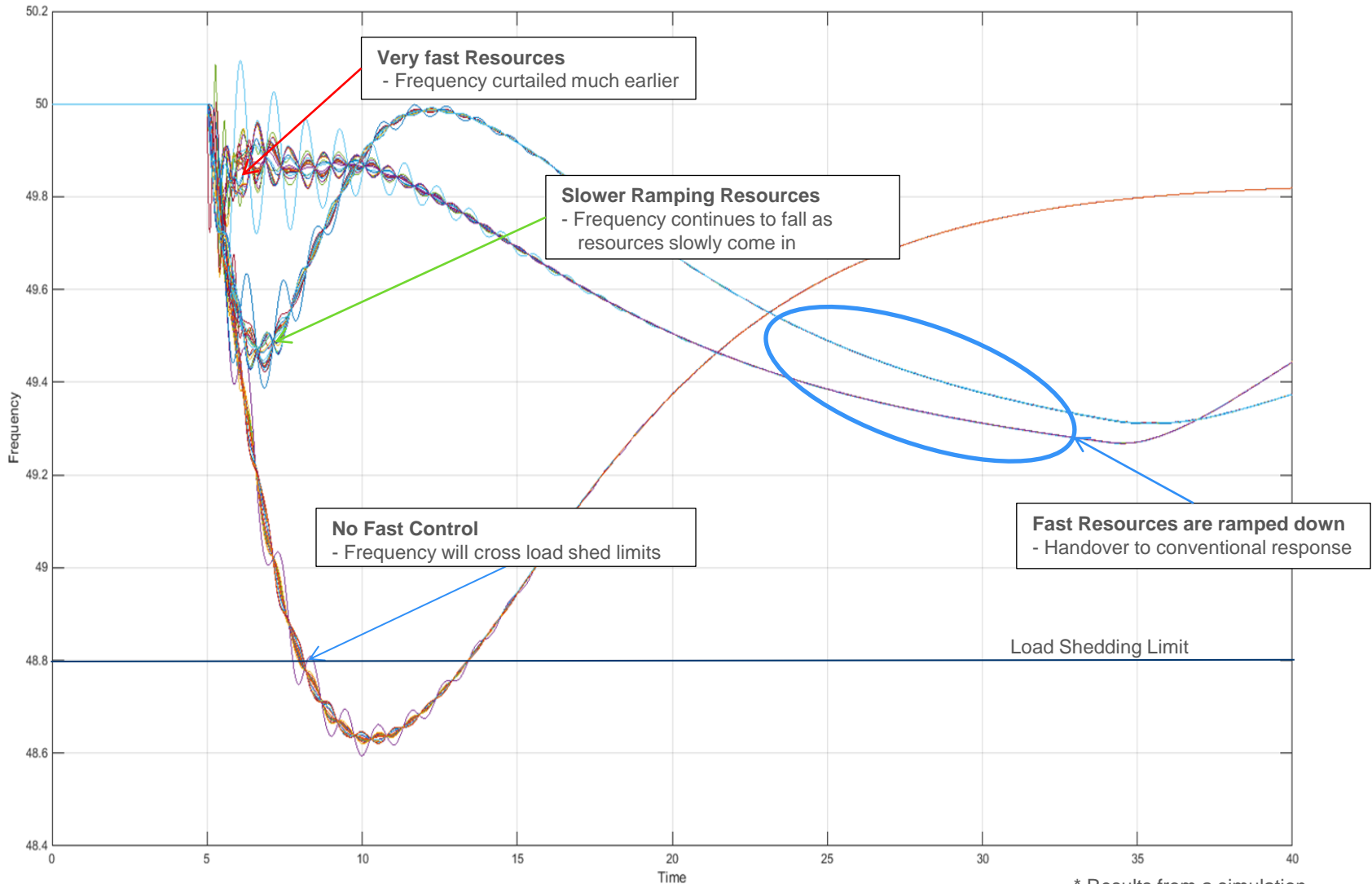
Example Extreme Behaviour during a frequency event



NG Interconnector Event



Effect of Response



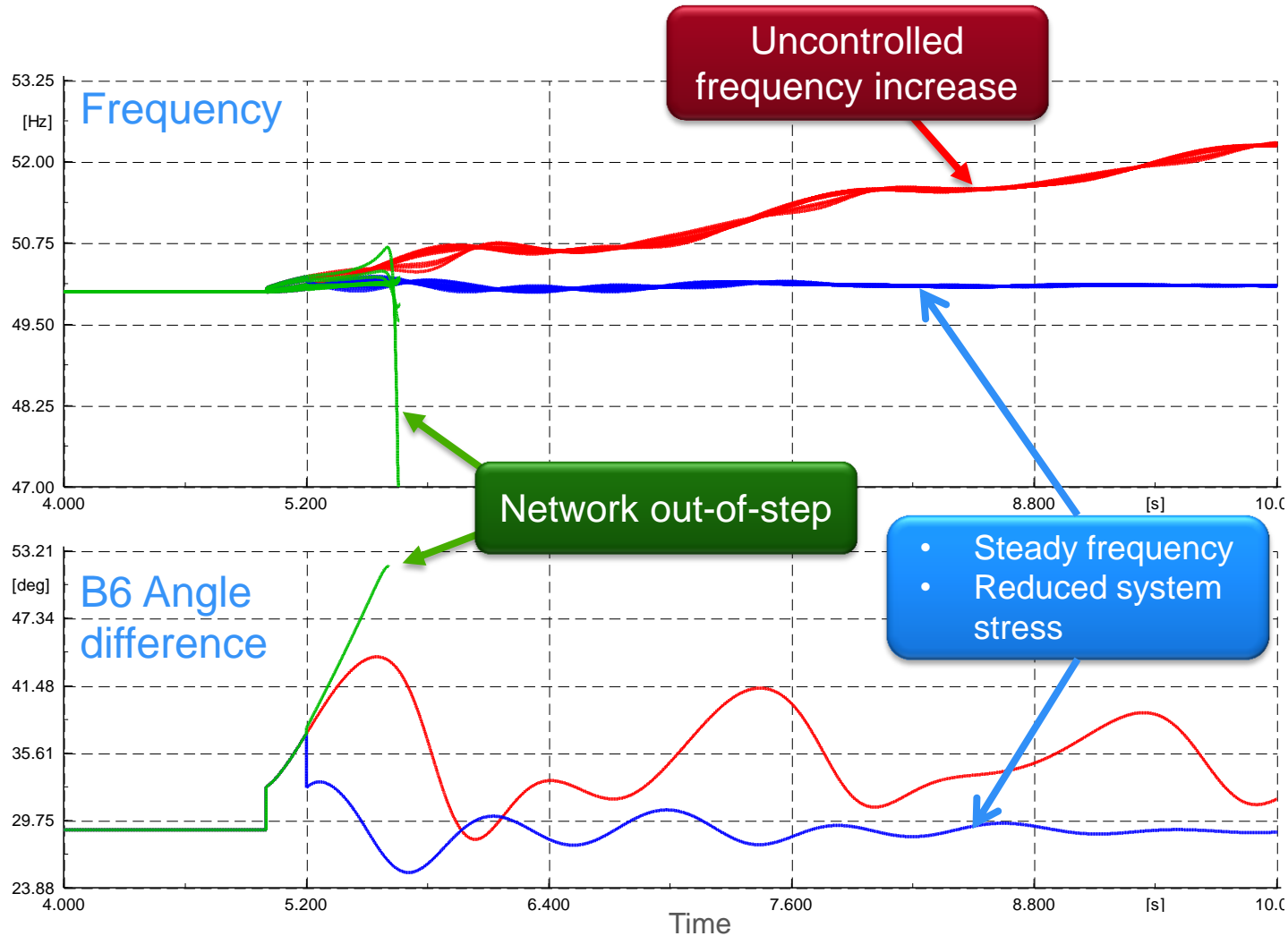
* Results from a simulation






Simplified GB Network Simulations

Assumptions:

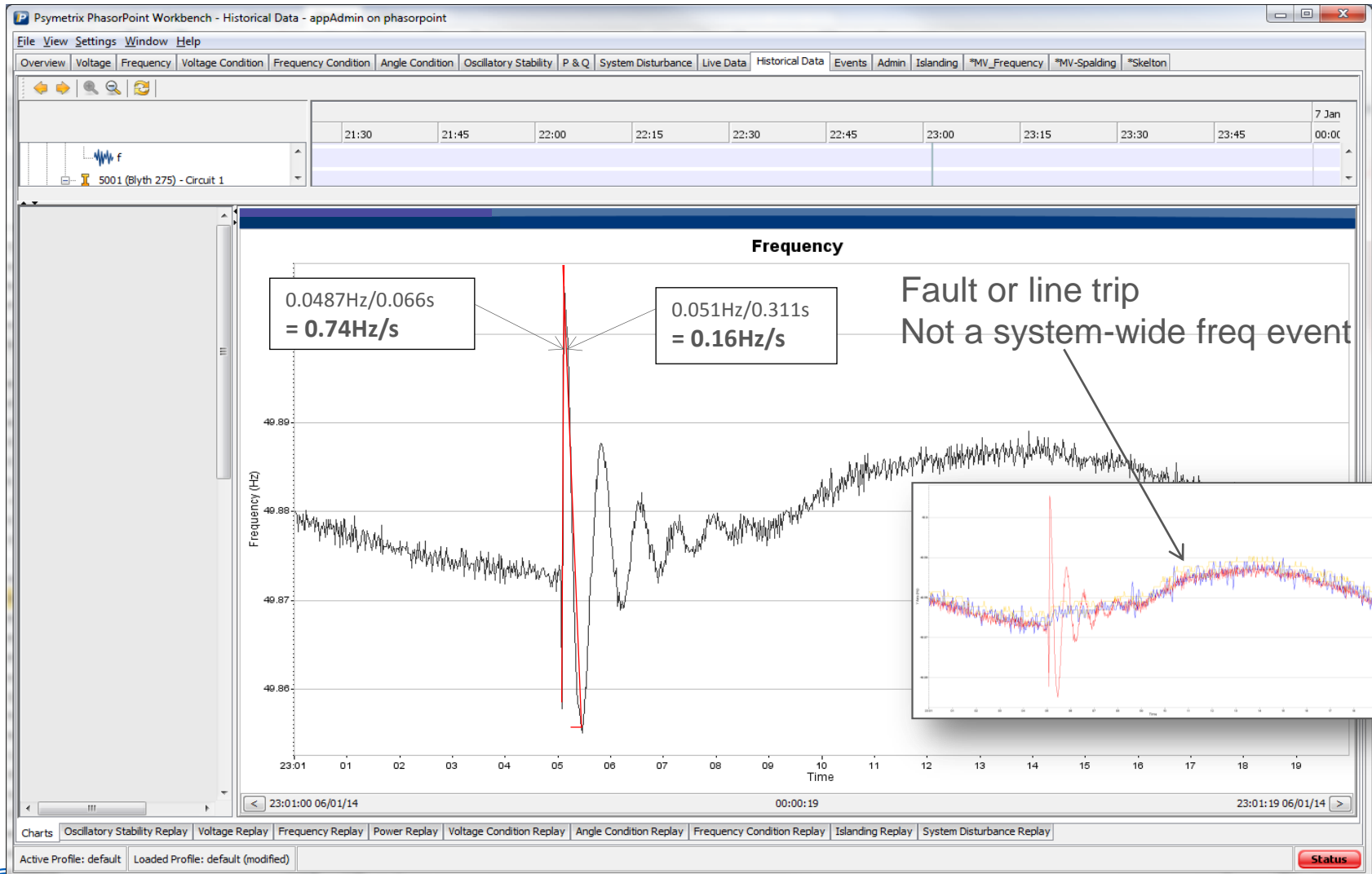
- Simplified model of **Future network with reduced inertia** (0.2 Hz/s)
- **Loss of load in Scotland** (1000 MW)



-  No control action
-  SFC control action
-  Uncoordinated action



Local frequency disturbances



Uncoordinated local Control

Local frequency/RoCoF varies across system – noisy signal

Deploying on Frequency or RoCoF can lead to **spurious triggering**

- Line fault or trip event will perturb local frequency
- Responding to non-frequency event negatively impacts stability

Following frequency or RoCoF can lead to poor **oscillation damping**

- Delays in measurements/response can excite oscillations

Higher occurrence of events on lower voltage networks

- What would the effect be on resources connected at these levels?
- Excessive trips/response, reduced resource lifetime, reduction in confidence
- How would resources be rewarded for responding to non-frequency events?

How to **distinguish frequency events** from other events such as line trips?

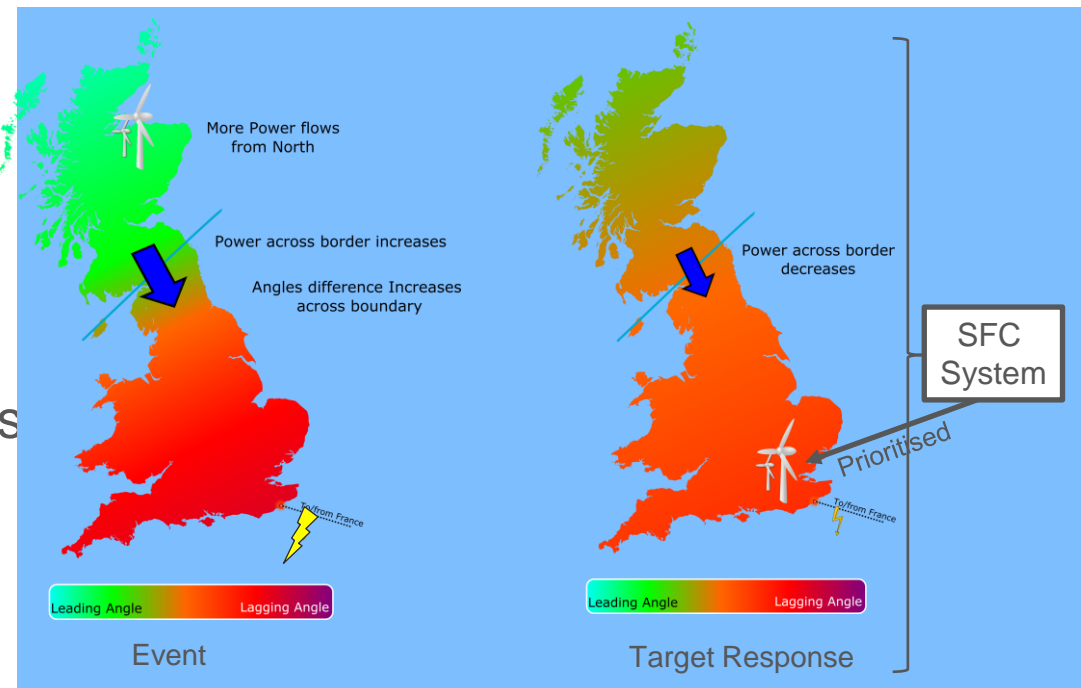
Uncoordinated local control should act slower than wide-area to prevent these negative impacts



Wide Area Frequency Control

Monitoring & control system targets:

- Detecting true system frequency events quickly
- Prioritising response in area, reducing network stress
- Proportionately, predictably deploying fast response



Control Scheme

Design of the Control Scheme



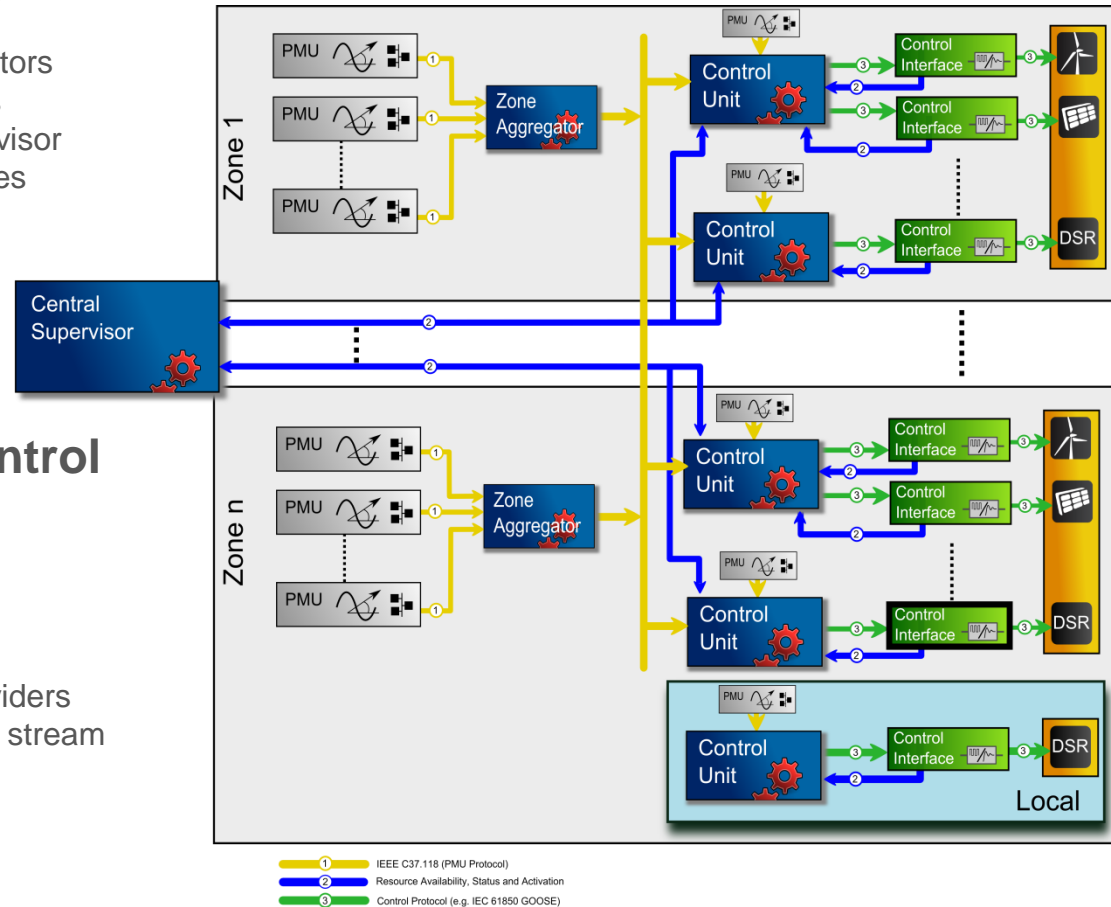
Distributed Control Scheme

System split into a number of regions

- Multiple distributed controllers
- In each region, PMUs send data to Aggregators
- Aggregated signals broadcast to Controllers
- Resource information sent to Central Supervisor
 - CS coordinates scheme and resources
- **Not** model based
 - Would be too slow for fast control action
 - Uses real-time measurements

Distributed Vs. Centralised Control

- Better Self Regulation (autonomous decisions)
- Communication:
 - Efficient use of bandwidth
 - Well defined latency
- Plug & play Infrastructure
 - No scheme reconfiguration for new providers
 - New service just receives common data stream
- Robust - No single point of failure
- Graceful Degradation
 - Signal loss
 - Communications loss



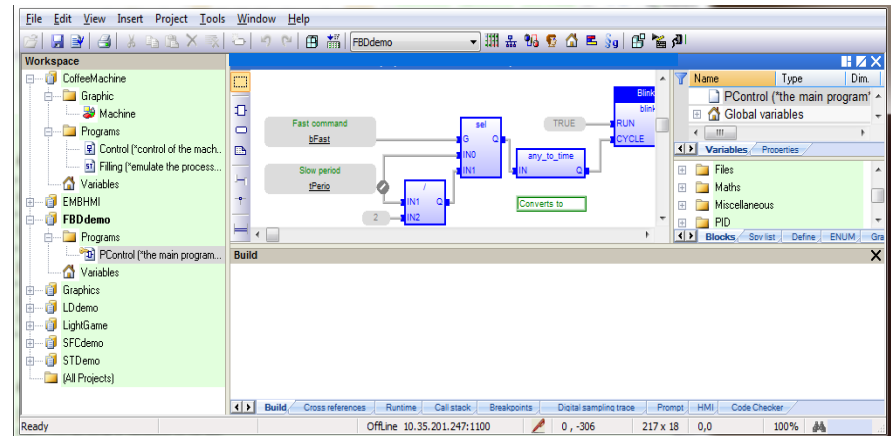
Flexible Control Platform

Flexible control platform at centre of scheme

- Library Elements and Custom Elements
 - Greater flexibility for scheme design and algorithms
 - Developed by Power Systems Engineers in a familiar environment
 - Implemented in a PLC environment
- Variety of implementation protocols
 - IEC 60870-5-104
 - IEC 61850
 - IEEE C37.118
 - Modbus
 - Digital I/O's
 - Other protocols possible



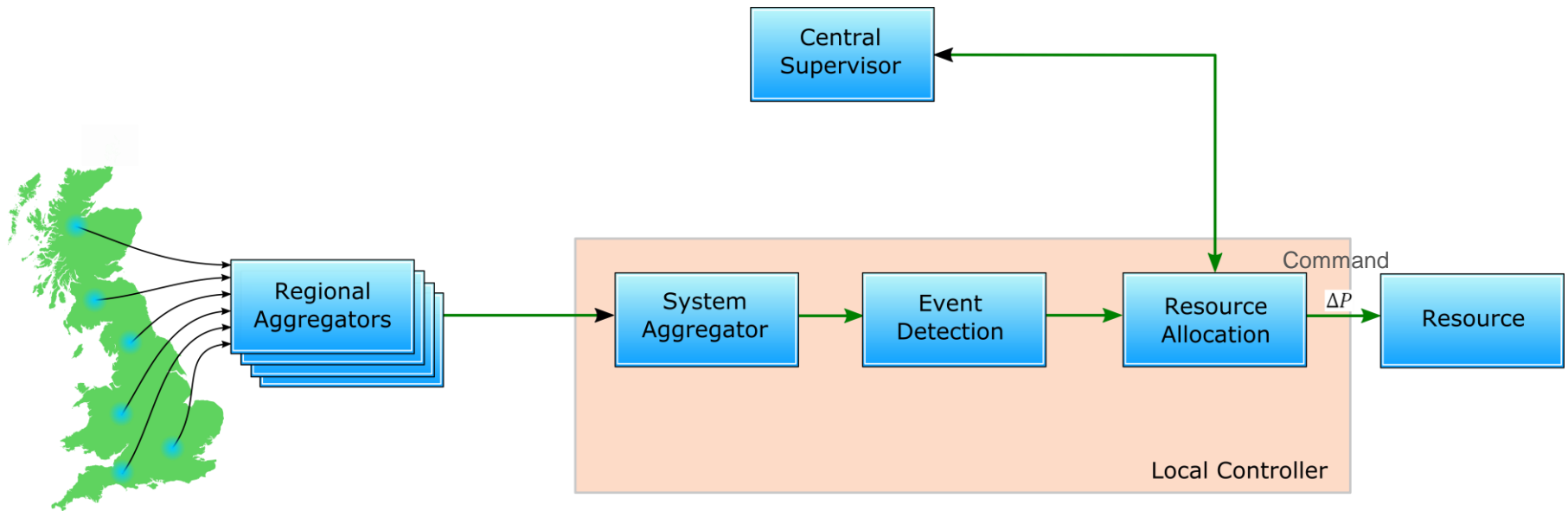
e-terra phasor controller



Applications

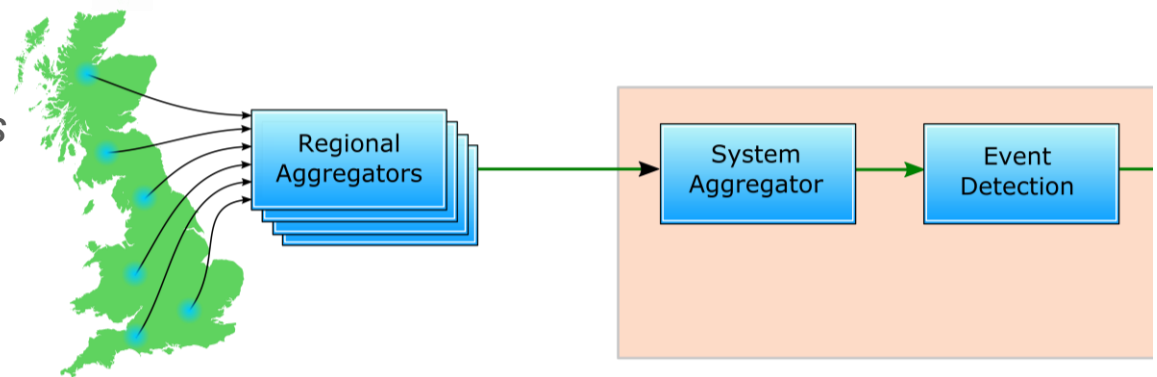


SFC Application Overview



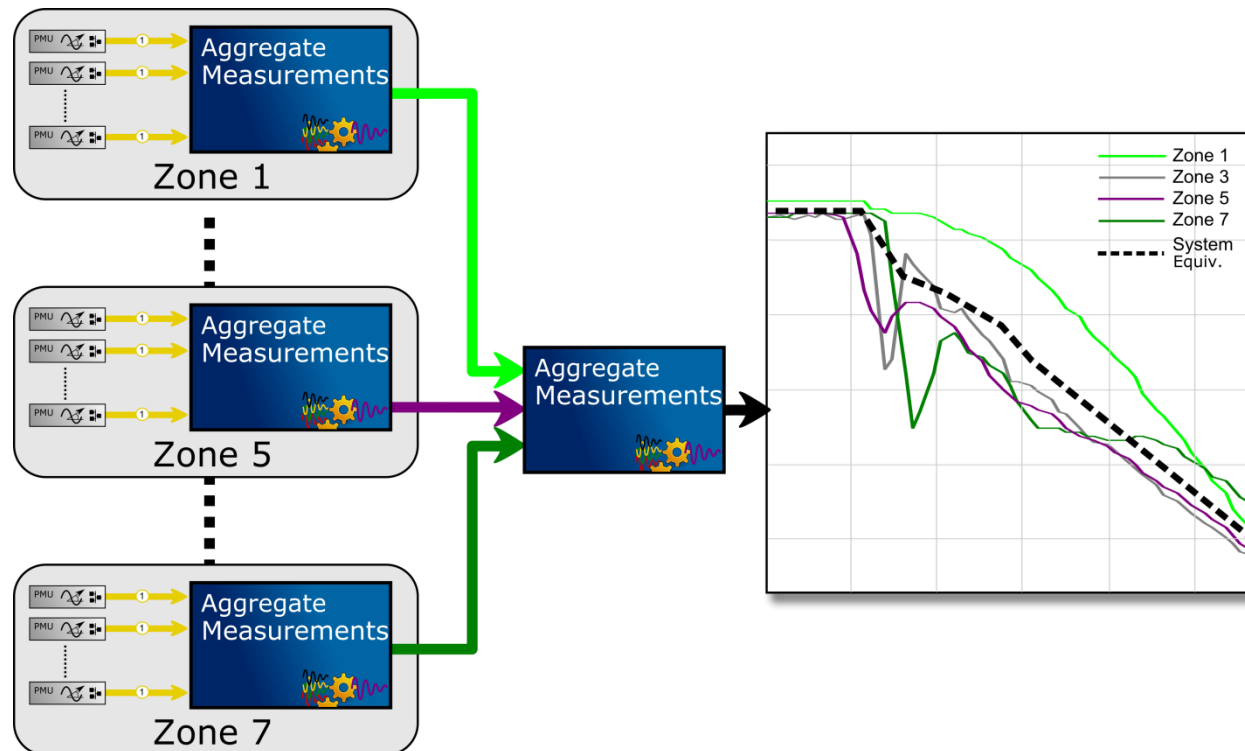
Event Detection Requirements for SFC

- *To detect, as quickly as possible, events which warrant system response*
 - *Target of 500ms from event to trigger for large events*
 - *Significant Generator/load loss (including after faults, trips etc.)*
 - *Interconnector loss*
- *Not trigger on non-frequency events such as*
 - *Faults*
 - *Line trips*
 - *Oscillations*
 - *Small Generator/load loss*



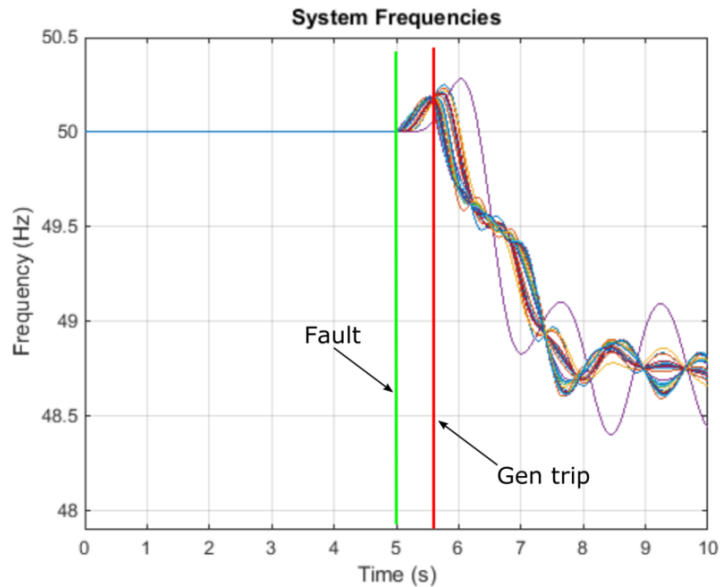
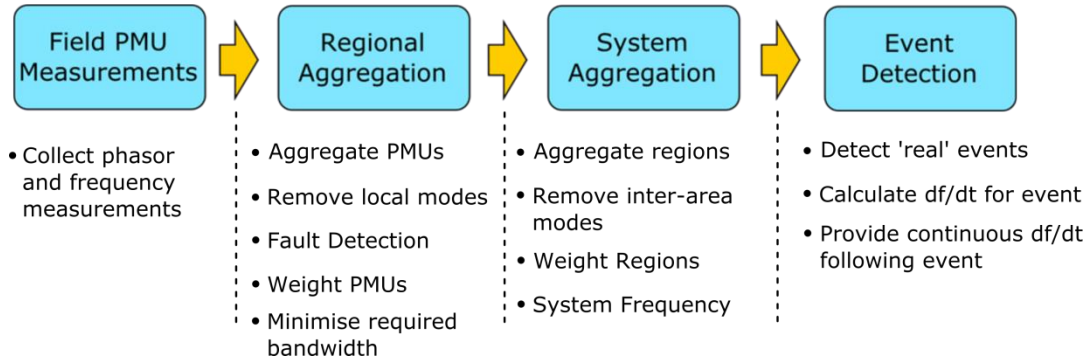
Event Detection Concept

- Each PMU signal assigned to a region
- Aggregate signals represent the region
- Aggregate regions into System equivalent
- Detect 'System Events'

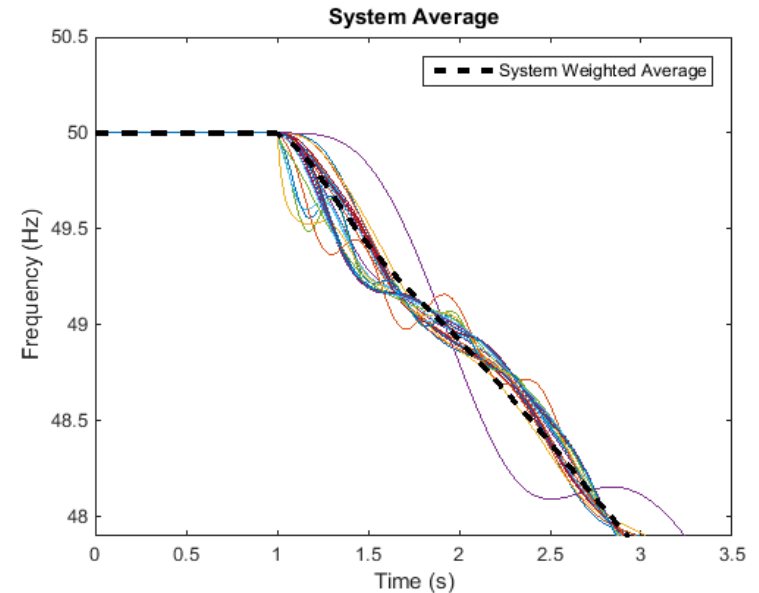


Event Detection Concept

Roles



Fault Case



System Frequency



Resource Allocation - Supervision

Variety of resources in system

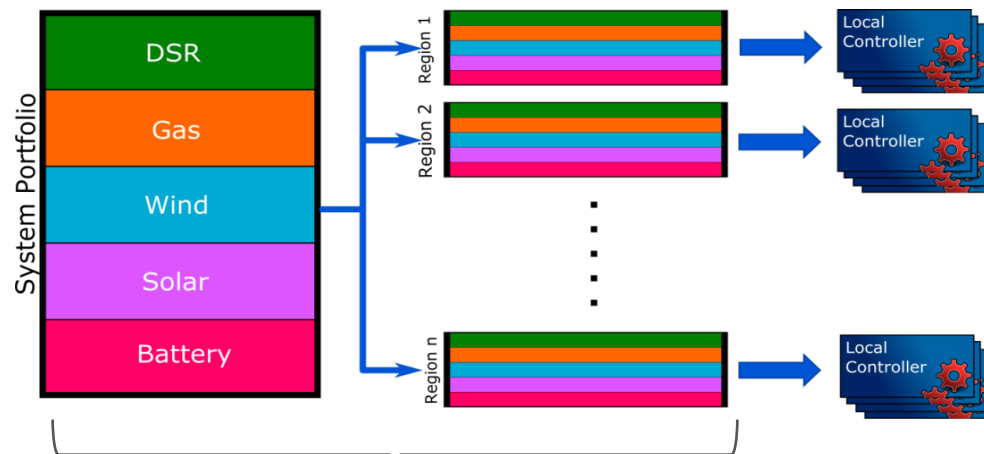
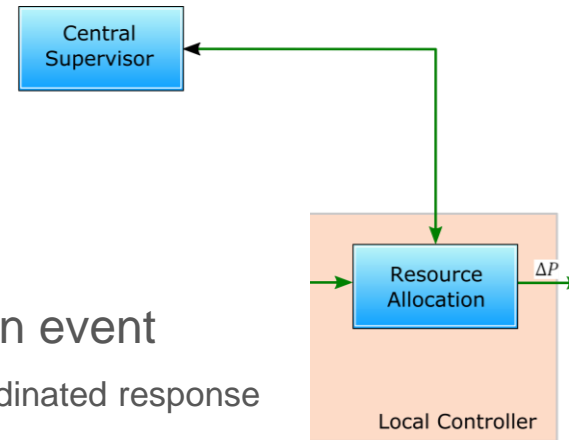
- Different resource characteristics – ramp rates, duration etc.
- Need to manage active portfolio of available resources
- Ranked according to Optimization algorithm
 - Aim to deploy fastest response first

CS communicates active portfolio information prior to an event

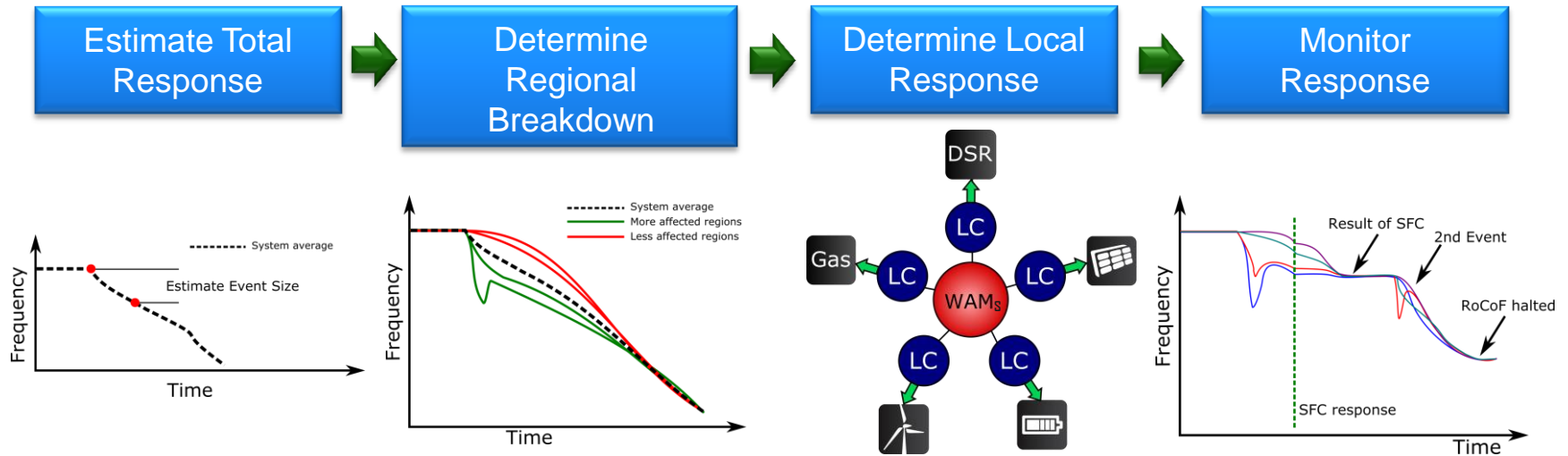
- Local controllers need information on the active portfolio to deploy a coordinated response

Resources are deployed according to an optimisation algorithm

- Selects which resources to deploy and how much to request from them



Resource Allocation - Deployment



Local Controllers determine:

- Appropriate size of response
- Locations at which to target response
- Which resources should be utilised in delivering response
- If any subsequent response is required, due to insufficient response, or subsequent events

Information about resource portfolio is received from Central Supervisor prior to an event



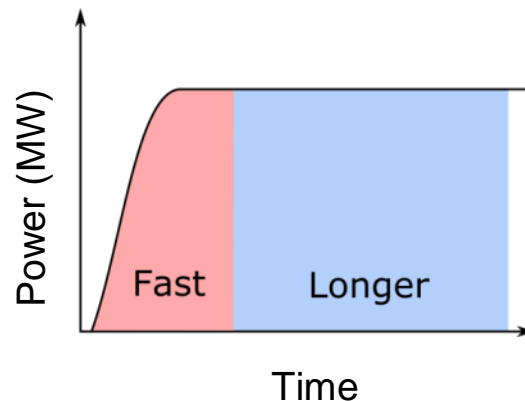
Optimisation - Ideal response

The ideal response is one that reduces the event's effect before the system degrades

For example:

- Region A loses 500 MW of generation at time 0s
- If 500 MW of load is tripped in Region A at time 0s, the event becomes negligible

Whilst this is obviously not possible, it provides a target with which to rank responses:

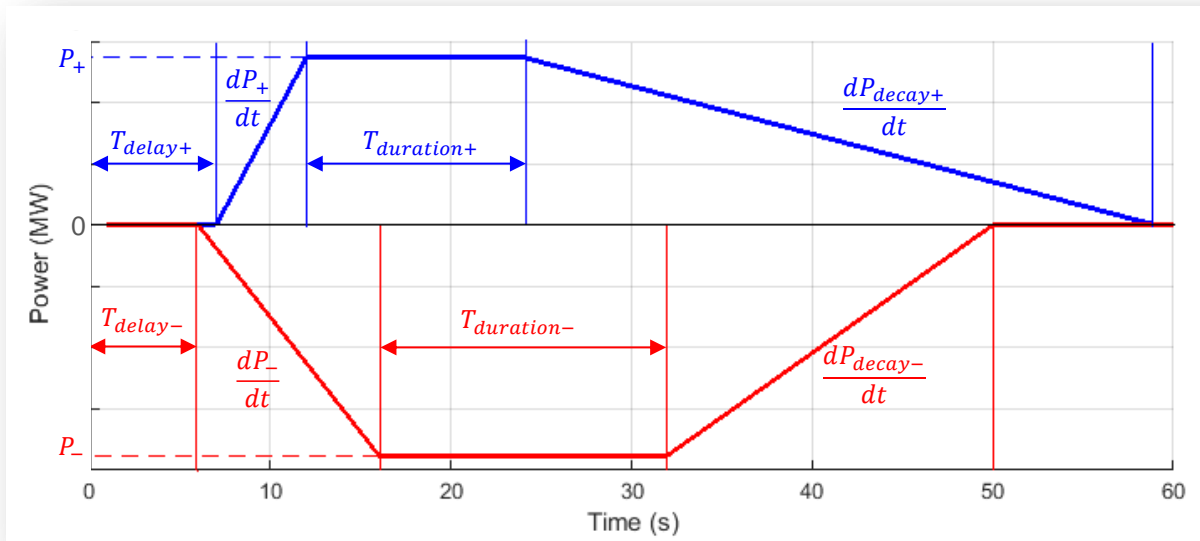


Square wave is best

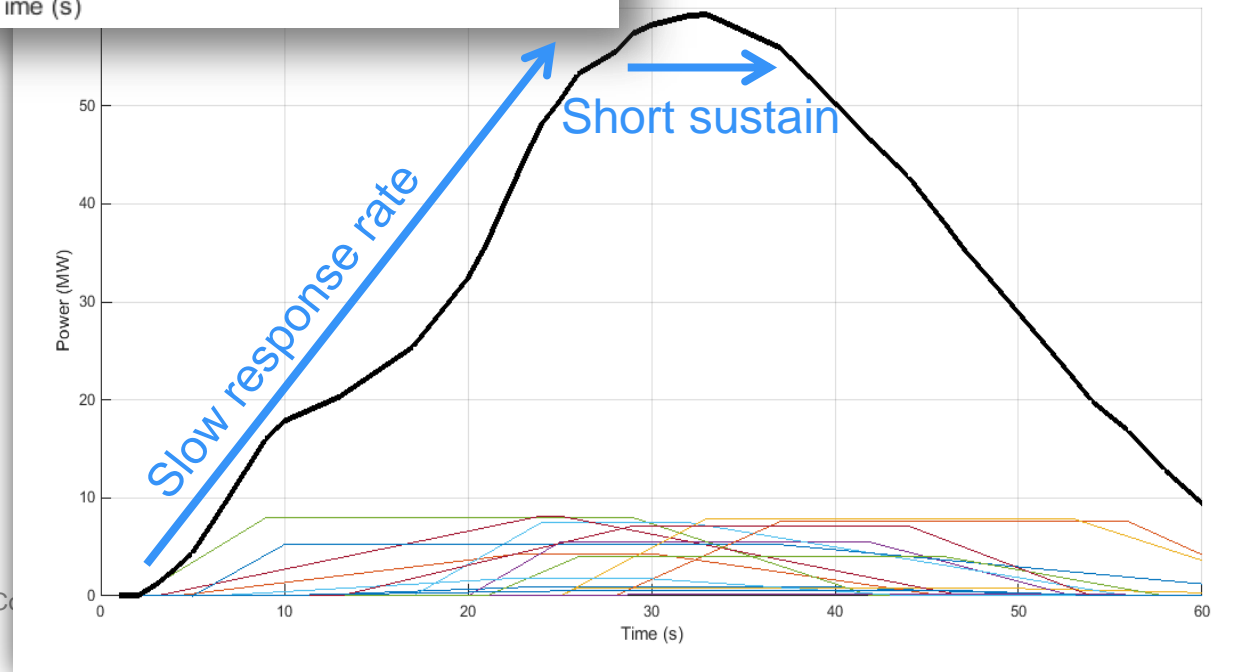
- 0 s time delay
- Infinite ramp rate
- Sustained response



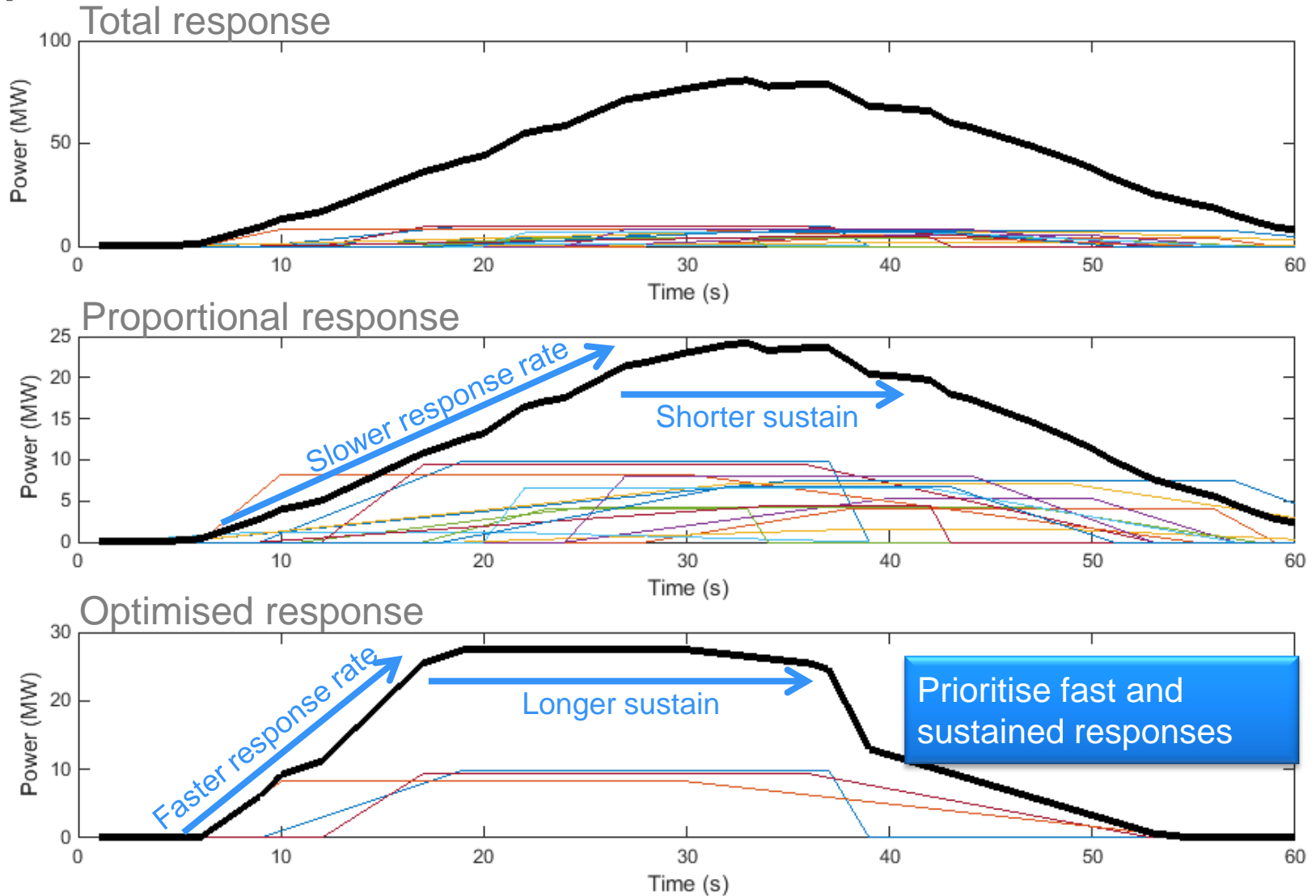
Optimisation – Total regional response



Total response tends away from 'ideal' response



Optimisation outcome



Perspective of a Service Provider



Perspective of a Service Provider

- What is expected of a **Service Provider** and **Service Operator**?

National Grid as Service Operator	Service Providers
Need to know the response profile	Provide NG with response profile
Need to maintain active portfolio	Update NG on status of resource
Needs to alert service provider if they are live or not	Will be aware if they are live in scheme
Determine how service providers will be rewarded: <ul style="list-style-type: none"> • Speed of response • Duration of sustained fast response • Availability etc. 	<ul style="list-style-type: none"> • Greatest value will lie in speed of response (in coordinated way) – connection to WAMS • Local control is possible but care must be taken not to reduce system stability – reducing value • Cost – benefit analysis of installing comms
Facilitate the integration of new service providers to the scheme	May not be called upon for all frequency events – locational element
Prioritisation of resources by ‘willingness to be deployed’	An option to bid according to a ‘willingness to be deployed’, e.g. so many times per month/year etc.
Determine suitable data resolution for response payment – particularly with greatest value on	Capture the deployed response for reward – higher resolution data capture





Wide-Area Frequency
Control Scheme
25th february 2016

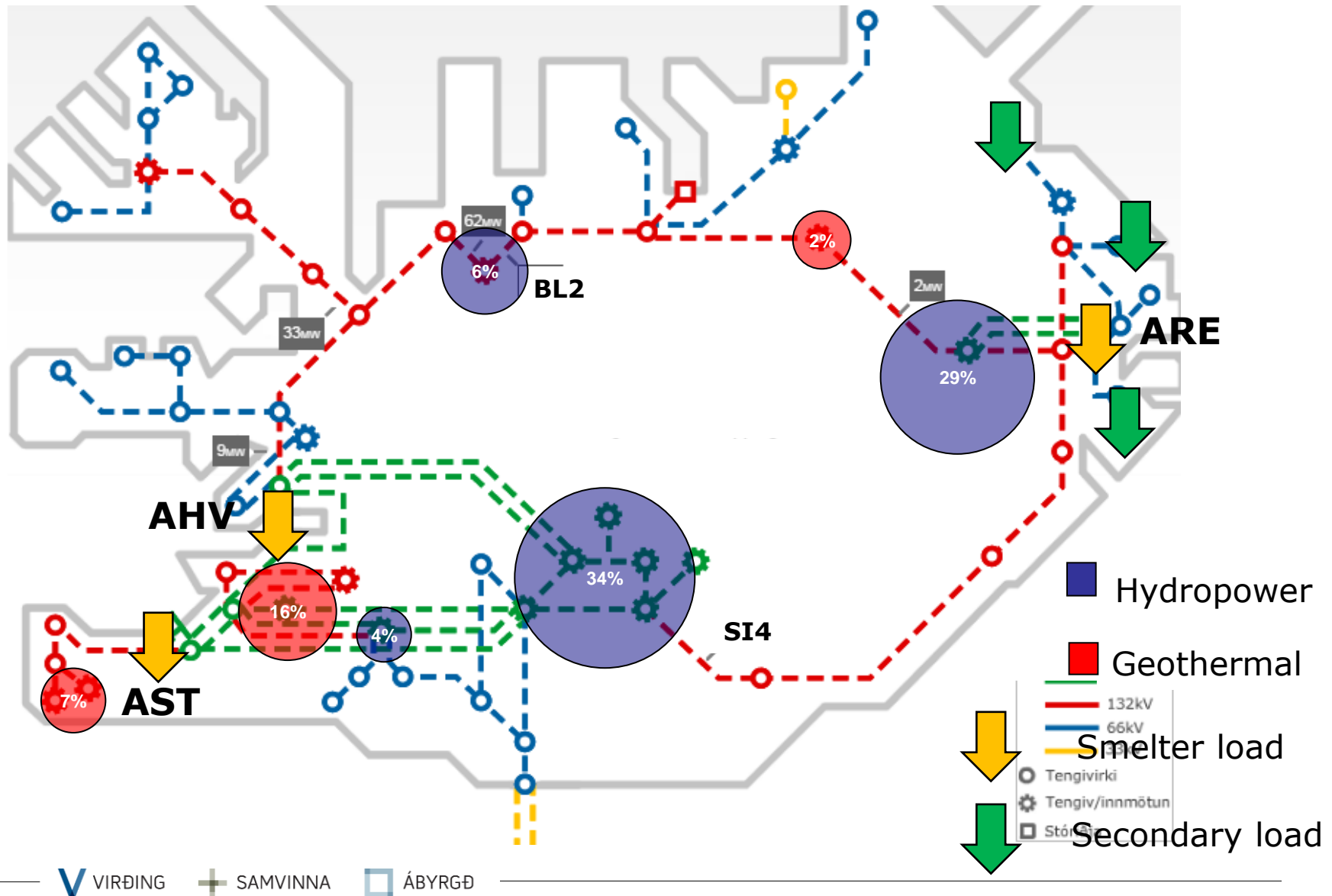
Ragnar Guðmannsson

Overview

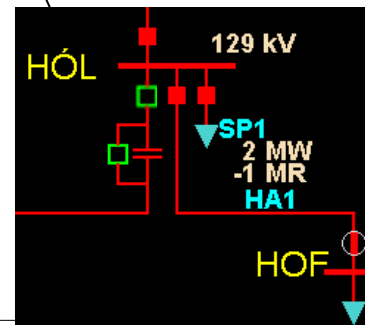
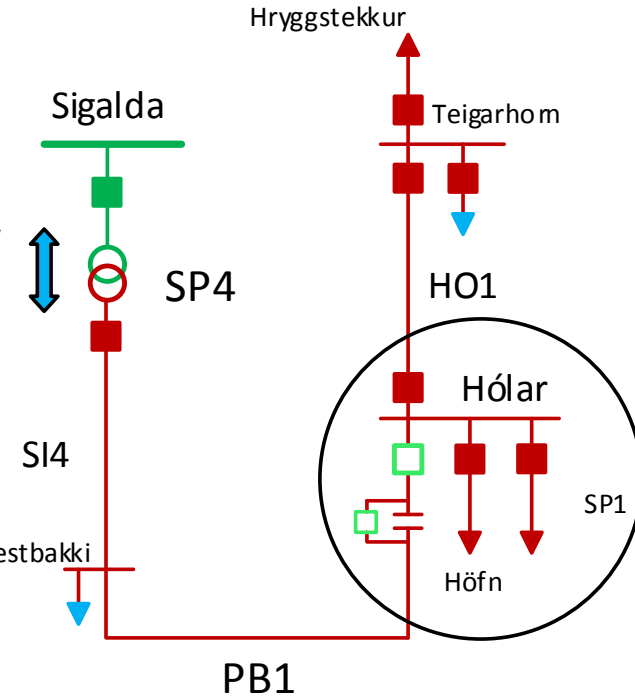
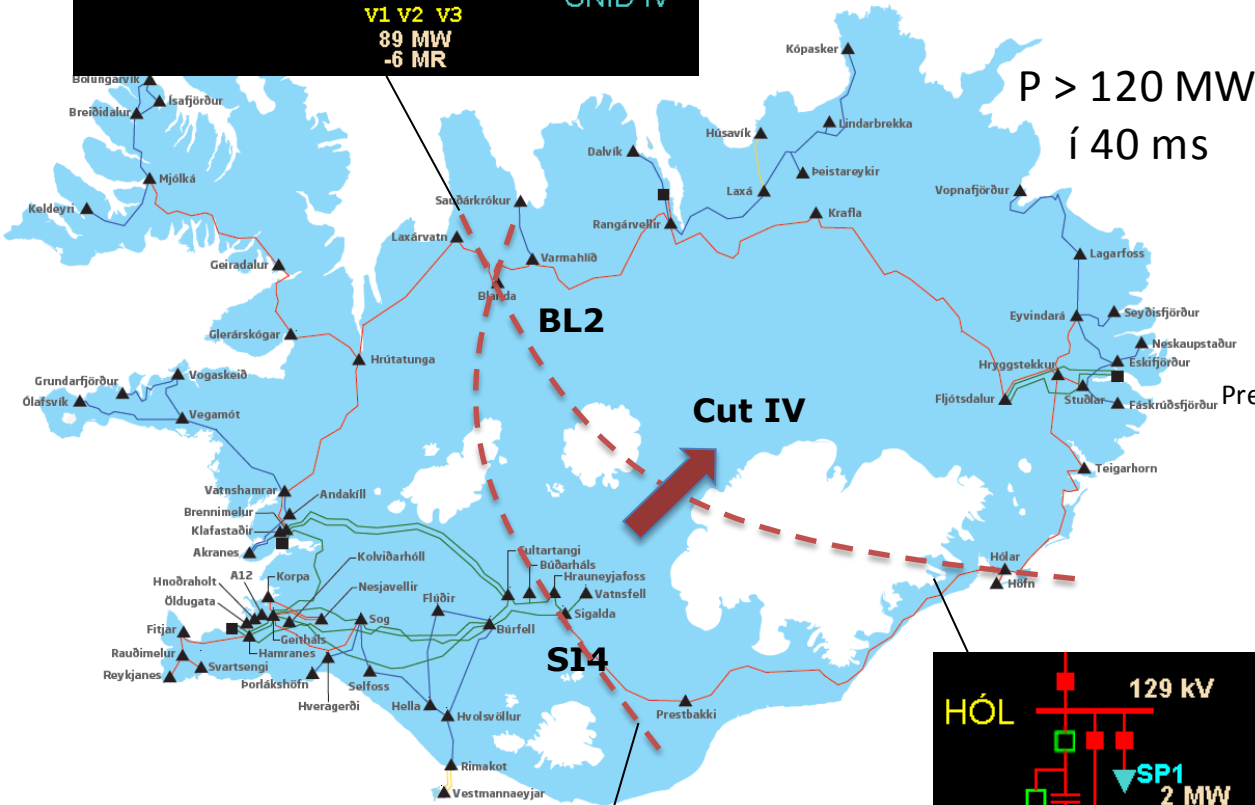
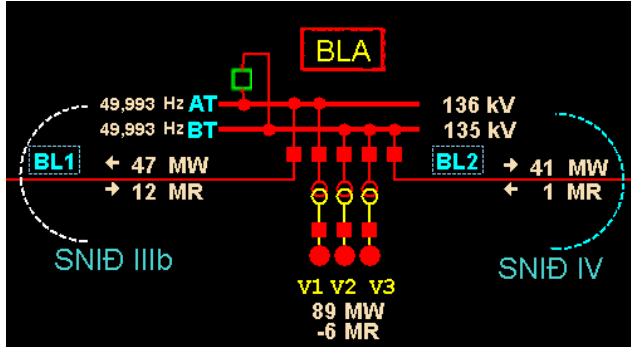
1. The Icelandic Transmission System
2. WAMS in Landsnet's control room
3. Operational challenges in cut IV
4. WACS in operation
5. Summary and future plans



1. The Icelandic Transmission System

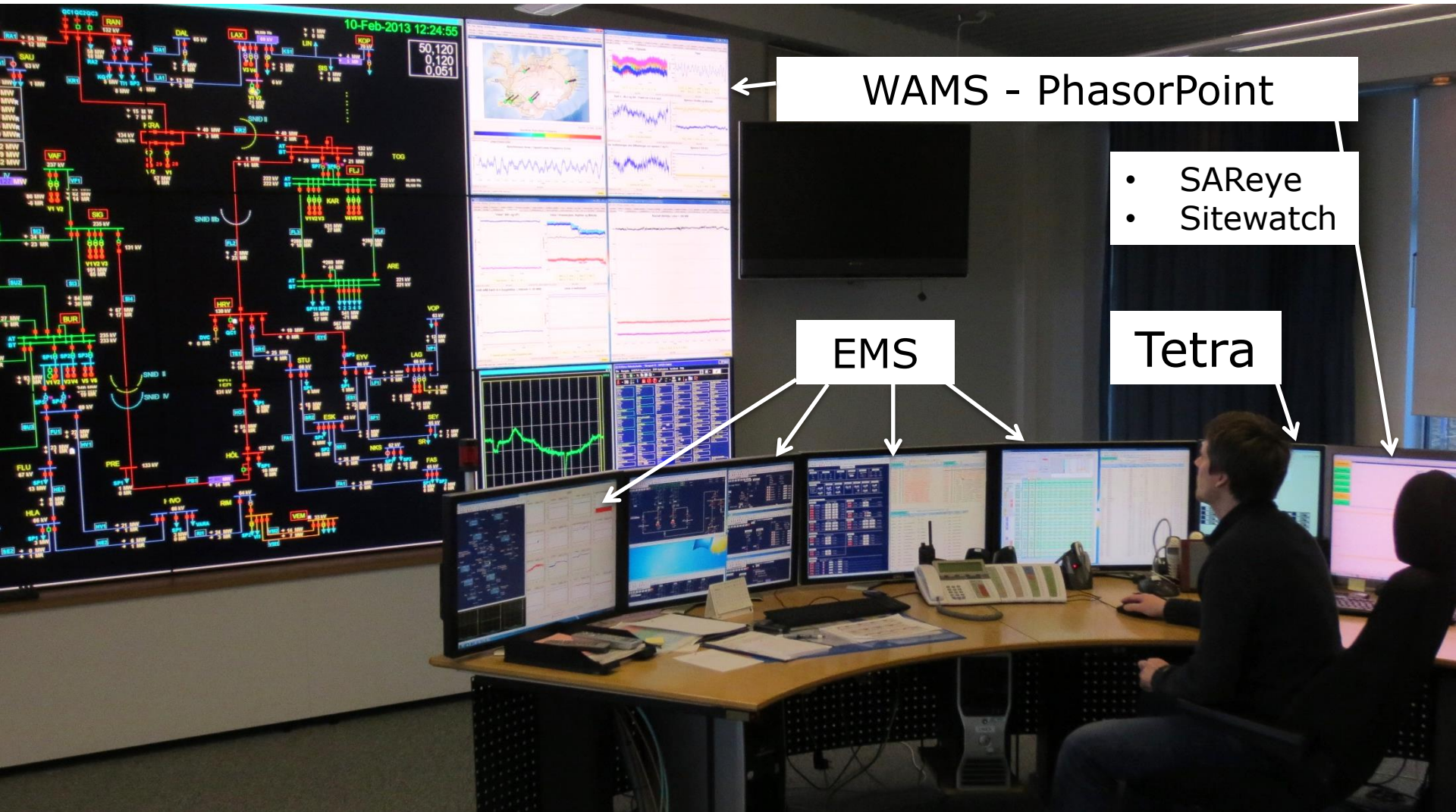


1. The Icelandic Transmission System

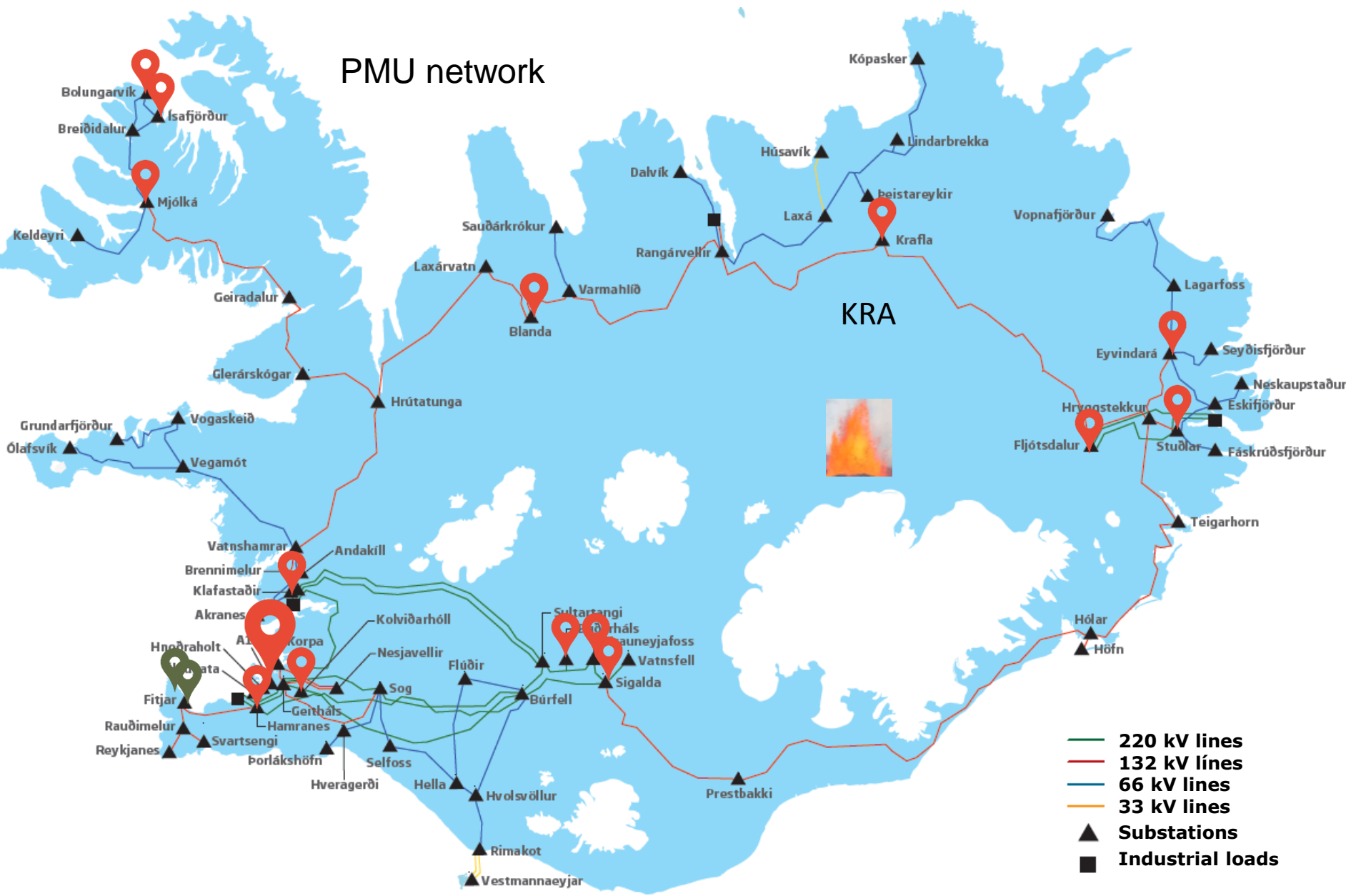


New spilt BLA-SIG

2. WAMS in Landsnet's control room

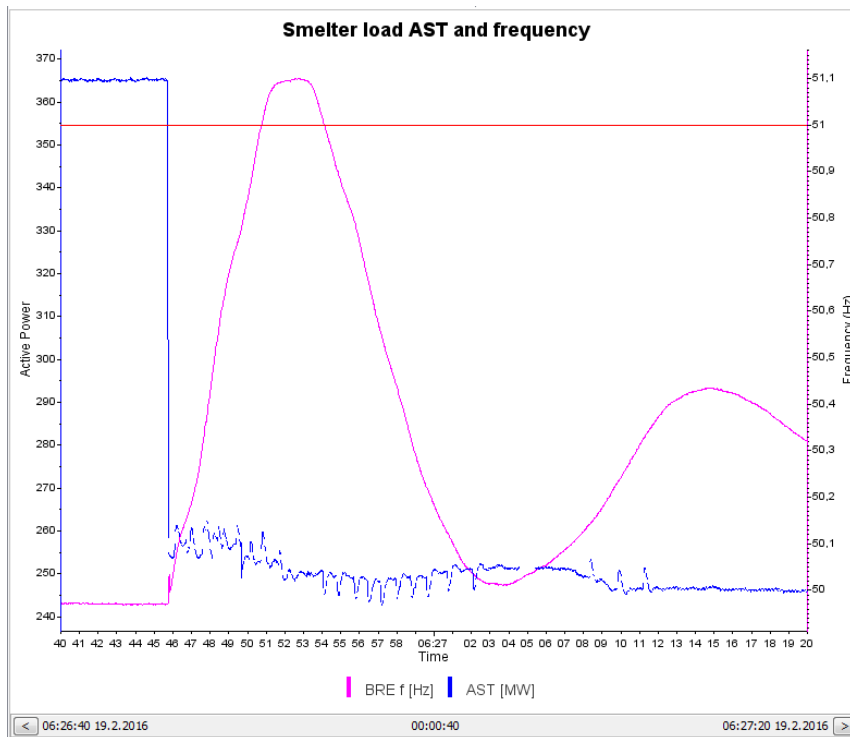


PMU network

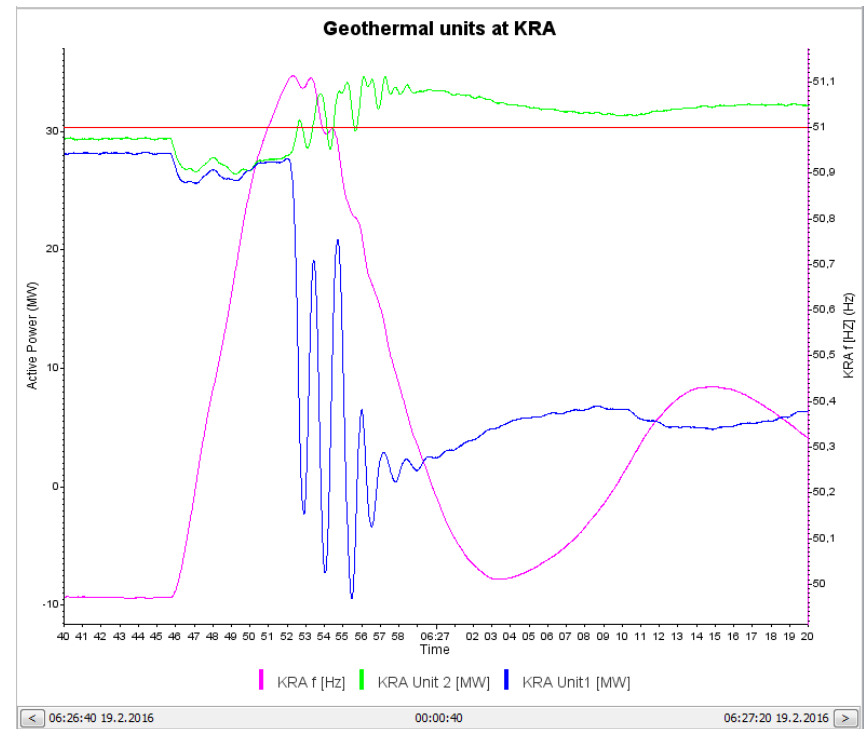


- 220 kV lines
- 132 kV lines
- 66 kV lines
- 33 kV lines
- ▲ Substations
- Industrial loads

- Trip of Smelter load

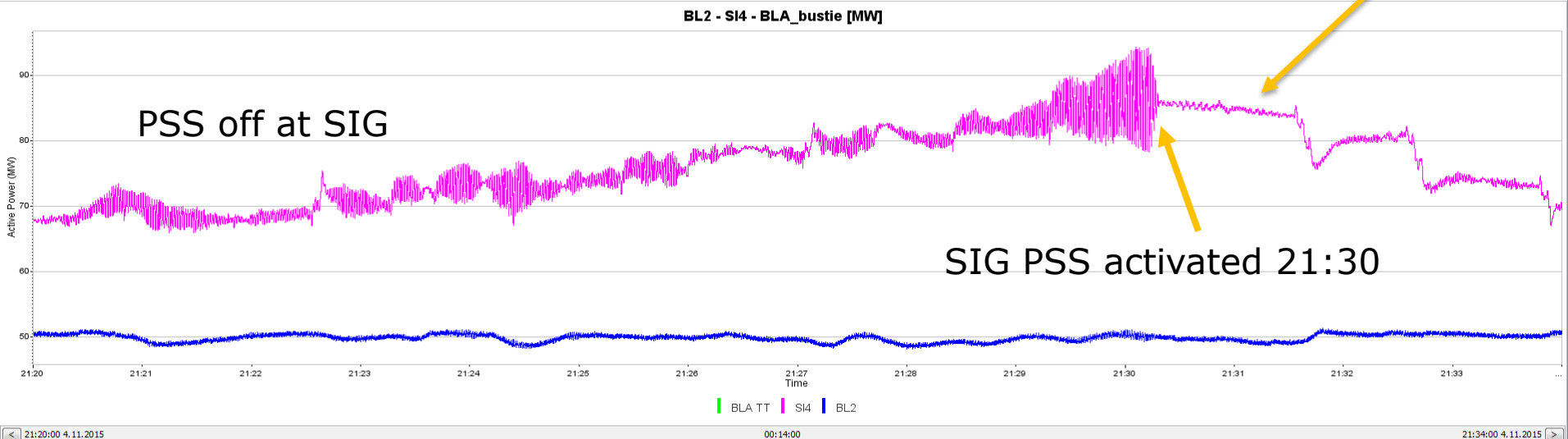


- Geothermal unit response +/- 51 Hz - 1 s → speed control

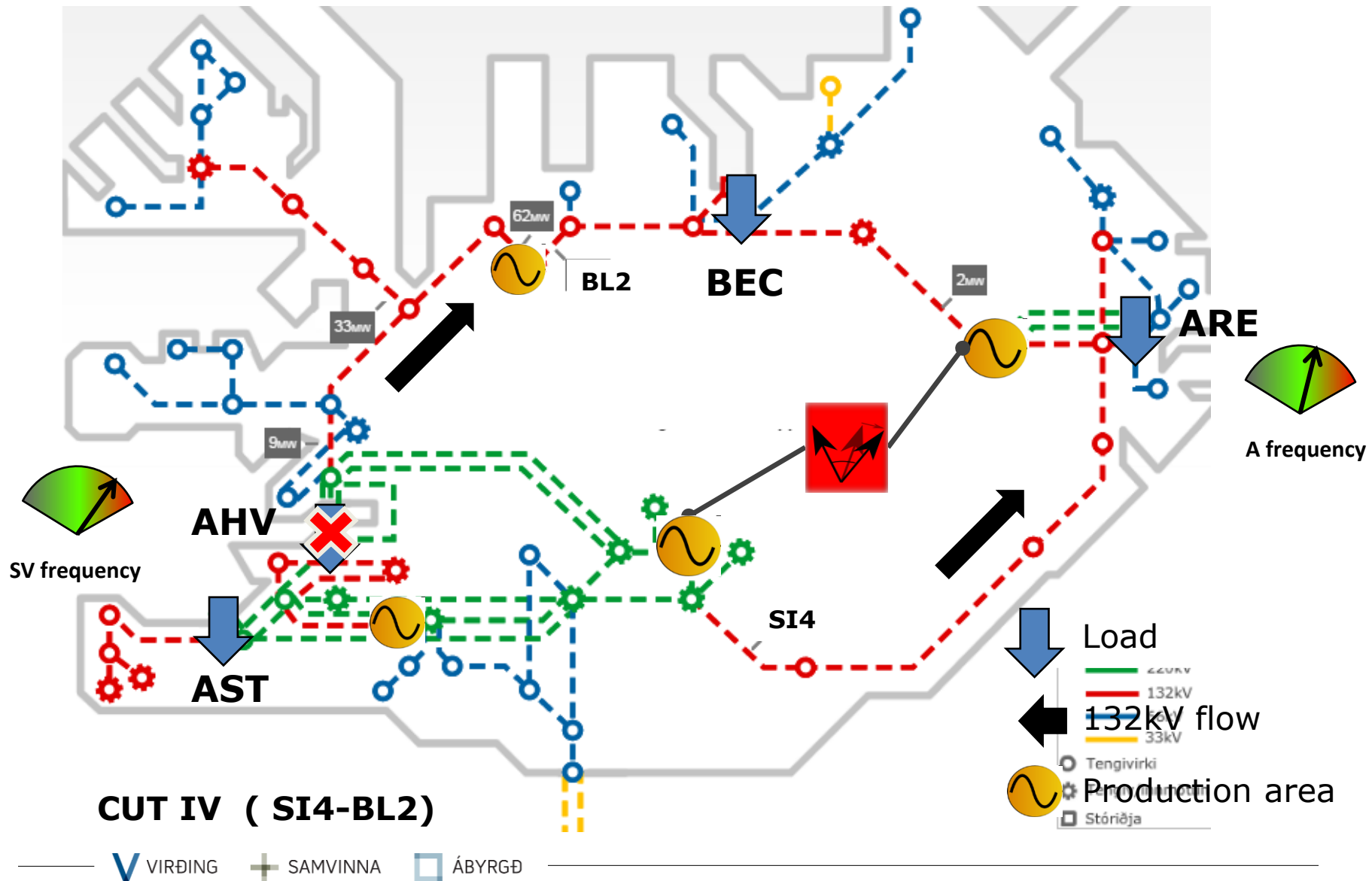


WAMS in control room – 4.11.2015

- PSS testing at Sigalda
- New CB installed to enable a better balanced split and to increase transfer in cut IV

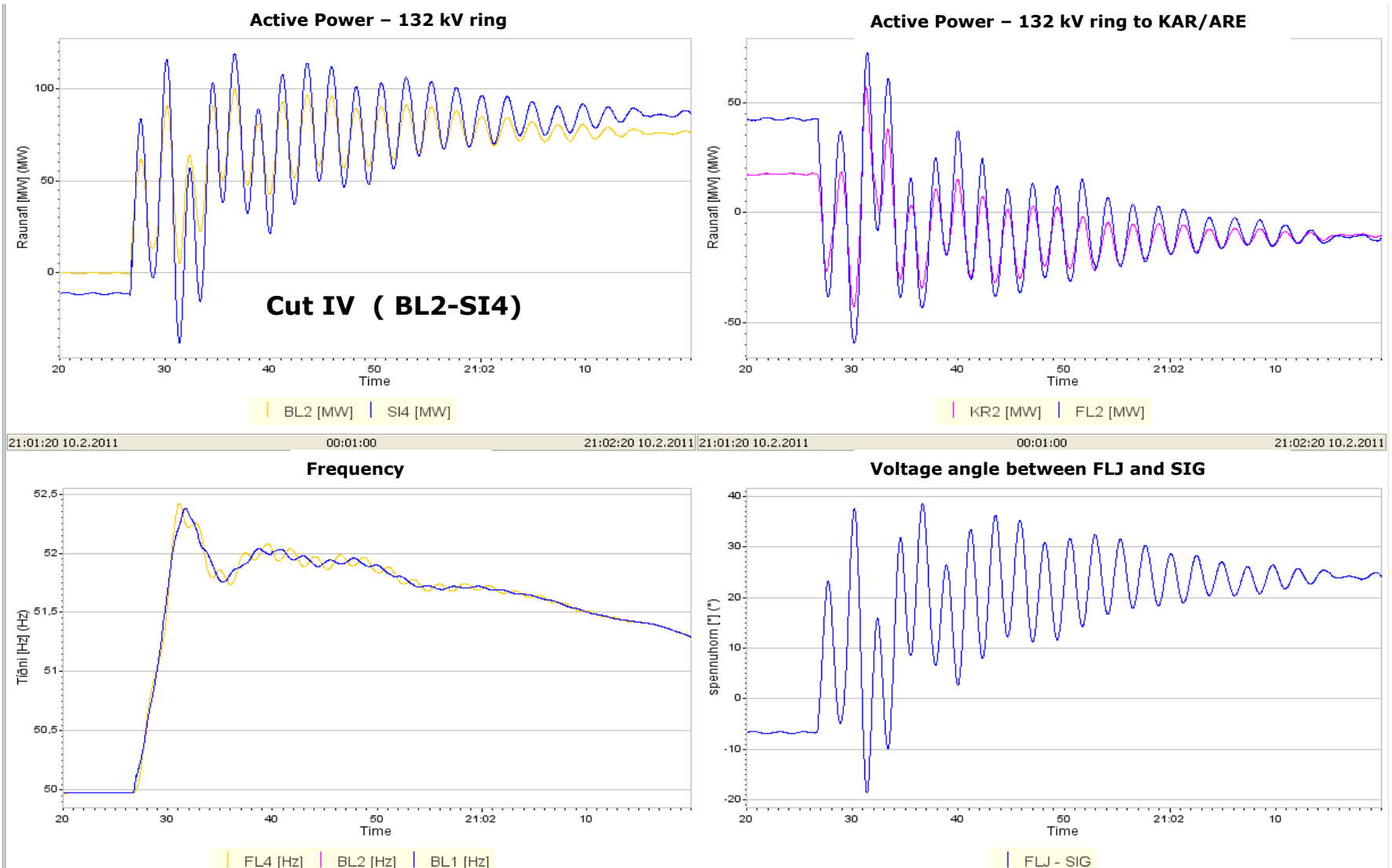


3. Operational challenges in cut IV trip off smelter load in SouthWest



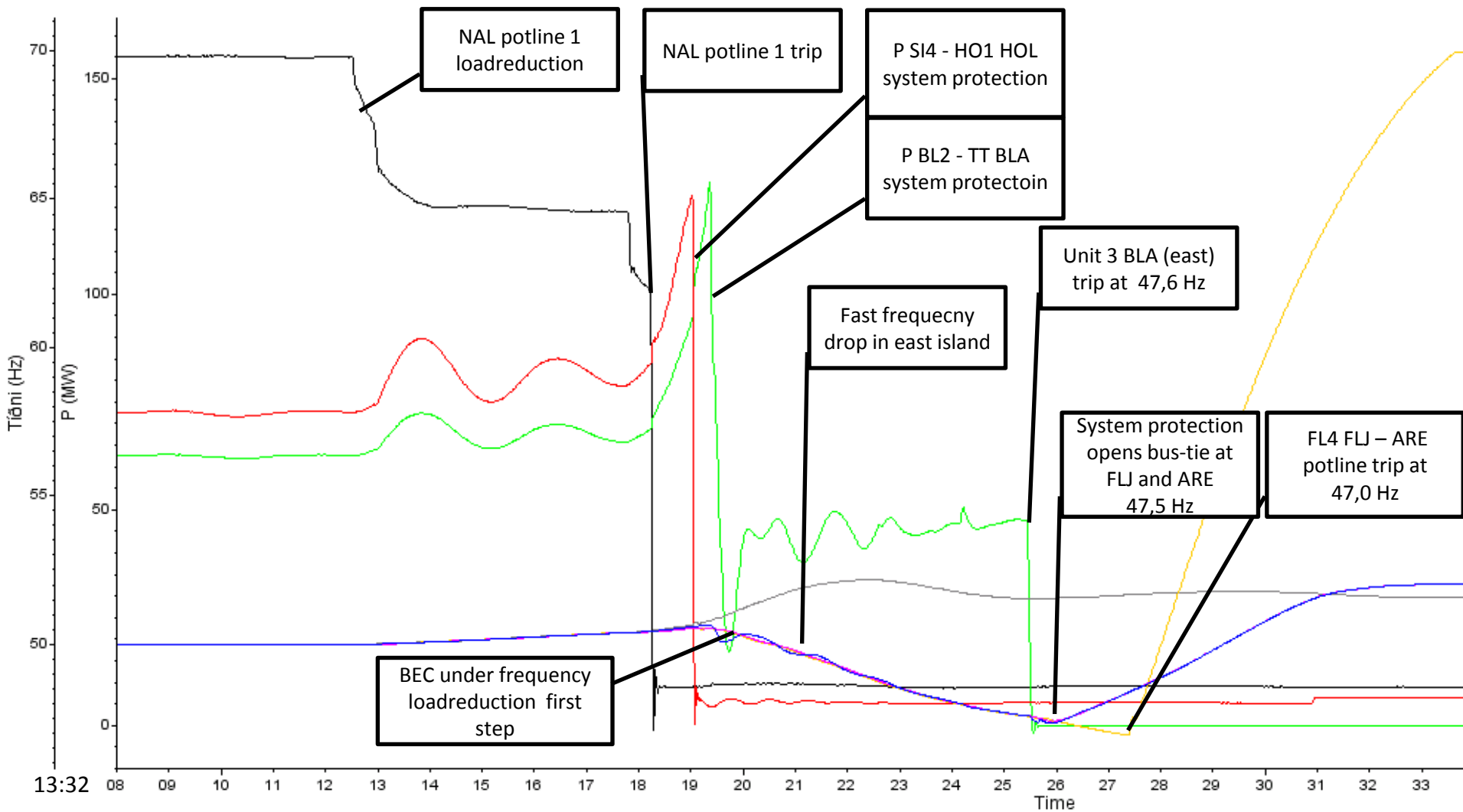
3. Operational challenges in cut IV

trip off smelter load in SouthWest 500 MW

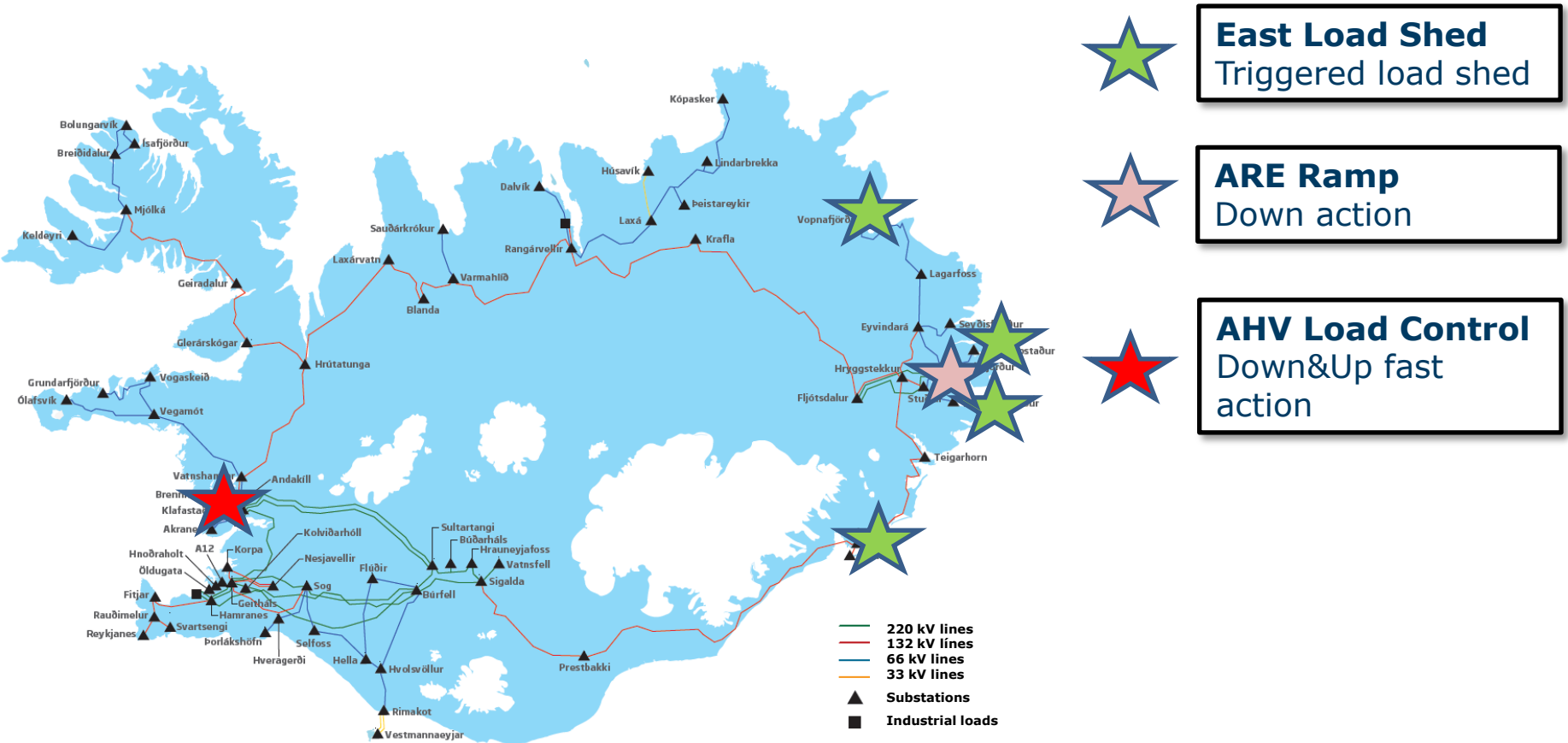


3. Operational challenges in cut IV

SP split BLA - HOL 08.05.13



4. WACS in operation

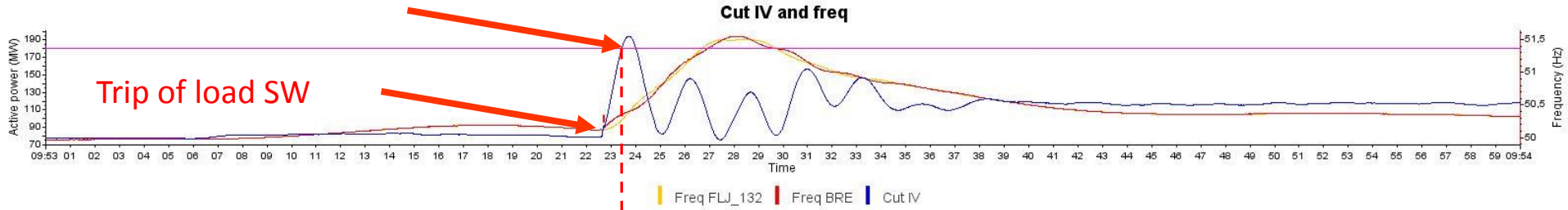




East Load Shed Triggered load shed

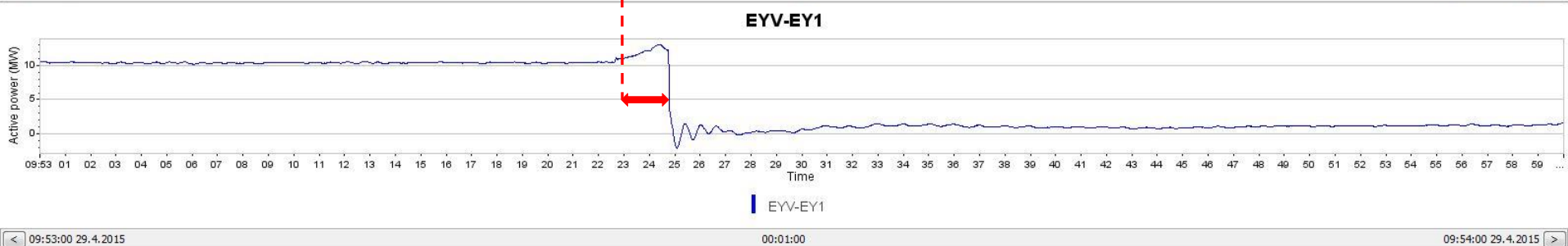
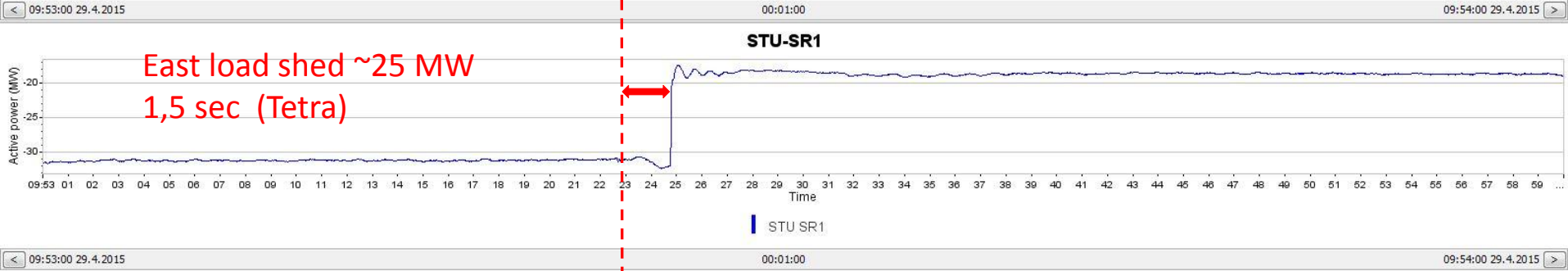


Trigger of East load shed



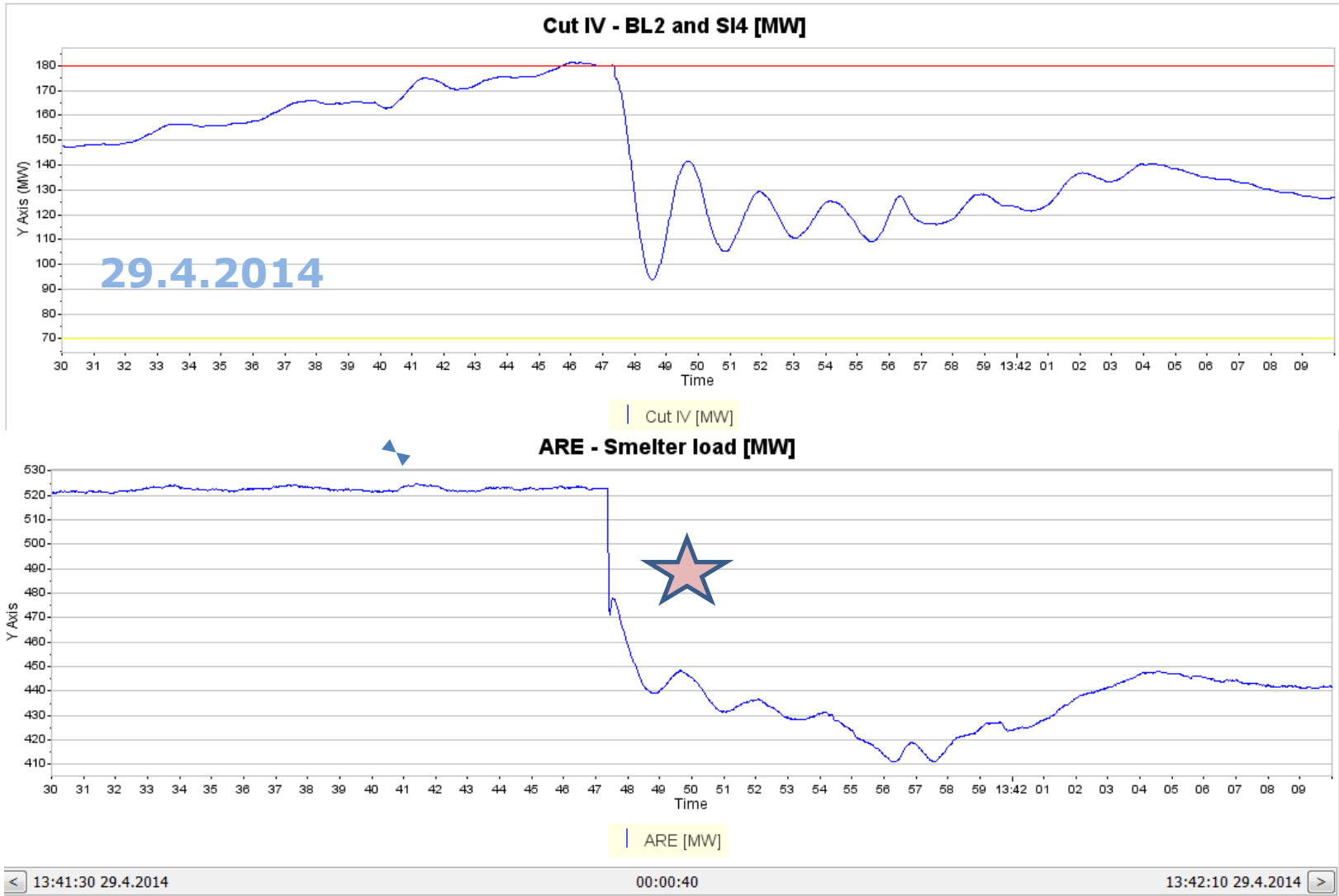
Trip of load SW

East load shed ~25 MW
1,5 sec (Tetra)





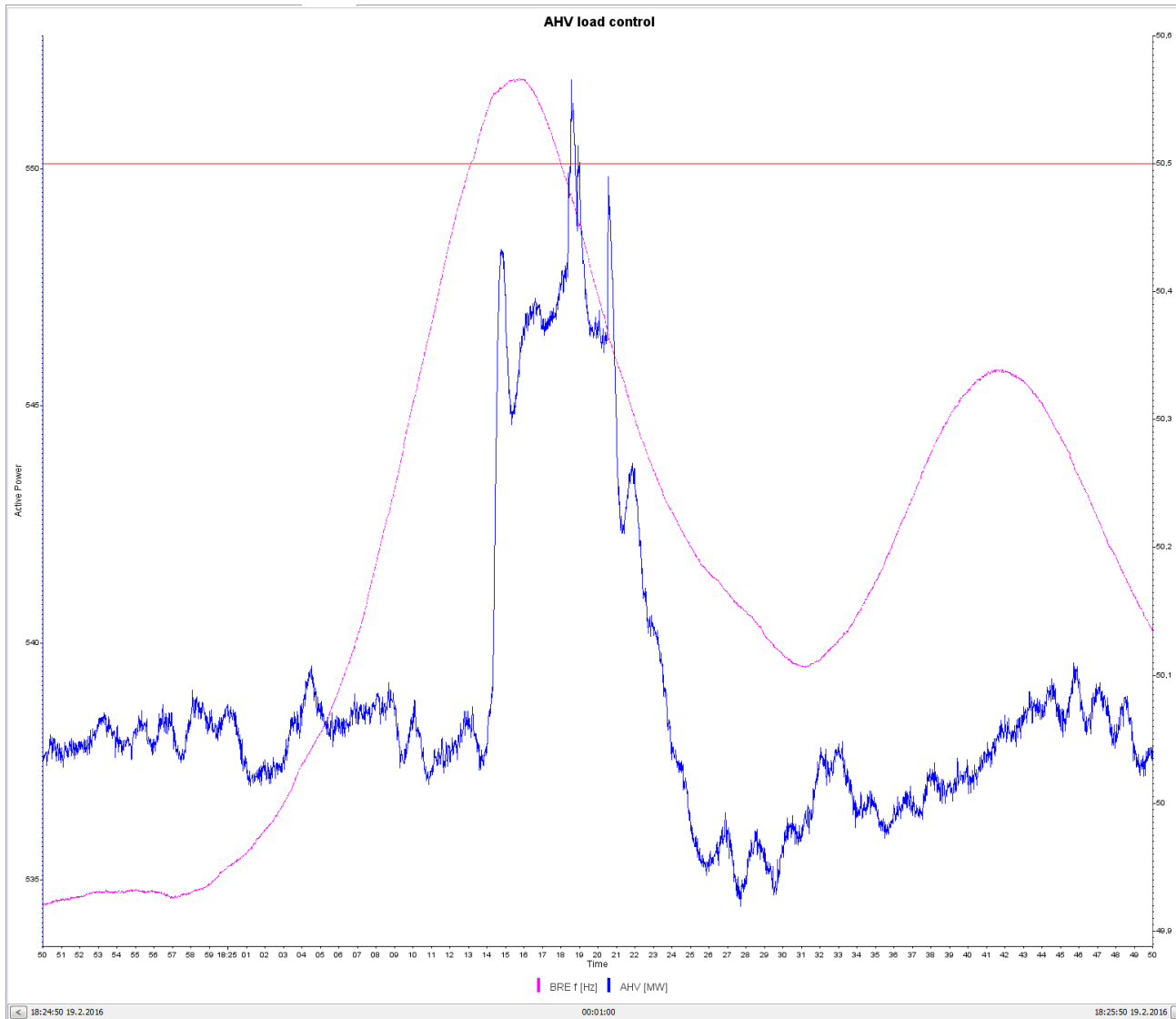
ARE Ramp Down action





AHV Load Control

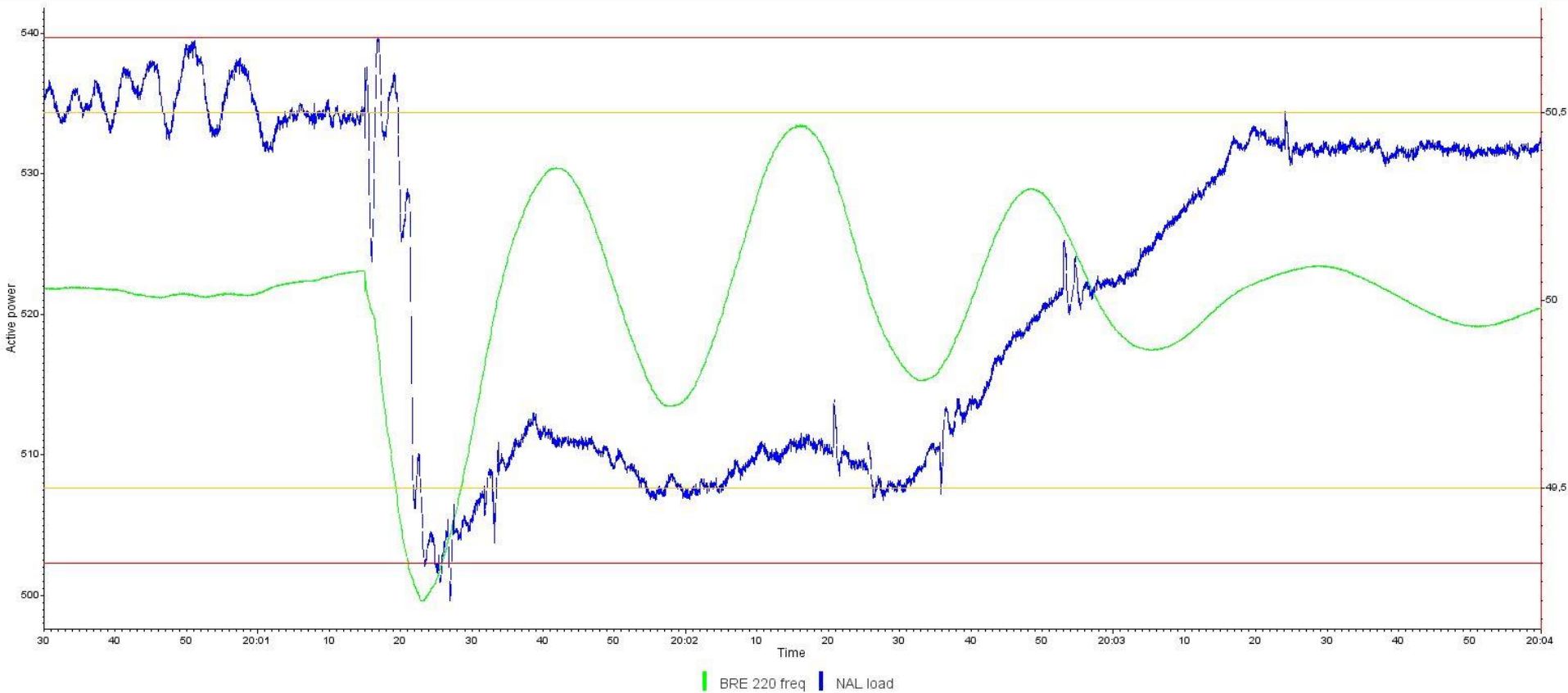
Up fast action





NAL Load Control

Down fast action



Event 25.05.2015



5. Summary and future plans

Control of all smelter load → (0-120 sec)

- Fast down & up regulation
- Balance action within disturbance area
- Goal to prevent system split

Fast ramping of generating units

- Faster response within disturbance area
- PMU based blocking of change over to frequency mode
- Emergency control in AGC

Adaptive Islanding

- Split-line armed depending on power flow and balance
- Intelligent system design - CB at SIG
- Increased power flow on 132 kV ring

Thank You



EFCC Stakeholder Engagement

Laboratory Testing and Optimisation of SFC at The University of Manchester

Prof. Vladimir Terzija

Dr Peter Wall

Mingyu Sun

Alexandru Nechifor

Negar Shams

Outline

1. Objectives and Role of UoM in EFCC
2. Context for UoM Research
3. Laboratory Testing
4. Economic Optimisation
5. Progress and Next Steps

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Role and Objectives of UoM in EFCC

Laboratory Testing and Optimisation of SFC
at The University of Manchester

Role of UoM in the EFCC Project

1. Laboratory Testing of SFC
 - Using PowerFactory and the Manchester RTDS to test the proposed Monitoring and Control Scheme (MCS)
2. Optimisation of SFC
 - Optimise the response of the proposed MCS
 - Create a supervisory wide-area controller and compare its performance to the proposed MCS
3. Develop SFC as a Balancing Service
 - Valuation of SFC, impact on policy and grid codes and other commercial considerations of SFC
4. Knowledge Dissemination

Further Objectives of UoM

1. Estimation of System Inertia
 - Create online methods for estimating system inertia with a view to real-time inertia monitoring
2. Understanding and Estimating Regional Inertia
 - Create rigorous methods for defining a region, estimating its inertia and understanding the impact of regional inertia
3. The possible role of locally triggered resources as part of fast frequency control
4. The nature of Frequency/Active Power Control in systems with high penetrations of power electronics

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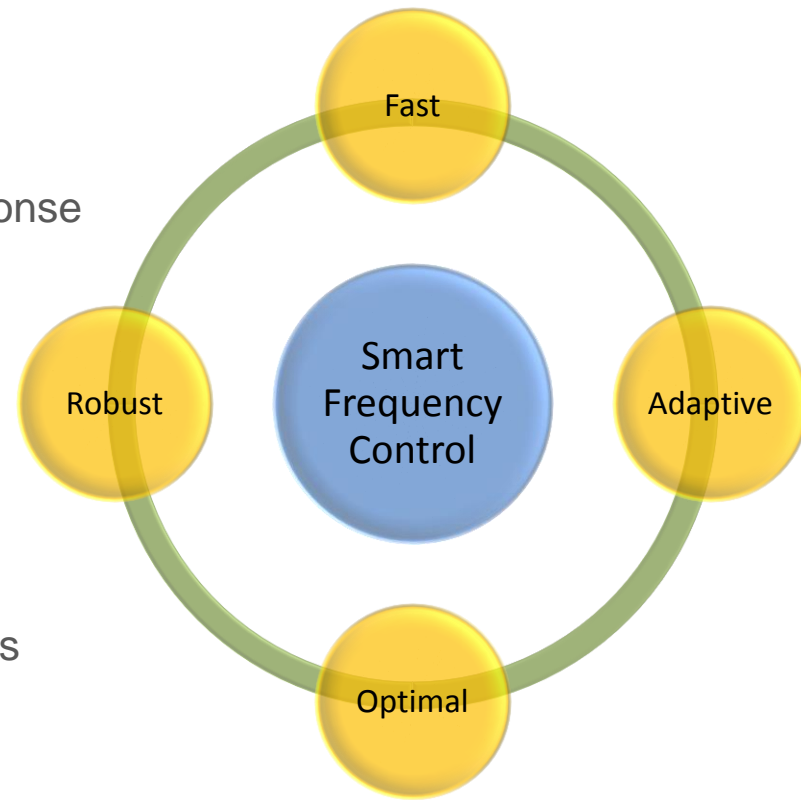
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Context for UoM Research

**Laboratory Testing and Optimisation of SFC
at The University of Manchester**

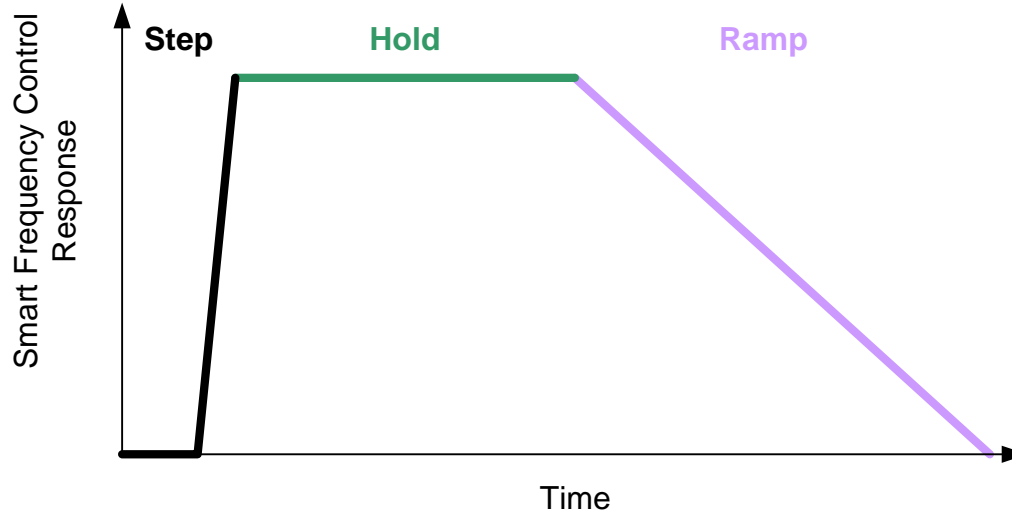
Smart Frequency Control (SFC)

- A new form of frequency control for low inertia systems
- It must be:
 - **Fast**
 - SFC must support inertial response
 - **Adaptive**
 - Variable inertia will require a variable response or it could jeopardise frequency security
 - **Optimal**
 - The cost and impact of service provision must be reasonable
 - **Robust**
 - Many elements of the system controlled in a short time (<1s), so the consequences of failures or errors may be high



Smart Frequency Control

- The response can be broken down into three stages

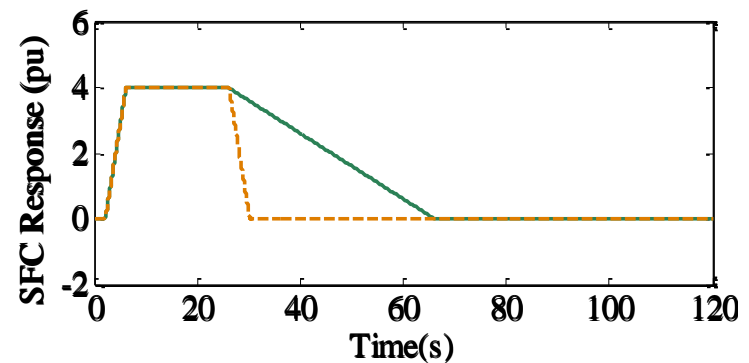
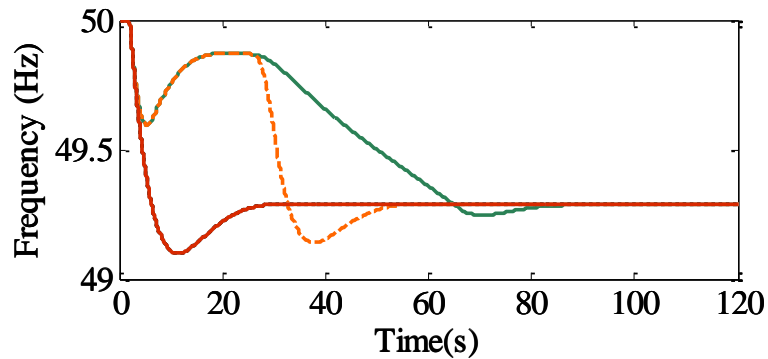


- Is tempting to focus on the step, as the speed of this response is the novel feature of SFC
- However the hold and ramp are equally important

Smart Frequency Control

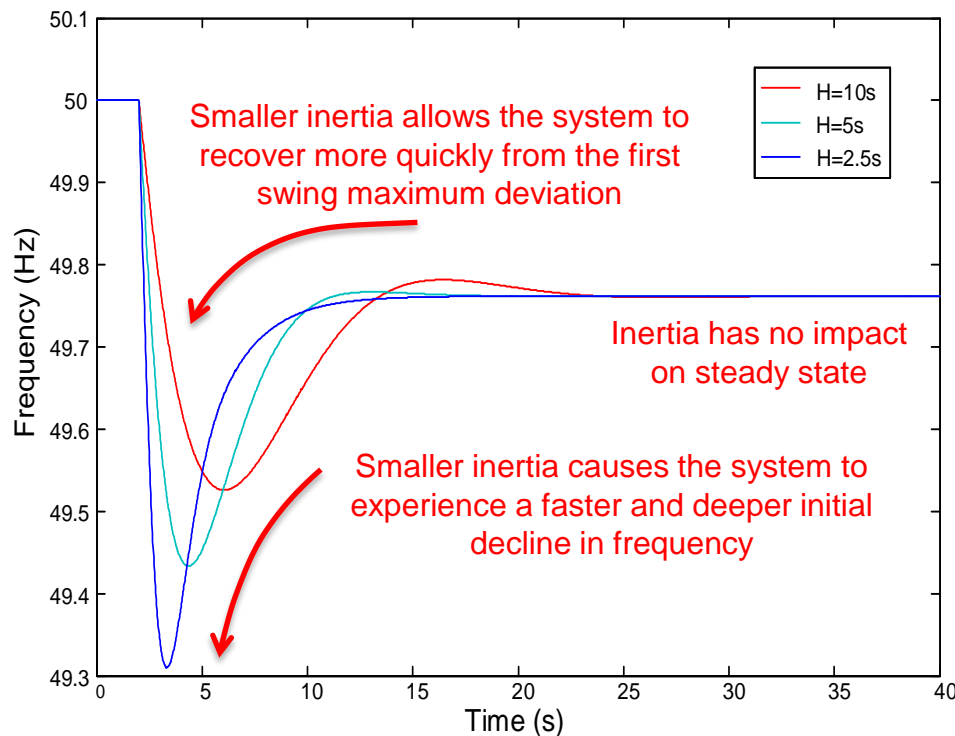
- The role of SFC can be viewed as:

Converting an active power disturbance that the existing primary control **cannot** contain into one that it **can** contain



Impact of Reduced Inertia – Frequency

- Inertia acts to oppose any change in frequency
- Less inertia means larger, faster changes in frequency

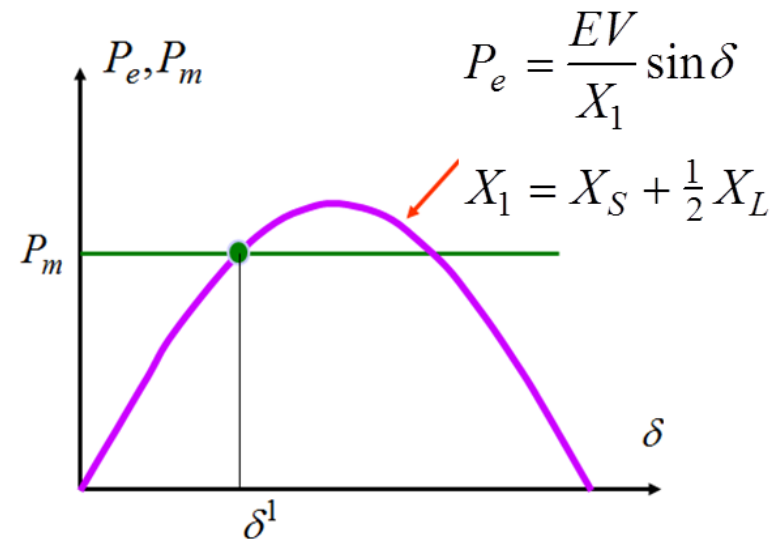
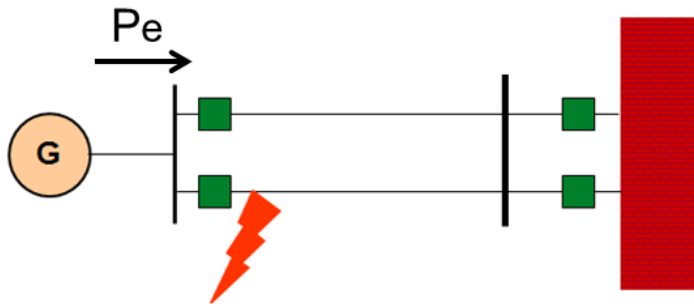


Impact of Reduced Inertia – Angle

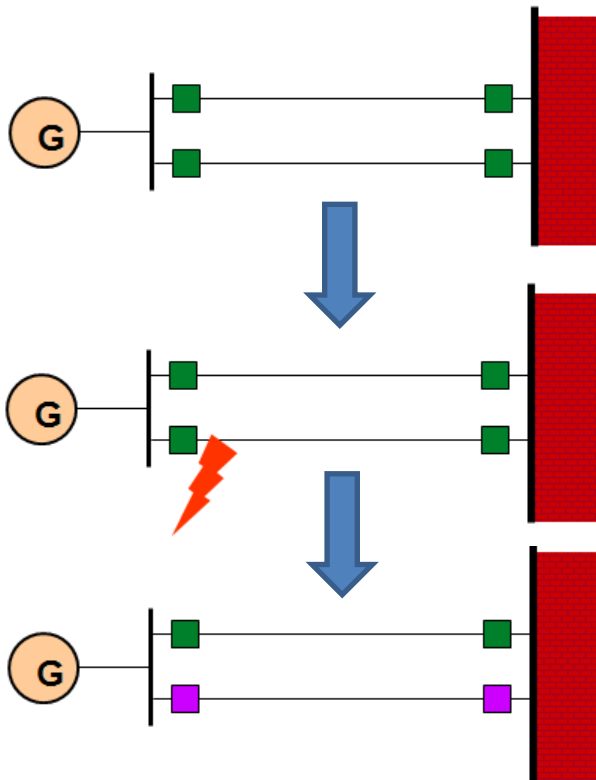
- Frequency is the derivative of angle
- Reduced inertia allows angles to change faster
- Regional inertia means regions can separate more easily and the period of vulnerability is longer
- Faster frequency control actions will intrude on period of interest for angular stability

Matlab Example of Equal Area Criteria

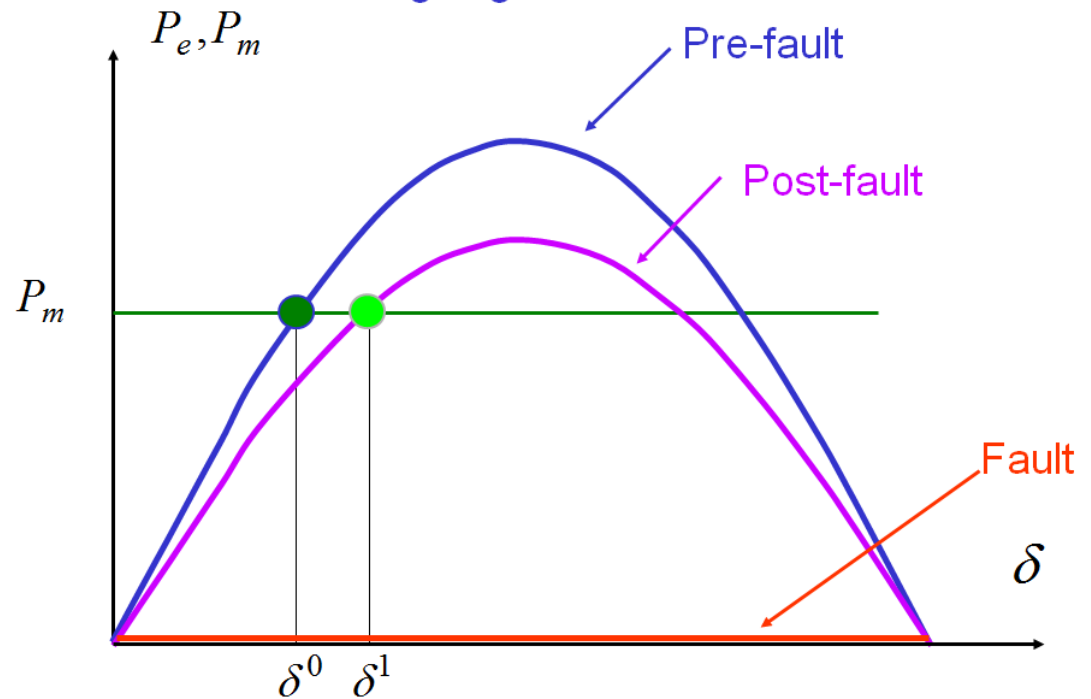
Example of a single generator connected to a large network (an infinite bus):



Matlab Example of Equal Area Criteria



Can we get from one steady state operating point to another without going unstable?

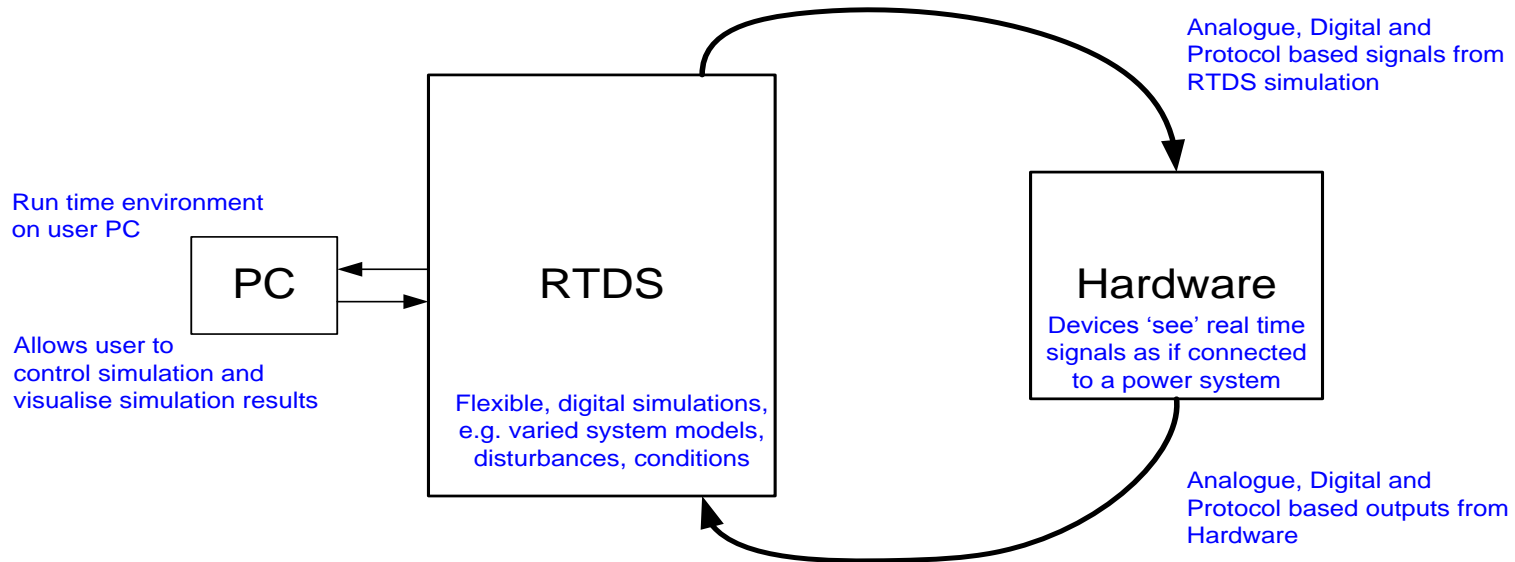


RTDS – Real Time Digital Simulator

- RTDS – Real Time Digital Simulator
- Electromagnetic Transient simulation
 - Simulation uses a 50 μ s time step
 - The simulation of 1 second takes **exactly** 1 second
- RTDS includes analogue and digital output boards as well as protocol based communication
- Hardware can use these signals as inputs, as if they were connected to an actual power system
- This allows Hardware in the Loop Testing

Hardware in the Loop (HiL) Testing

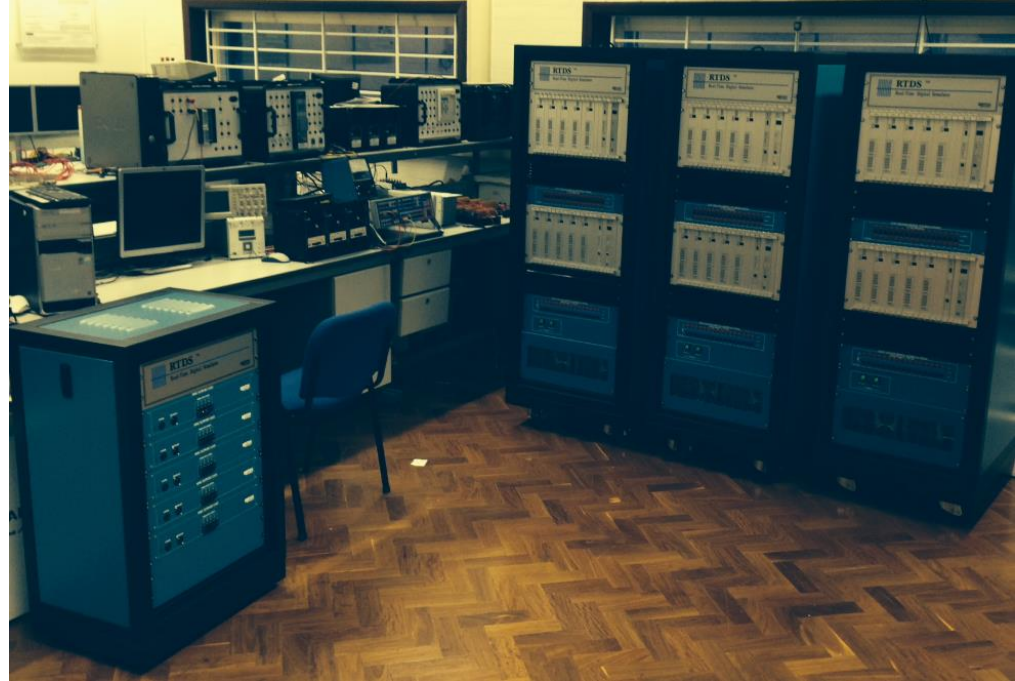
- Closed loop testing of hardware



- Can study the interaction between the hardware and the simulated power system
 - This is critical for studying controllers

Manchester RTDS

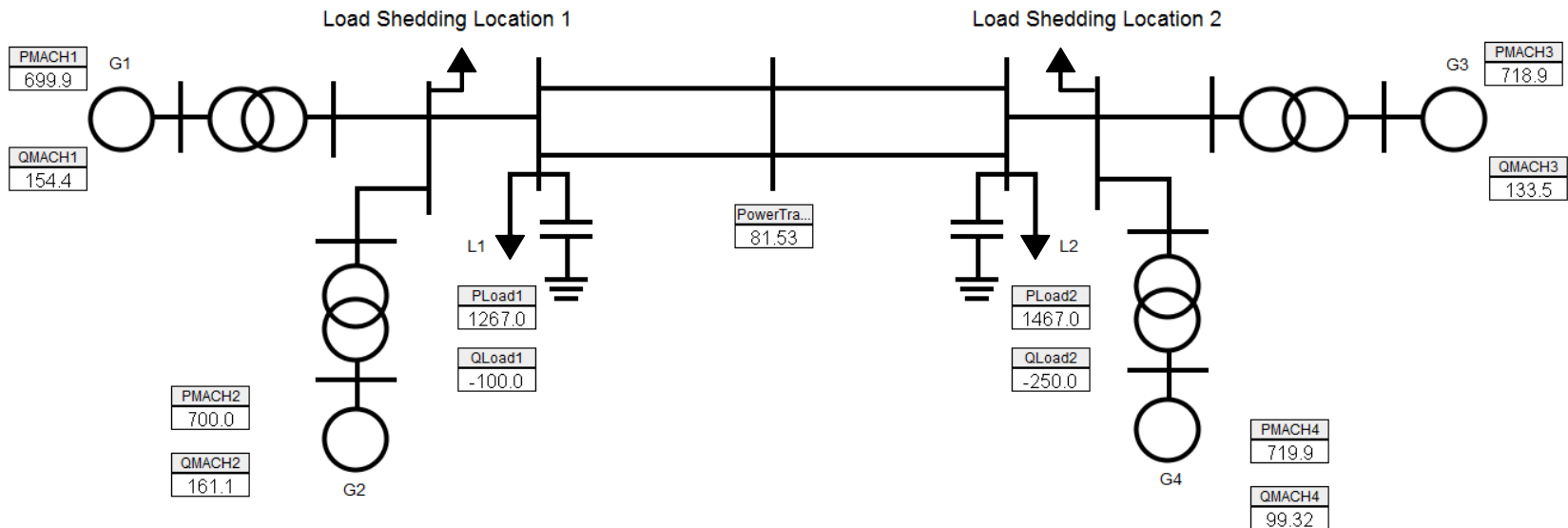
- M-RTDS has:
 - 6 racks 30 PB5 processor cards
 - 5 MMC support units
 - GTSync card for Synchronisation of the RTDS
 - GTNet cards for high level communication (e.g. IEC 61850, C37.118 and IEC 60870 protocols)
 - GTWIF cards to connect to workstations



Demonstration of M-RTDS

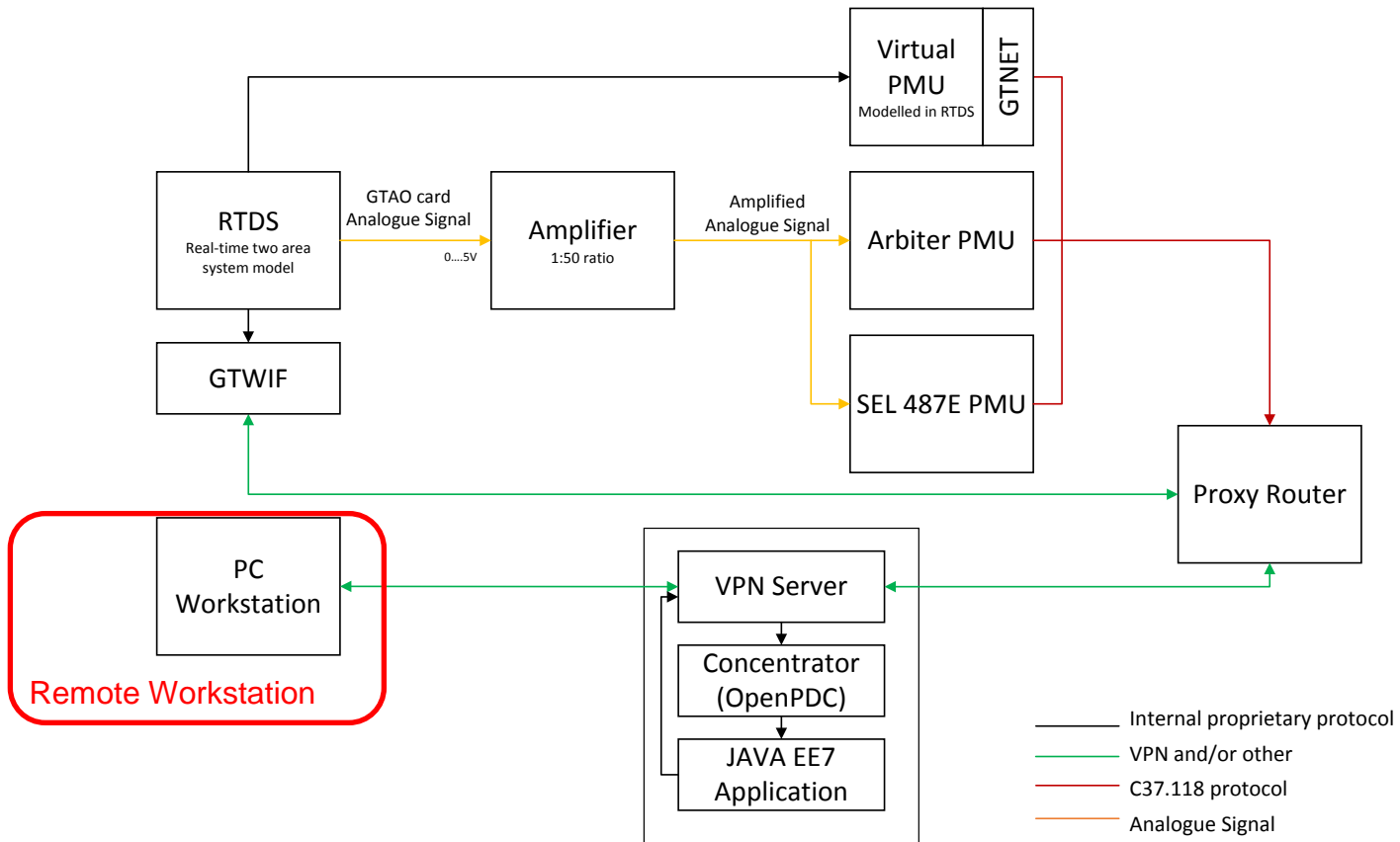
- Use the RTDS to present simulated examples of a Two Area power system

Two Area System EFCC Project



Demonstration of M-RTDS

- Connect to RTDS Laboratory using a VPN



Demonstration of M-RTDS - Runtime

- Runtime allows user to control simulation in real time

1) Vary inertia in each Area

2) Select Fast Control Action

3) Trigger a Disturbance

The screenshot displays three control panels from the M-RTDS runtime interface:

- Inertia Control Panel:**
 - Generator Inertia Control: Four dials (DialG1-DialG4) set to 0.0. Below are four switches (SWIG1-SWIG4) set to OFF (0).
 - Frequency (H) of G1: 6.500, G2: 6.500, G3: 6.175, G4: 6.175.
 - Total H: 6.338.
- Load Shedding Control Panel:**
 - Zone 1 Load Shedding: Am (Disabled 1), BRK2 (ON), Threshold (49.5 Hz), Delay Time (0.1 s), Load Shed Capa. (20.0 MW).
 - Zone 2 Load Shedding: Am (Disabled 1), BRK4 (ON), Threshold (49.5 Hz), Delay Time (0.1 s), Load Shed Capa. (20.0 MW).
- Load Disturbance Panel:**
 - Disturbance Trigger: Generation Loss (400 MW), LoadSelect3 (200 MW), Trigger GLoss (OFF 0), SW3 (OFF 0).
 - Load Loss Trgger: P1 (1267.0 MW), P2 (1467.0 MW).

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Laboratory Testing

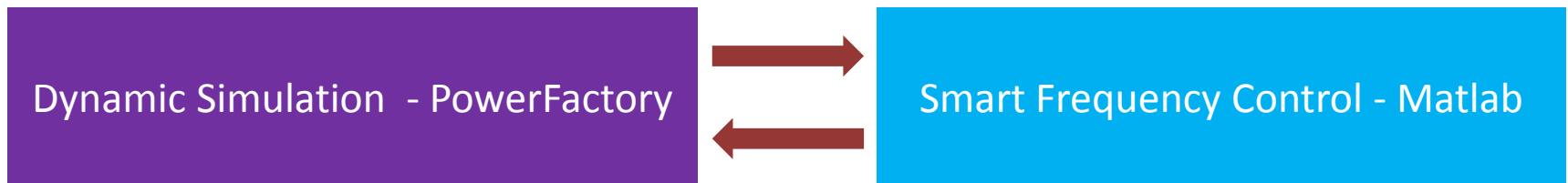
**Laboratory Testing and Optimisation of SFC
at The University of Manchester**

Laboratory Testing at UoM

- Non-Real Time Testing
 - Dynamic simulations using DIgSILENT Powerfactory
 - SFC elements (e.g. local controller) simulated in Matlab
- Real Time Testing
 - Dynamic simulations using the Manchester RTDS
 - Prototype Hardware used for all SFC elements

Non-Real Time Testing

- Closed loop tests to study response of software implementation of SFC elements
- Must Integrate PowerFactory and Matlab to allow the simulation to pass data to the controller and vice versa



- This is possible within PowerFactory
 - But, it requires the SFC modules to be modified (being delivered through collaboration with GE)

Non-Real Time Testing – Open Loop

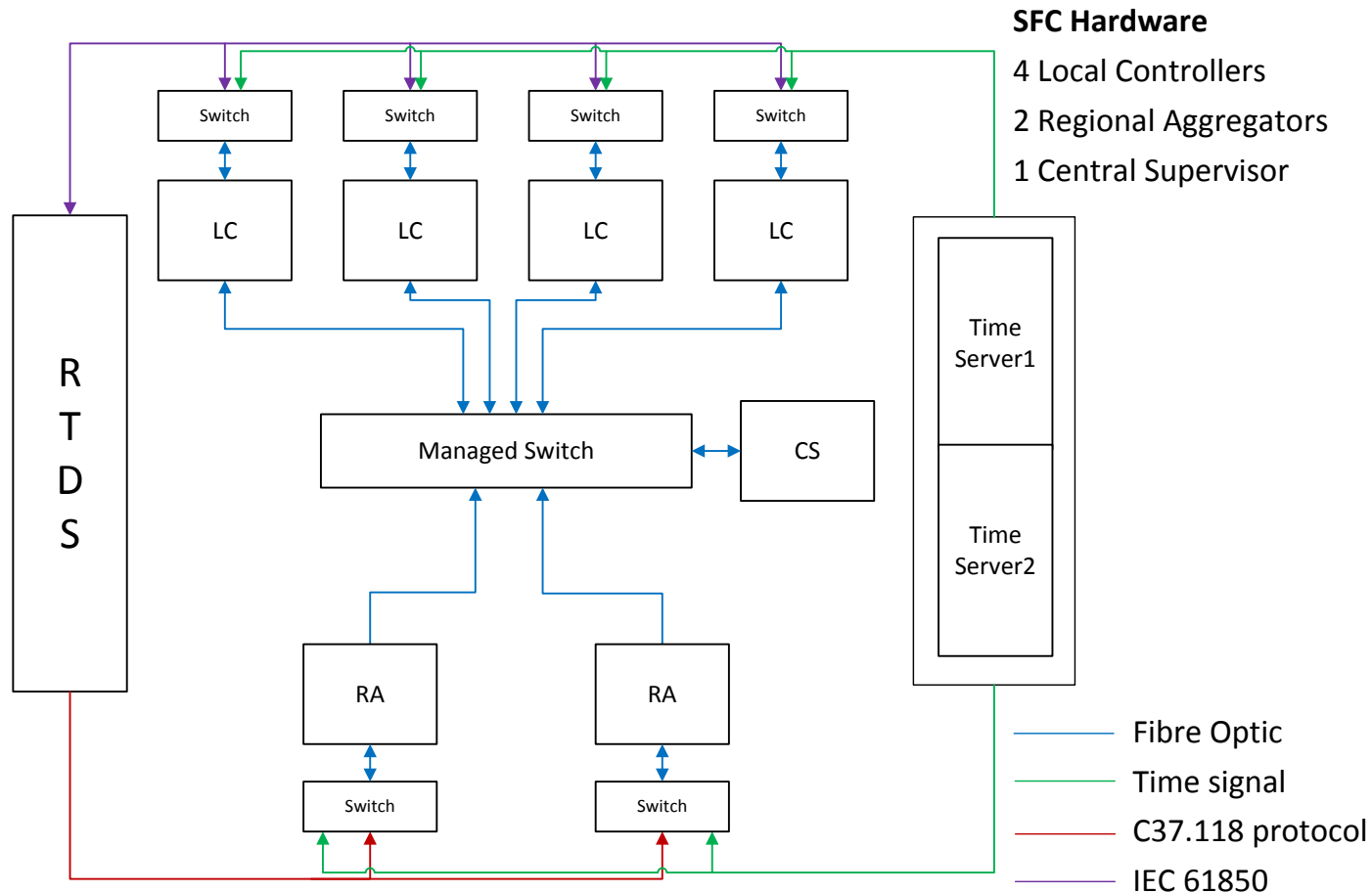
- No feedback into the simulation from the SFC
- Focus of testing is:
 - RoCoF estimation in presence of noise and errors
 - Dependability and accuracy of disturbance detection and size estimation
 - Security against short circuits and line disconnections
 - Performance during multiple events (e.g. a short circuit followed by the disconnection of a generator)
 - Impact of improper region selection

Non-Real Time Testing – Closed Loop

- Feedback into the simulation from the SFC
- Focus of testing is:
 - Resource Allocation by local controllers
 - Impact of noise and errors on resource allocation
 - Impact of finite resource and improper resource response
 - Resource allocation during multiple events
 - Impact of massive communication loss

Real Time Testing

- Use M-RTDS to test SFC hardware



Real Time Testing

- Use M-RTDS to test SFC hardware
- Testing is separated into two elements:
 1. Verify hardware response mimics software response
 - Repeat selected non-real time tests
 2. Impact of monitoring and communication performance
 - PMU measurement performance
 - Poorly defined data streams
 - Latency, jitter and lost packets
 - Configuration errors in hardware or communications

Question and Answer 1 – Laboratory Testing

**Laboratory Testing and Optimisation of SFC
at The University of Manchester**

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Economic Optimisation

**Laboratory Testing and Optimisation of SFC
at The University of Manchester**

Optimisation of SFC

- Ensuring SFC offers value for money to customers
- Some Key Questions:
 - How much response is required?
 - For a given inertia
 - Balance between slower and faster resources
 - The limitations on the energy of certain resources
 - What is the worst case?
 - Size and location of disturbance
 - Angular stress across the system
 - Availability of intermittent resources
 - How will the market work?
 - Balance between availability payments and utilisation payments
 - Ensuring technical deployment of SFC offers value for money to the customer

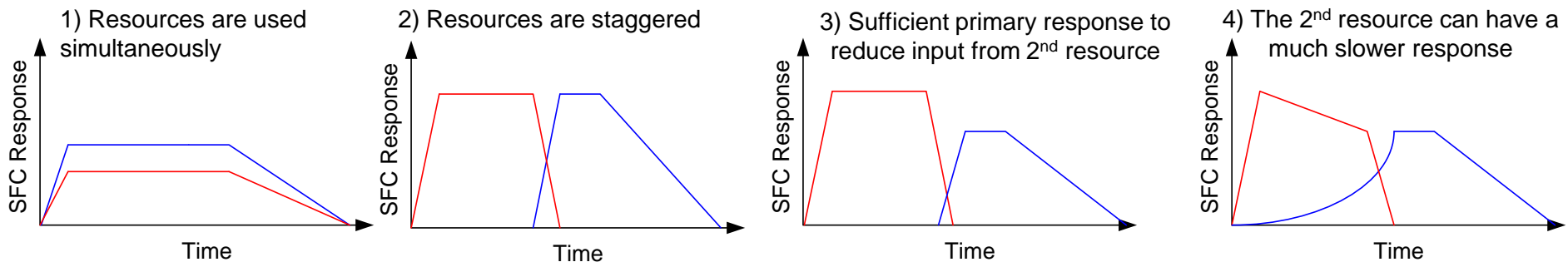
Offline and Online Optimisation

- **Offline** – Which resources are available to use?
 - Incurs Availability Payments
- **Online** - How do we use these resources?
 - Incurs Utilisation Payments
- Offline optimisation is intrinsically linked to the online
 - It ensures that the resources are available to allow the online optimisation to deliver a suitable response
 - How the online optimisation uses the resources will directly determine the resource required
 - Can't ignore utilisation payments for offline optimisation

Offline and Online Optimisation

- The approach of the online optimisation will drive the constraints and objectives of the offline optimisation

Consider a simple scenario with two resources (red and blue)



The market structure and pricing is of vital importance:

- What are the cost curves per MW for the resources?
- How much more expensive are faster services?
- Relative value of energy and power?
- Cost of primary response compared to slower SFC resources

Offline and Online Optimisation

- What is the worst case for the optimisation?
 - Conflict with angular stability may cause wider variation in this, particularly when optimising the fast resources
 - Disturbances at the edge of the system may require more dedicated resource
 - Regional Inertia may mean that resources in some areas become exclusively for one case
 - Size of disturbance may need to be balanced against location and angular stress (dispatch)



Offline and Online Optimisation

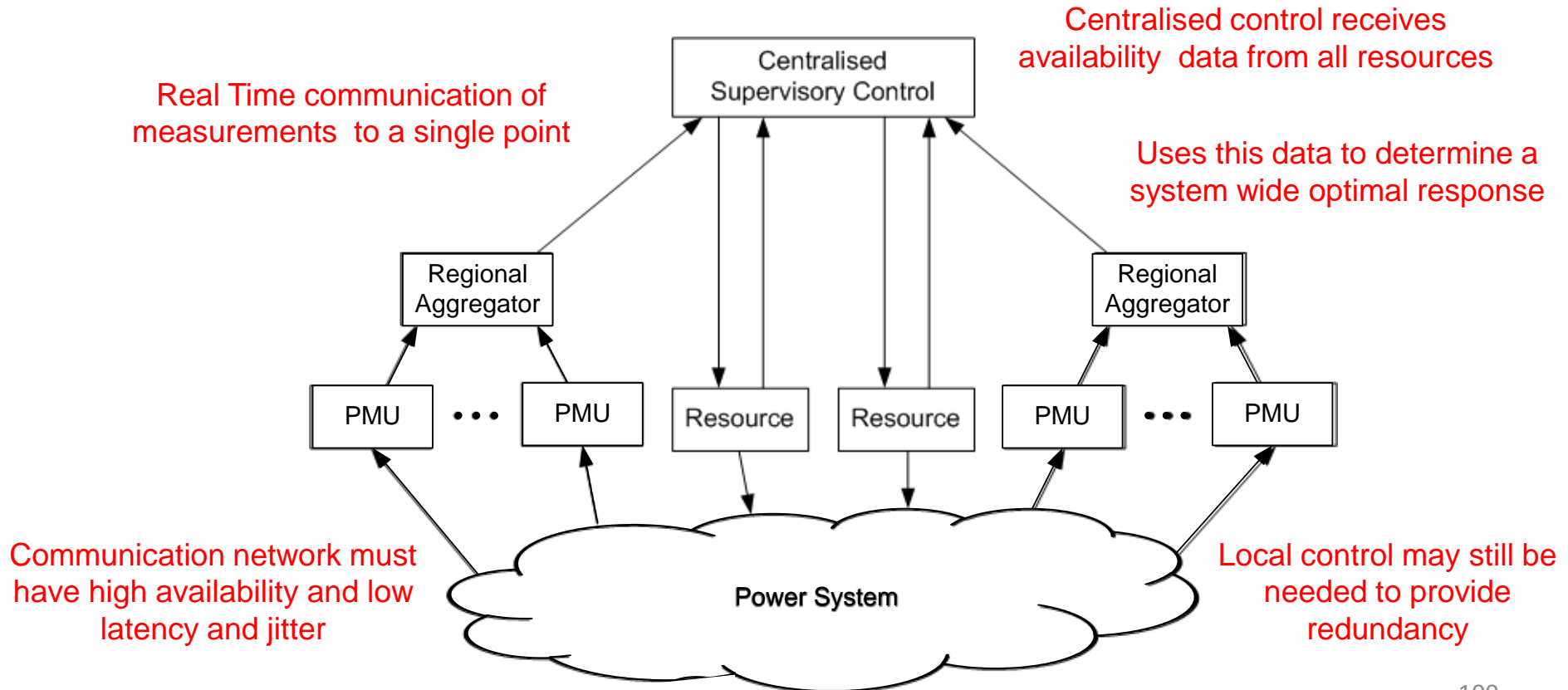
- Most cases aren't the worst case
 - How fast must the *fast* response be for these cases?
 - Will the online optimisation for these cases be harder?
 - How best to measure the severity of a frequency disturbance when optimising the response?
 - Will the online optimisation for these cases be harder?

Wide Area Supervisory Control

- SFC uses local controllers that make independent decisions based on wide area data and merit order
- Coordinated supervisory control, would allow each resource to be directly controlled by a central controller
 - This should offer a more efficient response, as limitations will exist on local, online optimisation
 - But, communication requirements are more significant,

Wide Area Supervisory Control

- Simple example for a Two Region System



Wide Area Supervisory Control

- Coordinated supervisory control, would allow each resource to be directly controlled by a central controller
 - This should offer a more efficient response, as limitations will exist on local, online optimisation
 - Resources could be used more optimally and the performance of the scheme would improve
 - But, communication requirements are more significant, so the scheme may become less reliable or more costly
- Does the benefit of this more complex control justify the increased cost and complexity?

Question and Answer 2 - Optimisation

**Laboratory Testing and Optimisation of SFC
at The University of Manchester**

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Progress

Laboratory Testing and Optimisation of SFC at The University of Manchester

Progress

- Defined scope of Laboratory Testing
- Defined requirements for integrating PowerFactory (Dynamic Simulations) and Matlab (SFC models)
- Built Two Area model in RSCAD
- Prototype of Runtime environment for Real-Time tests
- Connection of Hardware (PMUs) to the RTDS

What's Next?

- Define specific testing plan and expected outcomes
- Implement Non-Real Time Testing
- Begin Non-Real Time Testing
- Connect control hardware to the RTDS
- Finalise laboratory setup for Real-Time Testing

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EFCC Stakeholder Engagement

Laboratory Testing and Optimisation of SFC
at The University of Manchester

Prof. Vladimir Terzija